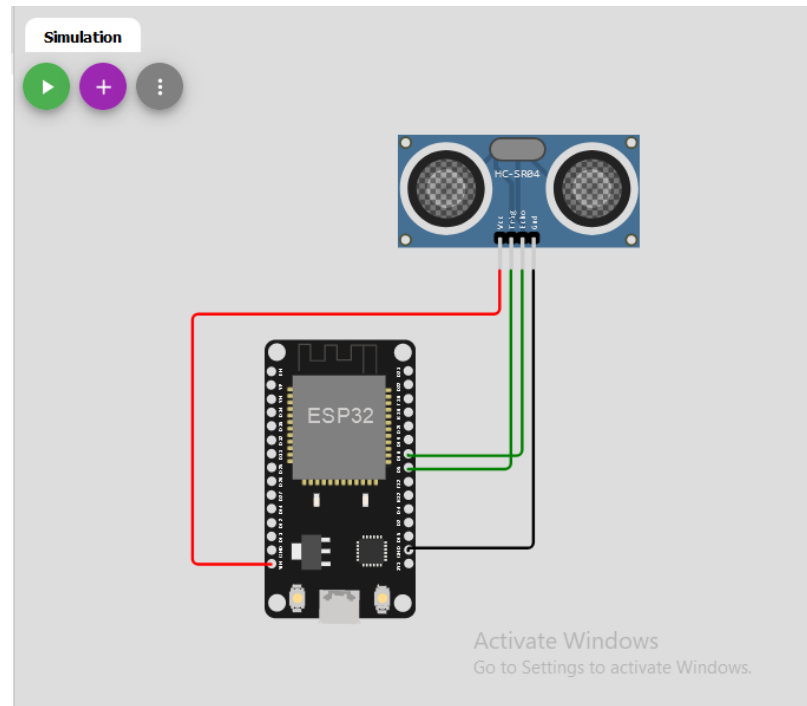


## ASSIGNMENT – 4

**Qn.** Write code and connections in wokwi for the Ultrasonic Sensor. Whenever the distance is less than 100cms, send an alert to ibm cloud and display in the device recent events.

**Circuit Diagram:**



**Code:**

```
#include <WiFi.h>
#include <PubSubClient.h>
WiFiClient wifiClient;
String data3;
#define ORG "t5y3in"
#define DEVICE_TYPE "UltrasonicSensor"
#define DEVICE_ID "12345"
#define TOKEN "dnf*JvI-?(Ud3wbkpv"
#define speed 0.034
#define led 14
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Beautlin J D/fmt/json";
char topic[] = "iot-2/cmd/led/fmt/String";
char authMethod[] = "use-token-auth";
```

```

char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);

const int trigpin=5;
const int echopin=18;
String command;
String data="";

long duration;
float dist;

void setup()
{
  Serial.begin(115200);
  pinMode(led, OUTPUT);
  pinMode(trigpin, OUTPUT);
  pinMode(echopin, INPUT);
  wifiConnect();
  mqttConnect();
}

void loop() {
  bool isNearby = dist < 100;
  digitalWrite(led, isNearby);

  publishData();
  delay(500);

  if (!client.loop()) {
    mqttConnect();
  }
}

void wifiConnect() {
  Serial.print("Connecting to "); Serial.print("Wifi");

  WiFi.begin("Wokwi-GUEST", "", 6);
  while (WiFi.status() != WL_CONNECTED) {
    delay(500);
    Serial.print(".");
  }
  Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
}

```

```

void mqttConnect() {
if (!client.connected()) {
Serial.print("Reconnecting MQTT client to "); Serial.println(server);
while (!client.connect(clientId, authMethod, token)) {
Serial.print(".");
delay(500);
}
initManagedDevice();
Serial.println();
}
}

```

```

void initManagedDevice() {
if (client.subscribe(topic)) {
// Serial.println(client.subscribe(topic));
Serial.println("IBM subscribe to cmd OK");
} else {
Serial.println("subscribe to cmd FAILED");
}
}

```

```

}
void publishData()
{
digitalWrite(trigpin,LOW);
digitalWrite(trigpin,HIGH);
delayMicroseconds(10);
digitalWrite(trigpin,LOW);
duration=pulseIn(echopin,HIGH);
dist=duration*speed/2;
if(dist<100){
String payload = "{\"Alert Distance\":";
payload += dist;
payload += "}";

Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c_str())) {
Serial.println("Publish OK");
}
}

```

```

}
if(dist>100){
String payload = "{\"Distance\":";
payload += dist;

