SPRINT 2

Date	10 November 2022
Team ID	PNT2022TMID17635
Project Name	IoT Based Safety Gadget for Child Safety Monitoring and Notification

ALGORITHM:

- ➤ Import Packages
- Create 'myConfig' location
- > Implement the wiotp.sdk.device.DeviceClient
- > Run a while Loop
- > Finally set the latitude and longitude range
- Desired result Obtained

Modified Version of Code according to main project:

```
import json
import wiotp.sdk.device
import time
myConfig={ "identity
    ":{
    "orgId": "hj5fmy", "typeid": "NodeMCU",
    "deviceId": "12345"
    },
```

```
"auth": {
     "token": "12345678
     }
     }
client = wiotp.sdk.device.DeviceClient (config=myConfig, logHandlers=None)
client.connect()
     while True:
     name= "Smartbridge" #in area location
     #latitude- 17.4225176 longitude 78.5450842 #out area location
     latitude = 17.4219272
     longitude =70.5400783
     myData = {'name':name, 'lat':latitude, 'lon': longitude} client.publishEvent
     (eventId="Status", msgformat="json", data=myData,
     qos=0, onPublish=None)
     print ("Data published to IM IoT platfrom: ",myData) time.sleep(5)
     client.disconnect()
 Reference Code:
 import time
 def stopwatch(seconds,d,lspoint):
       start = time.time()
       time.clock()
       elapsed = 0
       flag = False
       num = 0
       while elapsed < seconds:
```

```
print "%02d" % elapsed
            if elapsed > d[num] and elapsed < d[num+1] and flag == False:
                  x = Ispoint[num][0]
                  y = Ispoint[num][1]
                  createpoint(x,y)
                  flag = True
                  print "Shot Taken"
                  print point_in_poly(x,y,polygon)
            if elapsed > d[num+1]:
                  print "Shot Taken"
                  flag == False
                  num = num + 1
                  x = Ispoint[num][0]
                  y = lspoint[num][1]
                  createpoint(x,y)
                  print point_in_poly(x,y,polygon)
            time.sleep(1)
def createpoint(x,y):
 crs = "point?crs=epsg:27700&field=id:integer"
 layer = QgsVectorLayer(crs, 'points', "memory")
  pr = layer.dataProvider()
  pt = QgsFeature()
```

elapsed = time.time() - start

```
point1 = QgsPoint(x,y)
  pt.setGeometry(QgsGeometry.fromPoint(point1)) pr.addFeatures([pt])
   layer.updateExtents()
  pt = QgsFeature()
  QgsMapLayerRegistry.instance().addMapLayers([layer])
def point in poly(x,y,poly):
  n = len(poly)
  inside = False
  p1x,p1y = poly[0]
  for i in range(n+1):
    p2x,p2y = poly[i \% n]
    if y > min(p1y,p2y):
      if y \le max(p1y,p2y):
        if x \le max(p1x,p2x):
           if p1y != p2y:
             xints = (y-p1y)*(p2x-p1x)/(p2y-p1y)+p1x
           if p1x == p2x or x \le x ints:
             inside = not inside
    p1x,p1y = p2x,p2y
  return inside
polygon =
[(512882.78819722467,120811.83924772343),(512960.84437170526,120809.
7007223952),(512960.84437170526,120809.7007223952),(512959.775109041
13,120754.09906386107),(512882.78819722467,120756.2375891893)]
time_seconds = 70
```

```
x = 512915
y = 120728
intervals = int(time_seconds / 10)
lspoint = []
for i in range(0,intervals+1):
        y1 = y + (i*12.5)
        lspoint.append([x,y1])
f = 10
a = 0
b = intervals+1
d = [x * f for x in range(a, b)]
stopwatch(time_seconds,d,lspoint)
```

