## ASSIGNMENT-4 DISTANCE DETECTION USING ULTRASONIC SENSOR

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Team ID	PNT2022TMID17661
Name	Mogit B T
Student Roll Number	713319EC064
Maximum Marks	2 Marks

## Question 1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 centimeters it should send "alert" to IBM cloud and display in device recent events.

## CODE:

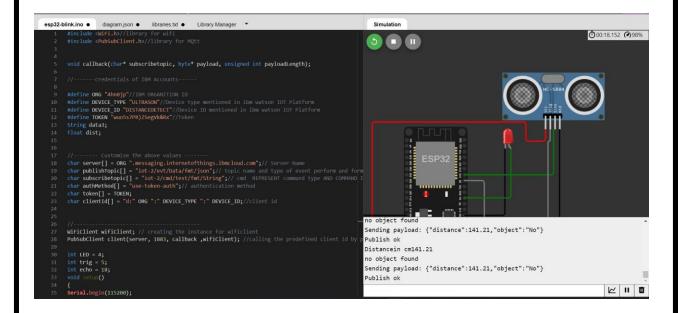
```
#include <WiFi.h>//library for wifi
 void callback(char subscribetopic, byte payload, unsigned int payloadLength);
#define ORG 4h0jp"//IBM ORGANITION IO
#define TOKEN "wuo5s7PR)ZSegvk&Rx"
String data3;
float dist;
char server[] -ORG ".messaging internetofthings.ibmcloud.com";// Server Name
char publishTopic[] "iot-2/evata/fmt/json";
char authMethod[]"use-token-auth";// authentication method
char token[] TOKEN;
char clientId[]"d:" ORG ":" DEVICE_TYPE":"DEVICE_ID;//client id
int LED = 4;
int trig 5;
int echo= 18;
 void setic()
 Serial.begin(115200);
```

```
esp32-blink.ino
                  diagram.json •
                                   libraries.txt ●
                                                  Library Manager *
       pinMode(trig,OUTPUT);
       pinMode(echo,INPUT);
       pinMode(LED, OUTPUT);
       delay(10);
       wificonnect();
       mqttconnect();
       void loop()// Recursive Function
        digitalWrite(trig,LOW);
         digitalWrite(trig,HIGH);
         delayMicroseconds(10);
         digitalWrite(trig,LOW);
         float dur = pulseIn(echo,HIGH);
         float dist = (dur * 0.0343)/2;
         Serial.print ("Distancein cm");
         Serial.println(dist);
         PublishData(dist);
         delay(1000);
         if (!client.loop()) {
         mqttconnect();
       void PublishData(float dist) {
         mqttconnect();//function call for connecting to ibm
```

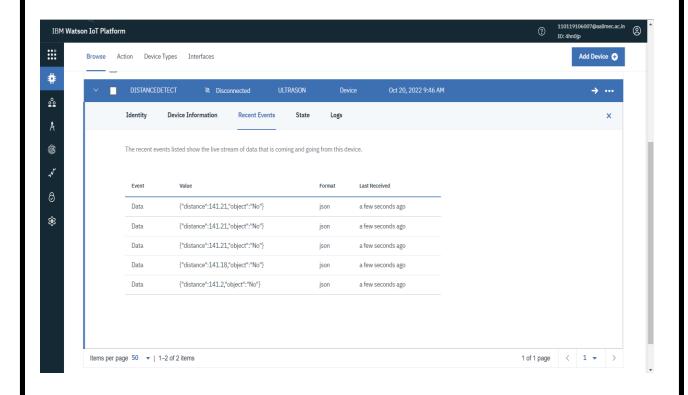
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```
esp32-blink.ino •
                   diagram.json •
                                   libraries.txt ●
                                                  Library Manager
         WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
         while (WiFi.status() != WL_CONNECTED) {
           delay(500);
           Serial.print(".");
         Serial.println("");
         Serial.println("WiFi connected");
         Serial.println("IP address: ");
         Serial.println(WiFi.localIP());
       void initManagedDevice() {
         if (client.subscribe(subscribetopic)) {
           Serial.println((subscribetopic));
           Serial.println("subscribe to cmd OK");
           Serial.println("subscribe to cmd FAILED");
       void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
         Serial.print("callback invoked for topic: ");
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         Serial.println(subscribetopic);
         for (int i = 0; i < payloadLength; i++) {</pre>
           data3 += (char)payload[i];
```

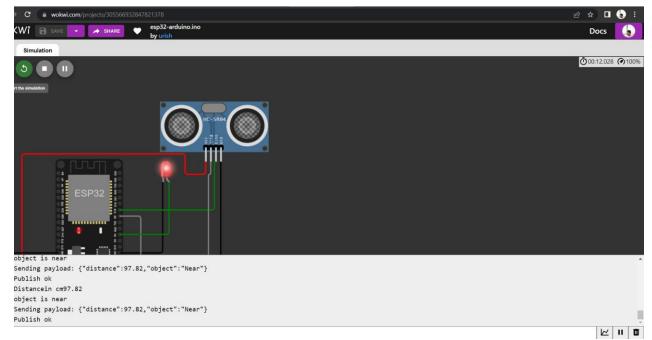
## **OUTPUT:**



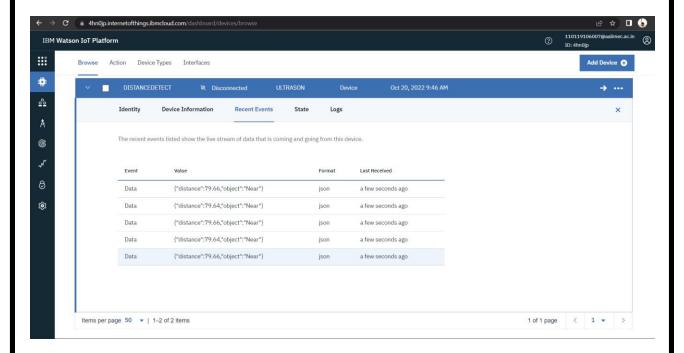
Data send to the IBM cloud device when the object is far



when object is near to the ultrasonic sensor



Data sent to the IBM Cloud Device when the object is near



https://wokwi.com/projects/305566932847821378