

Date	5 November 2022
Team ID	PNT2022TMID17659
Project Name	Smart waste management system for metropolitan cities
Story Points	15

## Sprint 2

Develop the python code to find the GPS location using Latitude and Longitude (random values) and send it to Node red using IBM Watson platform and view location of bins on map

### **PYTHON CODE :**

```
import wiotp.sdk.device
import time
import random

myConfig = {
    "identity": {
        "orgId": "fzv53v",
        "typeId": "Bin",
        "deviceId": "Bin_1"
    },
    "auth": {
        "token": "1234567890"
    }
}

def myCommandCallback (cmd):
    print ("Message received from IBM IoT Platform: %s" % cmd.data['command'])
    m=cmd.data['command']
```

```

client = wiotp.sdk.device.DeviceClient(config=myConfig, logHandlers=None)

client.connect()

def pub (data):

    client.publishEvent(eventId="status", msgFormat="json", data=myData, qos=0,
onPublish=None)

    print ("Published data Successfully: %s", myData)

while True:

    myData={'name': 'Bin1', 'lat': 13.092677, 'lon': 80.188314}

    pub (myData)

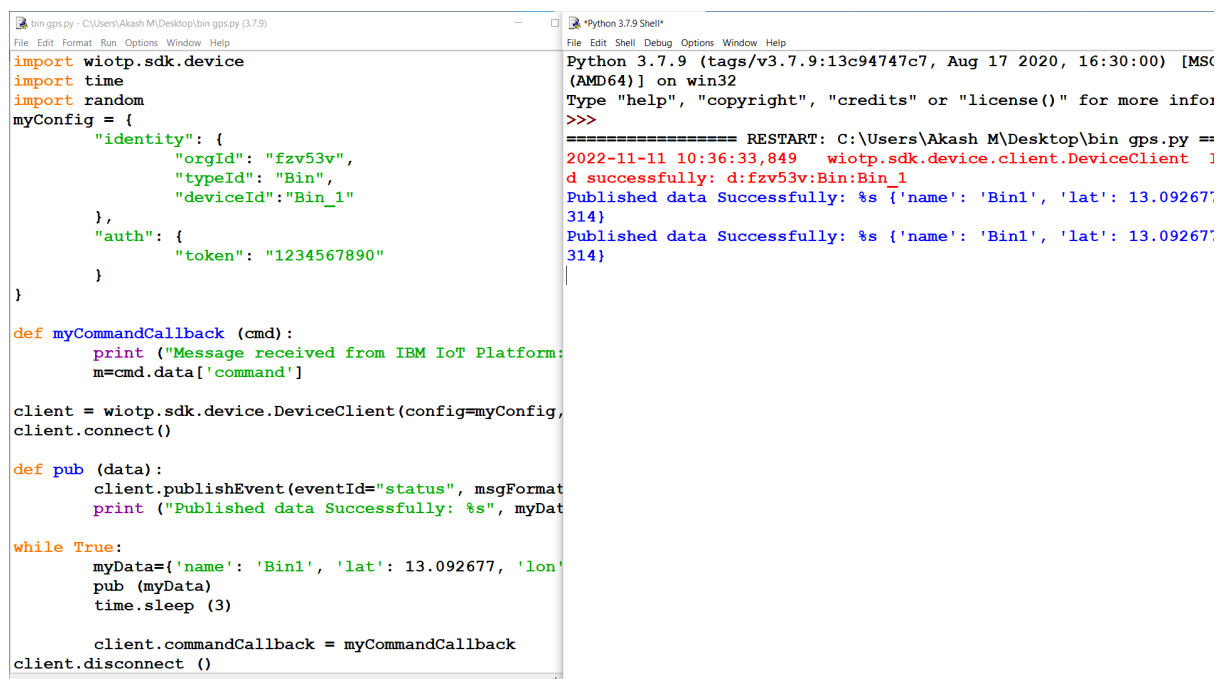
    time.sleep (3)

    client.commandCallback = myCommandCallback

client.disconnect ()

```

## Output in python IDLE :



The screenshot shows the Python IDLE interface with a script on the left and its output on the right. The script defines a configuration for a DeviceClient, connects to the IBM Watson IoT Platform, and publishes data in a loop. The output shows the successful connection and data publication.

```

bin gps.py - C:\Users\Akash M\Desktop\bin gps.py (3.7.9)
File Edit Format Run Options Window Help
import wiotp.sdk.device
import time
import random
myConfig = {
    "identity": {
        "orgId": "fzv53v",
        "typeId": "Bin",
        "deviceId": "Bin_1"
    },
    "auth": {
        "token": "1234567890"
    }
}

def myCommandCallback (cmd):
    print ("Message received from IBM IoT Platform: ", cmd)
    m=cmd.data['command']

client = wiotp.sdk.device.DeviceClient(config=myConfig,
client.connect()

def pub (data):
    client.publishEvent(eventId="status", msgFormat="json", data=myData, qos=0,
onPublish=None)
    print ("Published data Successfully: %s", myData)

while True:
    myData={'name': 'Bin1', 'lat': 13.092677, 'lon': 80.188314}
    pub (myData)
    time.sleep (3)

    client.commandCallback = myCommandCallback
client.disconnect ()

```

```

Python 3.7.9 (tags/v3.7.9:13c94747c7, Aug 17 2020, 16:30:00) [MS
(AMD64)] on win32
Type "help", "copyright", "credits" or "license()" for more info
>>>
===== RESTART: C:\Users\Akash M\Desktop\bin gps.py ==
2022-11-11 10:36:33,849 wiotp.sdk.device.client.DeviceClient : ]
d successfully: d:fzv53v:Bin:Bin_1
Published data Successfully: %s {'name': 'Bin1', 'lat': 13.092677, 'lon': 80.188314}
Published data Successfully: %s {'name': 'Bin1', 'lat': 13.092677, 'lon': 80.188314}

```

## IBM Watson IOT platform :

The screenshot shows the IBM Watson IoT Platform dashboard. The top navigation bar includes 'Browse', 'Action', 'Device Types', and 'Interfaces'. A search bar is present with the text 'Search by Device ID'. The main content area displays a table of devices. The first device is highlighted with ID 12345, status 'Disconnected', and type 'Rasp'. Below the table, a detailed view for this device is shown, including fields for Device ID, Device Type, Date Added, Added By, and Connection Status. The bottom status bar indicates '1 Simulation running'.

Device ID	Status	Device Type	Class ID	Date Added	Descriptive Location
12345	Disconnected	Rasp	Device	Nov 12, 2022 10:39 AM	

Identity	Device Information	Recent Events	State	Logs
Device ID	12345			
Device Type	Rasp			
Date Added	Nov 12, 2022 10:39 AM			
Added By	mithradhanalakshmi915@gmail.com			
Connection Status	Disconnected			

## Node Red Platform :

The screenshot shows the Node-RED web interface. The left sidebar contains a 'parser' section with a 'json' node. The main workspace displays a flow diagram where an 'IBM IoT' node (labeled 'connected') is connected to three output nodes: 'weight', 'msg.payload', and 'location'. The right sidebar shows a 'dashboard' section with 'Layout', 'Site', and 'Theme' tabs, and a 'Tabs & Links' section with a 'Smart Waste Management System' link.