

ASSIGNMENT-4

DISTANCE DETECTION USING ULTRASONIC SENSOR

Date	28 October 2022
Team ID	PNT2022TMID17665
Name	Thameemum Ansari A
Student Roll Number	713319EC116
Maximum Marks	2 Marks

Question:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 centimeters it should send "alert" to IBM cloud and display in device recent events

Code:

```
#include <WiFi.h>
#include <PubSubClient.h>
#include <ArduinoJson.h>
```

```
WiFiClient wifiClient;
```

```
#define ORG "9tg03j"
#define DEVICE_TYPE "RaspberryPi"
#define DEVICE_ID "12345"
#define TOKEN "12345678"
#define speed 0.034
```

```
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/status1/fmt/json";
char topic[] = "iot-2/cmd/home/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
```

```
PubSubClient client(server, 1883, wifiClient);
void publishData();
```

```
const int trigpin=5;
```

```

const int echopin=19;
String command;
String data="";
String name="Alert";
String icon="";
long duration;
int dist;
void setup()
{
  Serial.begin(115200);
  pinMode(trigpin, OUTPUT);
  pinMode(echopin, INPUT);
  wifiConnect();
  mqttConnect();
}
void loop() {
  publishData();
  delay(500);
  if (!client.loop()) {
    mqttConnect();
  }
}

void wifiConnect() {
  Serial.print("Connecting to "); Serial.print("Wifi");
  WiFi.begin("Wokwi-GUEST", "", 6);
  while (WiFi.status() != WL_CONNECTED) {
    delay(500);
    Serial.print(".");
  }
  Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
}

void mqttConnect() {
  if (!client.connected()) {
    Serial.print("Reconnecting MQTT client to "); Serial.println(server);
    while (!client.connect(clientId, authMethod, token)) {
      Serial.print(".");
      Serial.print("*");
      delay(1000);
    }
    initManagedDevice();
    Serial.println();
  }
}

void initManagedDevice() {

```

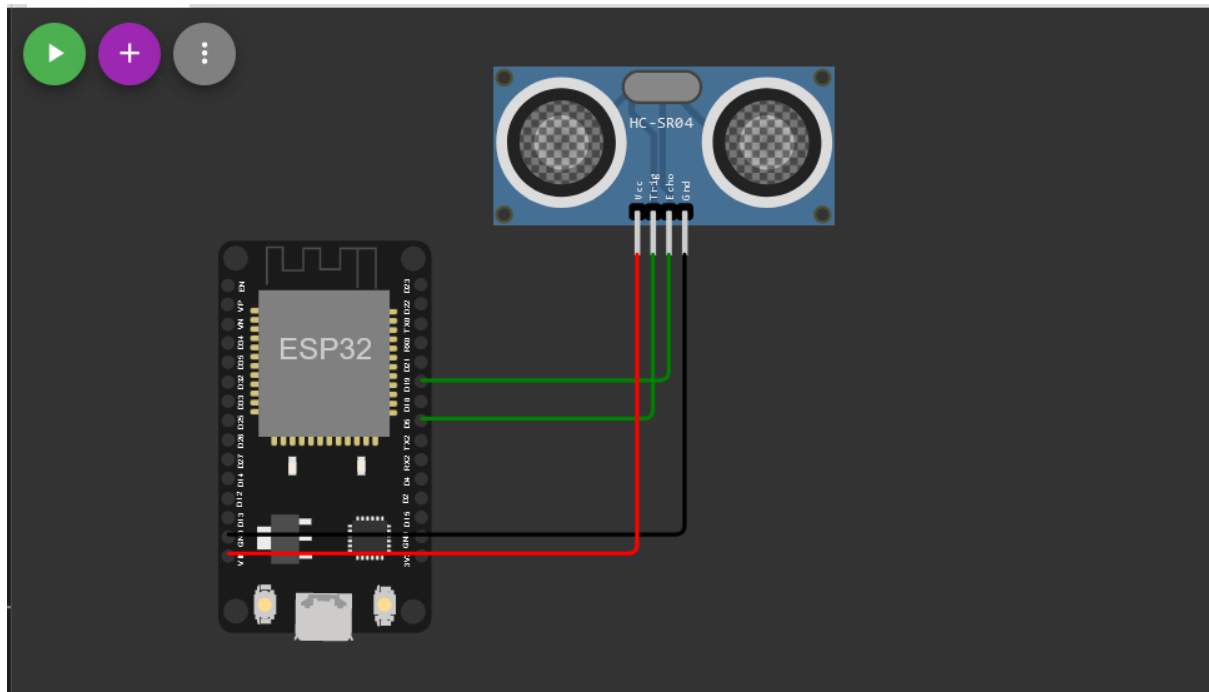
```

if (client.subscribe(topic)) {
    Serial.println(client.subscribe(topic));
    Serial.println("subscribe to cmd OK");
}
else {
    Serial.println("subscribe to cmd FAILED");
}
}

void publishData()
{
    digitalWrite(trigpin,LOW);
    digitalWrite(trigpin,HIGH);
    delayMicroseconds(10);
    digitalWrite(trigpin,LOW);
    duration=pulseIn(echopin,HIGH);
    dist=duration*speed/2;
    if(dist<100){
        dist=100-dist;
        icon="Not-Crashed";
    }
    else{
        dist=0;
        icon="Crashed";
    }
    DynamicJsonDocument doc(1024);
    String payload;
    doc["Name"]=name;
    doc["Impact"]=icon;
    doc["Distance"]=dist;
    serializeJson(doc, payload);
    delay(3000);
    Serial.print("\n");
    Serial.print("Sending payload: ");
    Serial.println(payload);
    if (client.publish(publishTopic, (char*) payload.c_str())) {
        Serial.println("Publish OK");
    }
    else {
        Serial.println("Publish FAILED");
    }
}

