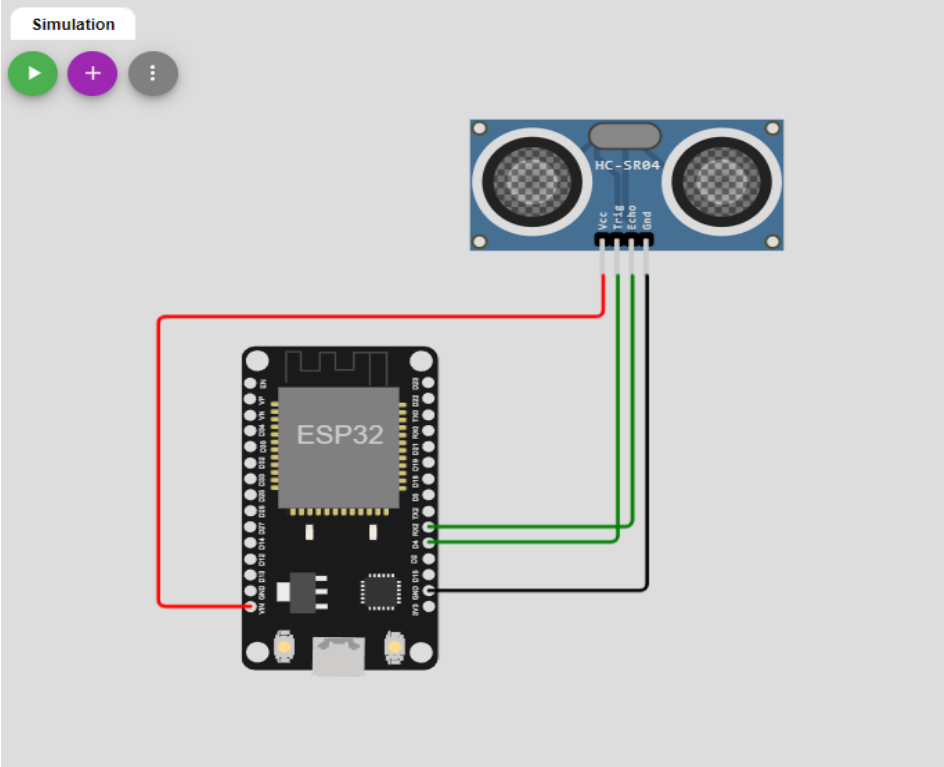
Assignment -4

1.Write code and connections in wowki for the ultrasonic sensor. Whenever the distance is less than 100cms send an alert to ibm cloud and display in the device recent events,

Circuit Diagram:



code:

```
 print("Hello, ESP32!")

#include <WiFi.h>

#include <PubSubClient.h>

WiFiClient wifiClient;

String data3;

#define ORG "uyhprk"

#define DEVICE_TYPE "UltraSonicSensor"
```

```
#define DEVICE_ID "456789"
#define TOKEN "Y0*7&wous&90TR2?f8"
#define speed 0.034
#define led 14
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Jijitha AL/fmt/json";
char topic[] = "iot-2/cmd/led/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);
const int trigpin=5;
const int echopin=18;
String command;
String data="";
long duration;
float dist;
void setup()
{
 Serial.begin(115200);
 pinMode(led, OUTPUT);
 pinMode(trigpin, OUTPUT);
 pinMode(echopin, INPUT);
 wifiConnect();
```

```
 mqttConnect();
}
void loop() {
 bool isNearby = dist < 100;
 digitalWrite(led, isNearby);
 publishData();
 delay(500);
 if (!client.loop()) {
 mqttConnect();
 }
}
void wifiConnect() {
 Serial.print("Connecting to "); Serial.print("Wifi");
 WiFi.begin("Wokwi-GUEST", "", 6);
 while (WiFi.status() != WL_CONNECTED) {
 delay(500);
 Serial.print(".");
 }
 Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
}
void mqttConnect() {
 if (!client.connected()) {
 Serial.print("Reconnecting MQTT client to "); Serial.println(server);
 while (!client.connect(clientId, authMethod, token)) {
```

```
 Serial.print(".");
 delay(500);
 }
 initManagedDevice();
 Serial.println();
 }
}
void initManagedDevice() {
 if (client.subscribe(topic)) {
 // Serial.println(client.subscribe(topic));
 Serial.println("IBM subscribe to cmd OK");
 } else {
 Serial.println("subscribe to cmd FAILED");
 }
}
void publishData()
{
 digitalWrite(trigpin,LOW);
 digitalWrite(trigpin,HIGH);
 delayMicroseconds(10);
 digitalWrite(trigpin,LOW);
 duration=pulseIn(echopin,HIGH);
 dist=duration*speed/2;
 if(dist<100){
```

