# ASSIGNMENT-4 DISTANCE DETECTION USING ULTRASONICSENSOR

Date	01 November 2022
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Number	
Maximum Marks	2 Marks

### **Question:**

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 centimetersit should send "alert" to IBM cloud and display in device recent events

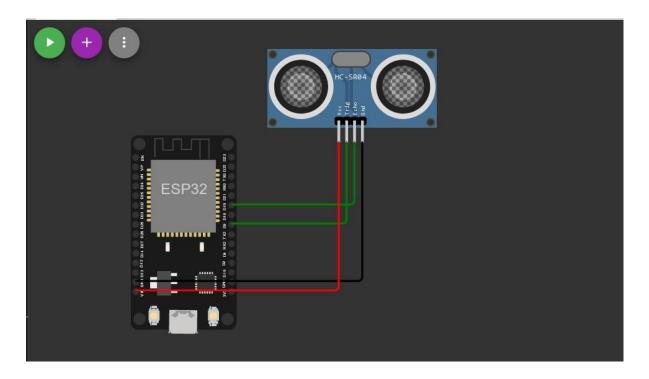
#### Code:

```
#include <WiFi.h>
#include
<PubSubClient.h>
#include <ArduinoJson.h>
WiFiClient wifiClient;
#define ORG "9tg03j"
#define DEVICE TYPE "RaspberryPi"
#define DEVICE ID "12345"
#define TOKEN "12345678"
#define speed 0.034
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/status1/fmt/json";
char topic[] = "iot-2/cmd/home/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE TYPE ":" DEVICE ID;
PubSubClient client(server, 1883, wifiClient);
void publishData();
const int trigpin=5;
```

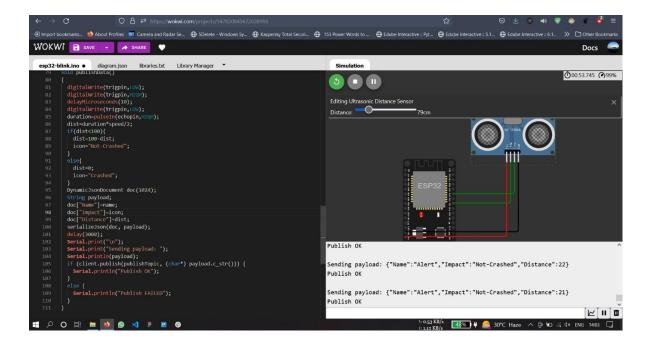
```
const int echopin=19;
String command;
String data="";
String name="Alert";
String icon="";
long duration;
int dist;
void setup()
 Serial.begin(115200);
 pinMode(trigpin, OUTPUT);
 pinMode(echopin, INPUT);
 wifiConnect();
 mqttConnect();
void loop() {
 publishData();
 delay(500);
 if (!client.loop()) {
  mqttConnect();
}
void wifiConnect() {
 Serial.print("Connecting to ");
 Serial.print("Wifi");
 WiFi.begin("Wokwi-GUEST", "", 6);
 while (WiFi.status() != WL CONNECTED) {
  delay(500);
  Serial.print(".");
 Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
void mqttConnect() {
 if (!client.connected()) {
  Serial.print("Reconnecting MQTT client to "); Serial.println(server);
  while (!client.connect(clientId, authMethod, token)) {
  Serial.print(".");
   Serial.print("*");
   delay(1000);
  initManagedDevice();
  Serial.println();
void initManagedDevice() {
```

```
if (client.subscribe(topic)) {
  Serial.println(client.subscribe(topic));
  Serial.println("subscribe to cmd OK");
 else {
  Serial.println("subscribe to cmd FAILED");
void publishData()
 digitalWrite(trigpin,LOW);
 digitalWrite(trigpin,HIGH);
 delayMicroseconds(10);
 digitalWrite(trigpin,LOW);
 duration=pulseIn(echopin,HIGH);
 dist=duration*speed/2;
 if(dist<100){
  dist=100-dist;
  icon="Not-Crashed";
 else{
  dist=0;
  icon="Crashed";
 DynamicJsonDocument doc(1024);
 String payload;
 doc["Name"]=name;
 doc["Impact"]=icon;
 doc["Distance"]=dist;
 serializeJson(doc, payload);
 delay(3000);
 Serial.print("\n");
 Serial.print("Sending payload: ");
 Serial.println(payload);
 if (client.publish(publishTopic, (char*) payload.c str())) {
  Serial.println("Publish OK");
 else {
  Serial.println("Publish FAILED");
}
```

#### **DIAGRAM:**

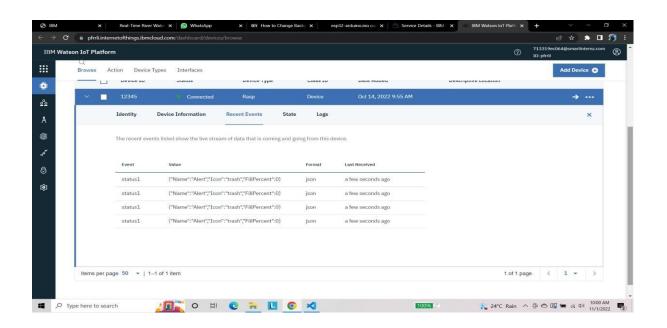


## **OUTPUT:**



```
| Simulation | Si
```

## Data uploaded to Iot Watson Platform



https://wokwi.com/projects/347824265812247123