```

```
payload += "}";
```

```
Serial.print("\n");  
Serial.print("Sending payload: ");  
Serial.println(payload);  
if(client.publish(publishTopic, (char*) payload.c_str())) {  
Serial.println("Publish OK");  
}else {  
Serial.println("Publish FAILED");  
}  
}  
}  
}
```

Wokwi Simulation Link:

<https://wokwi.com/projects/347769248776454739>

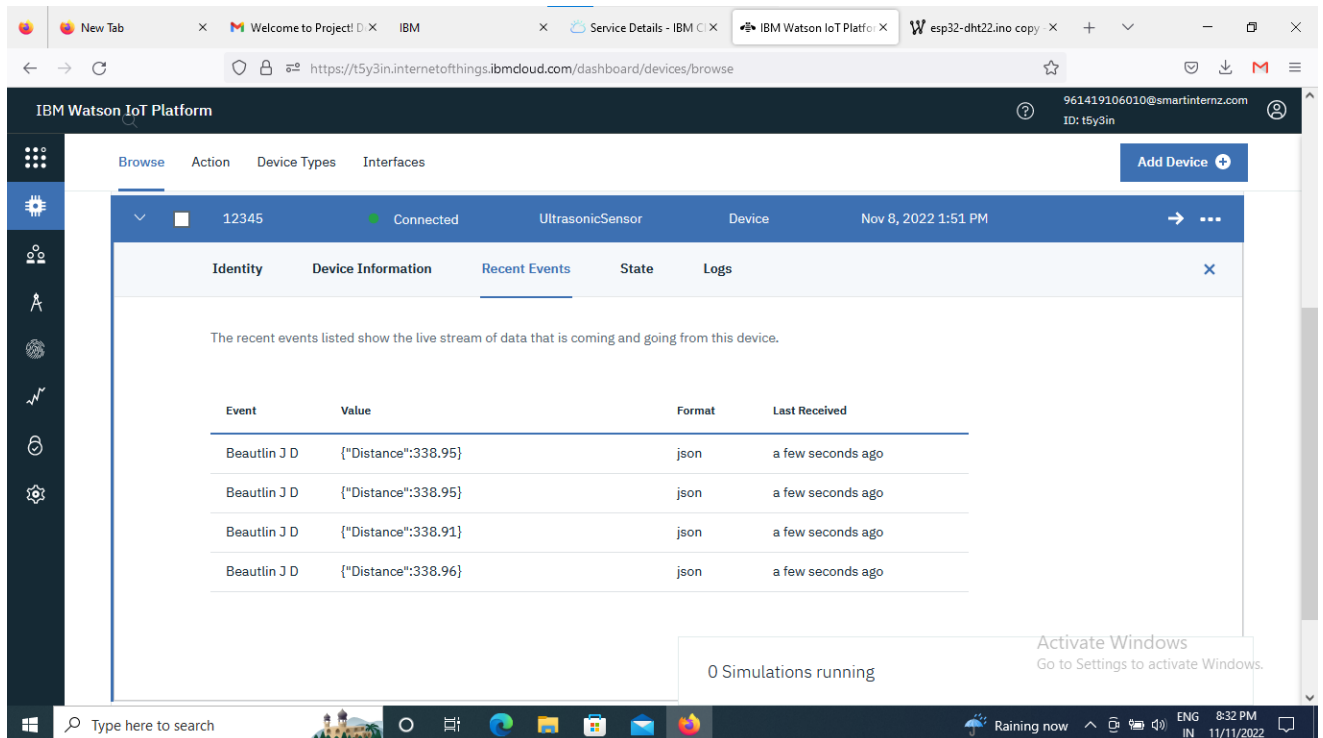
Output:

1. When the distance is greater than 100 cms

The screenshot displays the Wokwi web-based IDE. On the left, the code for `esp32-dht22.ino` is shown, which includes headers for `WiFi`, `PubSubClient`, and `UltrasonicSensor`. It defines constants for the server, topic, token, and sensor pin, and includes a `setup` function that initializes the serial port and the ultrasonic sensor. On the right, the simulation interface shows a visual representation of the ESP32 and the HC-SR04 ultrasonic sensor connected by wires. Below the simulation, the output console shows the following messages:

```
Publish OK  
Sending payload: {"Distance":338.96}  
Publish OK  
Sending payload: {"Distance":338.96}  
Publish OK
```

The bottom of the screen shows a Windows taskbar with the date and time as 11/11/2022, 8:33 PM.



## 2. When the distance is less than 100 cms

