Assignment-4

1. Write Code and connections in wokwi for ultrasonic sensor. whatever distance is less than 100 cm send "Alert" to IBM cloud and display in devicerecent events.

```
Solutio
n:

//Pins

const int TRIG_PIN = 7;

const int ECHO_PIN = 8;

//Anything over 400 cm (23200 us pulse) is "out of range"

const unsigned int MAX_DIST = 23200;

void setup() {

// The Trigger pin will tell the sensor to range find

Pin Mode(TRIG_PIN, OUTPUT);

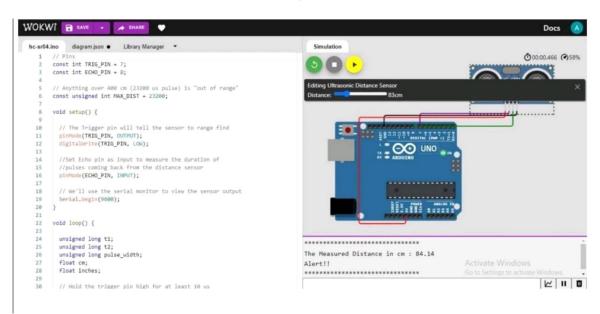
digital Write(TRIG_PIN, LOW);
```

```
//Set Echo pin as input to measure the duration of
 //pulses coming back from the distance sensor
pinMode(ECHO_PIN, INPUT);
// We'll use the serial monitor to view the sensor output
 Serial.begin(9600);
}
void loop() {
unsigned long t1
unsigned long t2;
 unsigned long pulse_width;
 float cm;
 float
 inches;
// Hold the trigger pin high for at least 10 us
digitalWrite(TRIG_PIN,
HIGH);
delayMicroseconds(10);
digitalWrite(TRIG_PIN,
LOW);
// Wait for pulse on echo pin
```

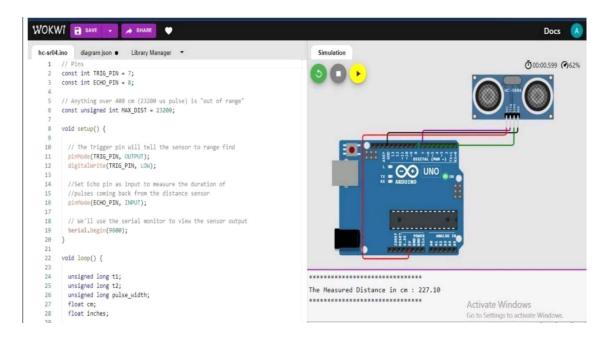
```
while (digitalRead( ECHO_PIN )==0 );
// Measure how long the echo pin was held high (pulse width)
 // Note: the micros() counter will overflow after-70
 mint1= micros ();
 while (digitalRead(ECHO_PIN) ==
  1);t2= micros ();
  pulse_width = t2-t1;
 // Calculate distance in centimeters and inches. The constants
 //are found in the datasheet, and calculated from the assumed speed
 // of sound in air at sea level (-
 340m/s)cm=pulse Width / 58;
 inches = pulse_width/148.0;
// Print out results
if (pulse_width >MAX DIST
){Serial.println("Out of
range");
} else {
Serial.println("******************************);
Serial.print("The Measured Distance in cm: ");
Serial.println(cm);
if( cm < 100 ){
    //while(true){
```

Output:

• If the distance is less than 100 cm, it alerts.



• If the distance is more than 100 cm, it won't alert



Simulation and code execution