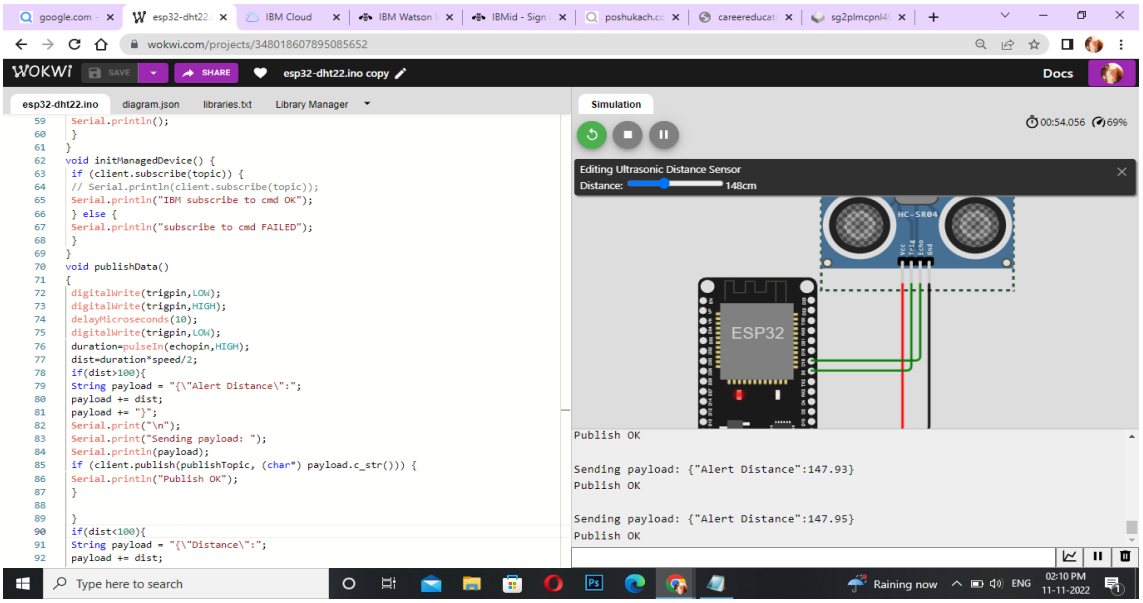
```
String payload = "{\"Alert Distance\":";
payload += dist;
payload += "}";
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c_str())) {
Serial.println("Publish OK");
}
}
if(dist>100){
String payload = "{\"Distance\":";
payload += dist;
payload += "}";
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if(client.publish(publishTopic, (char*) payload.c_str())) {
Serial.println("Publish OK");
}else {
Serial.println("Publish FAILED");
}
}
}
```

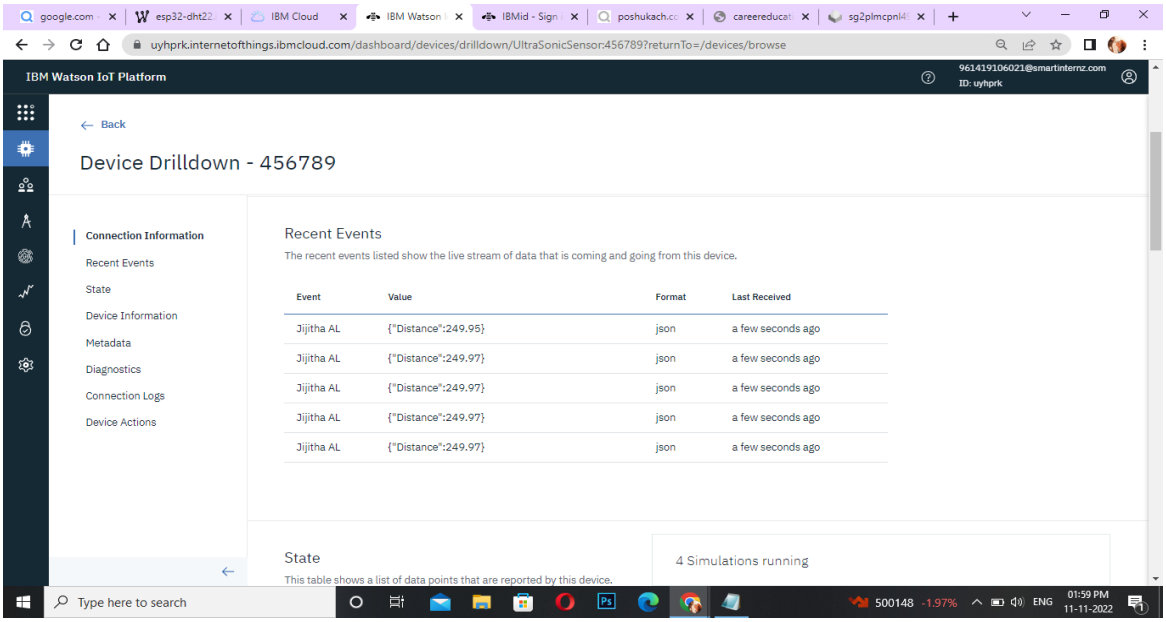
Wowki Stimulation Link:

https://wokwi.com/projects/348018607895085652

Output:

1) When the distance is greater than 100 cms





2) When the distance is less than 100 cms