```
// Tinkercad Arduino : Automatic Room Lightning System
Int LightSensorVal = 0; //Input Sensor
Int PIRSensorVal = 0; //Input S
Int RelayOutputVal = 0; //Output Relay
Void setup()
{
 pinMode(A0, INPUT); // Read the LDR sensor Value digital Input
 pinMode(2, INPUT); // Read the PIR motion sensor value digital Input
 pinMode(8, OUTPUT); // Write the Relay output value, digital output
 Serial.begin(9600);
}
Void loop()
{
 LightSensorVal = analogRead(A0);
 PIRSensorVal = digitalRead(2);
 RelayOutputVal = 8;
 If (LightSensorVal < 600) {
  If (PIRSensorVal == HIGH) {
   digitalWrite(8, HIGH);
   delay(5000); // Wait for 5000 millisecond(s)
  } else {
   digitalWrite(8, LOW);
   delay(1000); // Wait for 1000 millisecond(s)
  }
 } else {
  digitalWrite(8, LOW);
  Serial.println(LightSensorVal);
```

```
Delay(300); // Wait for 300 millisecond(s)
}
}
Footer
© 2022 GitHub, Inc.
Footer navigation
Terms
Privacy
Security
Status
Docs
Contact GitHub
Pricing
API
Training
Blog
About
```