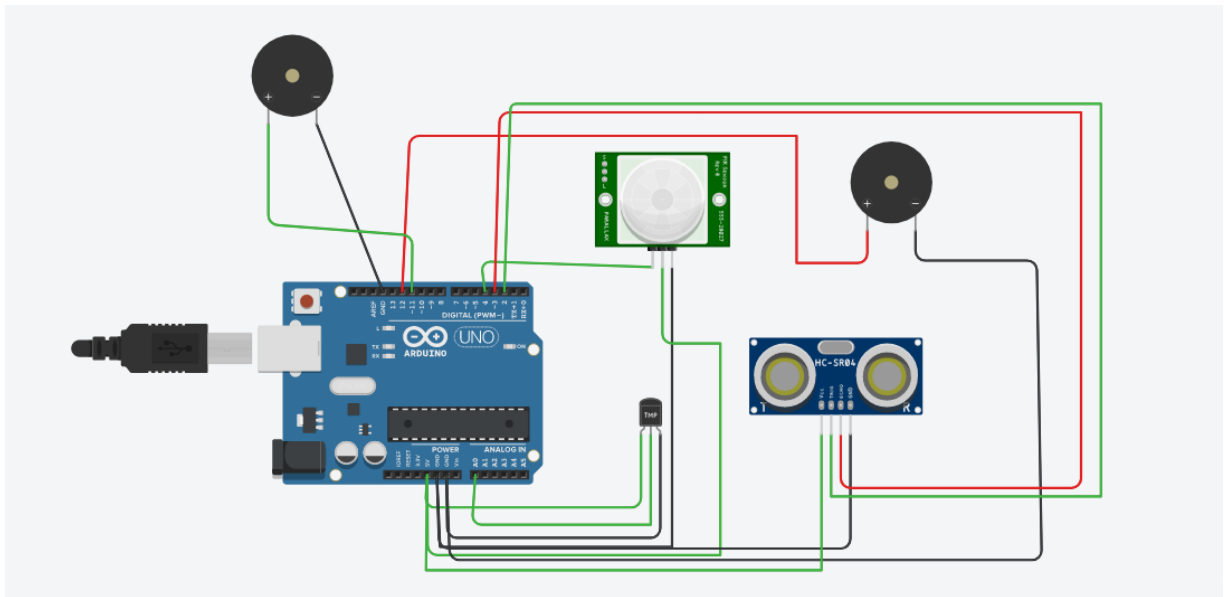


## Circuit Design



## Program

```
int t=2;
int e=3;
void setup()
{
  pinMode(4,INPUT);
  Serial.begin(9600);
  pinMode(t,OUTPUT);
  pinMode(e,INPUT);
  pinMode(13,OUTPUT);
  pinMode(11,OUTPUT);
  pinMode(12,OUTPUT);
}
void loop()
{
  digitalWrite(t,LOW);
```

```
digitalWrite(t,HIGH);
delayMicroseconds(10);
digitalWrite(t,LOW);

float dur=pulseIn(e,HIGH);
float dis=(dur*0.343)/2;
Serial.println("the distance is:");
Serial.println(dis);
    if(dis<1000){
        tone(12,30);
        delay(1000);
    }
    else{
        noTone(12);
        delay(1000);
    }

double a = analogRead(A0);
double c=((a/1024)*5)-0.5)*100;
Serial.print("Celcius value:");
Serial.print(c);
delay(1000);
if(c>50)
    digitalWrite(13,HIGH);
else
    digitalWrite(13,LOW);

int p=digitalRead(4);
Serial.println(p);
if(p==1){
    digitalWrite(11,HIGH);
```

```

    Serial.println("Motion detected!!!");
    delay(1000);
}
else{
    digitalWrite(11,LOW);
    Serial.println("Motion not detected!!!");
    delay(1000);
}
}

```

## Output:

