```
float x,y;
#define echoPin 10
int ledPin= 13;
int duration, distance; //ULTRA
#include<Servo.h> //servo
Servo my;
char val;
void setup() {
Serial.begin(9600);
pinMode(2,INPUT); //IR GATE FIRST
pinMode(3,INPUT);
pinMode(4, OUTPUT); //IR GATE FIRST
pinMode(7,OUTPUT);
pinMode(8,INPUT);
pinMode(9,OUTPUT);
pinMode(trigPin, OUTPUT); //12 PIN ULTRA
pinMode(echoPin, INPUT); //10 PIN ULTRA
pinMode(ledPin, OUTPUT); //13 PIN ULTRA
  void loop() {
x=analogRead(0);
 y=((x/1024)*5)*100;
 Serial.println(y);
 delay(500);
 if(y>44)
 digitalWrite(7,1);
```

```
digitalWrite(7,0);
 delay(500);
if(digitalRead(8)==HIGH)
 digitalWrite(9,HIGH);
{ digitalWrite(9,LOW);}
 delayMicroseconds(10);
 digitalWrite(trigPin, LOW);
 duration = pulseIn(echoPin, HIGH);
 distance = (duration/2) / 29.1;
 if (distance >= 10 || distance <= 0)</pre>
  digitalWrite(ledPin,LOW);
 Serial.println("object detected \n");
Serial.print("distance= ");
 Serial.print(distance);
 digitalWrite(ledPin,HIGH);
if(digitalRead(2) == HIGH) //gate first
 my.write(0); //servo
```

```
my.write(90);
analogRead(5);
 float a = analogRead(5);
Serial.println(a);
   digitalWrite(4,1);
  Serial.println("LDR is DARK, LED is ON");
   digitalWrite(4,0);
   Serial.println("----");
if (Serial.available())
 val = Serial.read();
Serial.println(val);
 if (val == TVT)
 digitalWrite(3,HIGH);
 else if(val == 'tv')
 digitalWrite(3,LOW);
```