```

DIAGRAM:



OUTPUT:

WOKWI [SAVE] [SHARE] Docs

esp32-blink.ino | diagram.json | libraries.txt | Library Manager

```
77 void publishData()
78 {
79     digitalWrite(trigpin, LOW);
80     digitalWrite(trigpin, HIGH);
81     delayMicroseconds(10);
82     digitalWrite(trigpin, LOW);
83     duration=pulseIn(echopin, HIGH);
84     dist=duration*speed/2;
85     if(dist<100){
86         dist=100-dist;
87         icon="Not-Crashed";
88     }
89     else{
90         dist=0;
91         icon="Crashed";
92     }
93     DynamicJsonDocument doc(1024);
94     String payload;
95     doc["Name"] = name;
96     doc["Impact"] = icon;
97     doc["Distance"] = dist;
98     serializeJson(doc, payload);
99     delay(3000);
100     Serial.print("\n");
101     Serial.print("Sending payload: ");
102     Serial.println(payload);
103     if (client.publish(topic, (char*) payload.c_str())) {
104         Serial.println("Publish OK");
105     }
106     else {
107         Serial.println("Publish FAILED");
108     }
109 }
110 }
111 }
```

Simulation 00:53.745 99%

Editing Ultrasonic Distance Sensor
Distance: 79cm

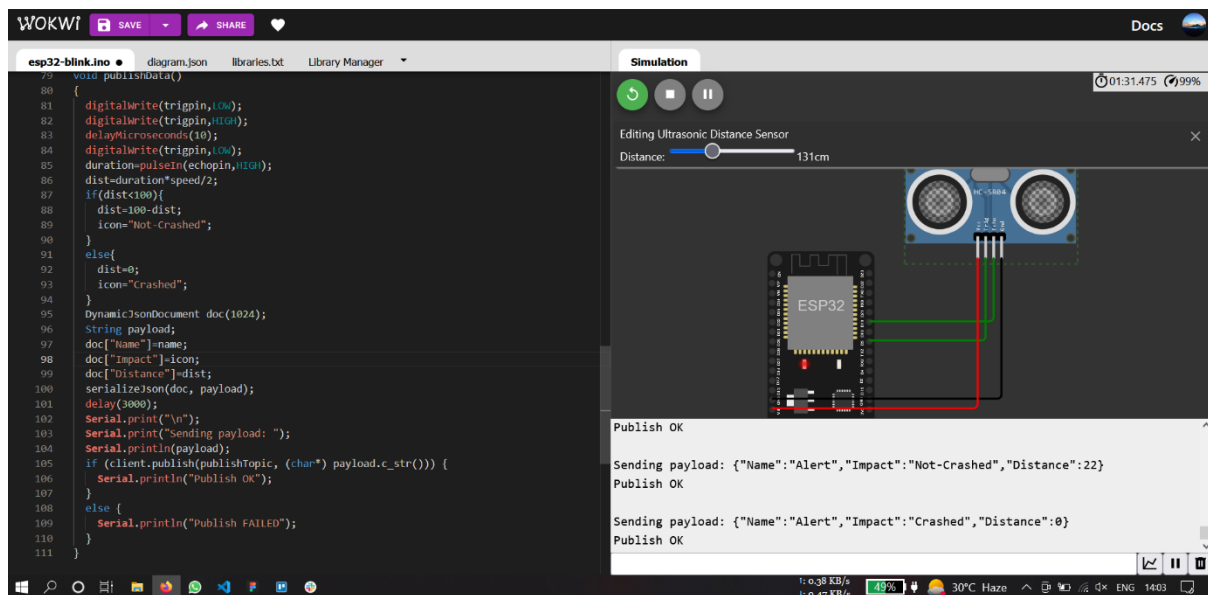
Publish OK

Sending payload: {"Name": "Alert", "Impact": "Not-Crashed", "Distance": 22}
Publish OK

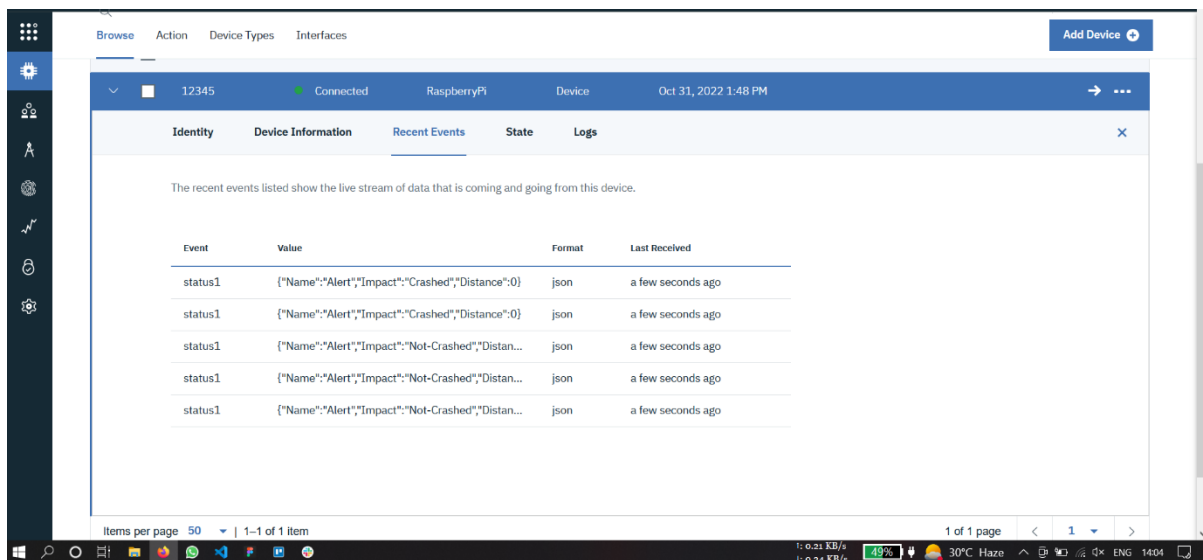
Sending payload: {"Name": "Alert", "Impact": "Not-Crashed", "Distance": 21}
Publish OK

1: 0.53 KB/s
1: 1.42 KB/s

48% 30°C Haze ENG 1403



Data uploaded to Iot Watson Platform



<https://wokwi.com/projects/347020845672038995>