# ASSIGNMENT-4

## Wokwi **Program**

| Assignment Date | 19 October 2022 |
|---|---|
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| Maximum Marks | 2 Marks |

**Question-1**

Write code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100 cms send an "alert" to the IBM cloud and display in the device recent events.
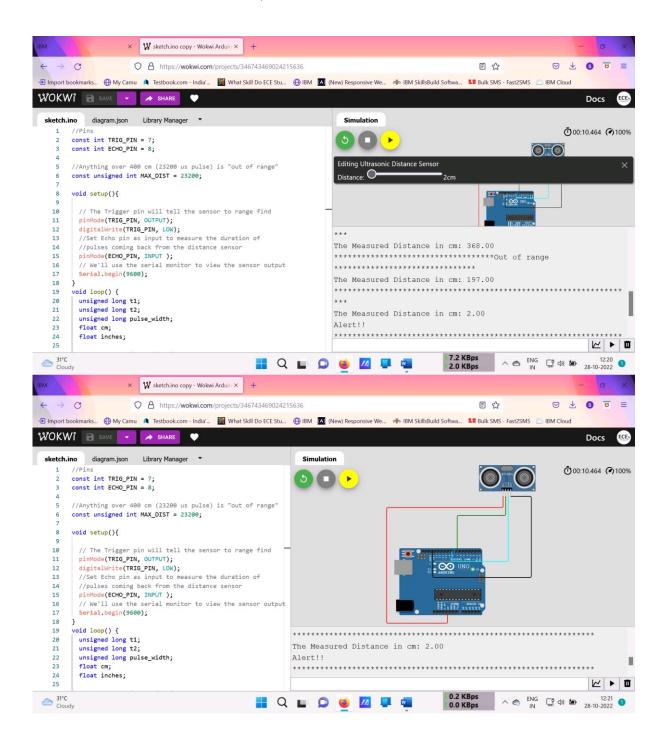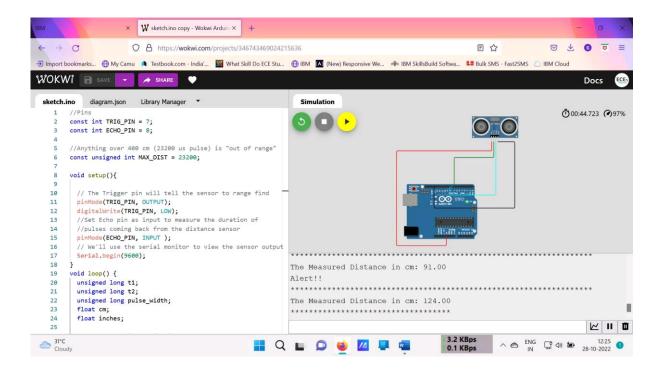
Program

```cpp
//Pins
const int TRIG_PIN =
7; const int ECHO_PIN
= 8;

//Anything over 400 cm (23200 us pulse) is "out of
range" const unsigned int MAX_DIST = 23200;

void setup(){

  // The Trigger pin will tell the sensor to range
  find pinMode(TRIG_PIN, OUTPUT);
  digitalWrite(TRIG_PIN, LOW);
  //Set Echo pin as input to measure the duration of
  //pulses coming back from the distance
  sensor pinMode(ECHO_PIN, INPUT );
  // We'll use the serial monitor to view the sensor output
  Serial.begin(9600);
}
void loop() {
  unsigned long
  t1; unsigned
  long t2;
  unsigned long
  pulse_width; float cm;
  float inches;

  // Hold the trigger pin high for at least
  10 us digitalWrite(TRIG_PIN, HIGH);
  delayMicroseconds(10);
  digitalWrite(TRIG_PIN, LOW);
```

```arduino
  // Wait for pulse on echo pin
  while (digitalRead( ECHO_PIN )==0 );

  // Measure how long the echo pin was held high (pulse width)
  // Note: the micros() counter will overflow after-
70 min t1= micros ();
  while (digitalRead(ECHO_PIN) ==
1); t2= micros ();
  pulse_width = t2-t1;
  // Calculate distance in centimeters and inches. The constants
  //are found in the datasheet, and calculated from the assumed speed
  // of sound in air at sea level (-
340m/s) cm=pulse_width/ 58 ;
  inches = pulse_width/148.0;
  // Print out results
  if (pulse_width>MAX_DIST){
    Serial.println("Out of range");
    }
    else{
      Serial.println(
      "*****************************"); Serial.
      print("The Measured Distance in cm: ");
      Serial.println(cm);

      if( cm < 100 ){
        //while(true){
          Serial.println("Alert!!");
          //}
    }
    Serial.print("*********************************");
    }
//wait at least 1000ms before next
measurement delay(1000);
}
```

# Output

If the distance is less than 100 cms ,it alerts.

Link:
https://wokwi.com/projects/346743469024215636