# SMART HOME USING TINKERCAD IBM ASSIGNMENT - 1

#### **DESCRIPTION:**

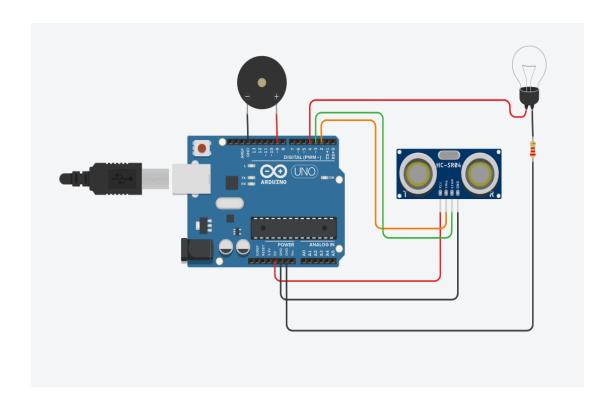
The circuit is a basic version of smart home using ultrasonic sensor which turns on the buzzer, bulb and setting doors open from close state while the person is within a particular range being set. Here the range being set is 15cm.

#### **CODE**:

```
int trigger_pin = 2;
int echo_pin = 3;
int buzzer_pin = 9;
int bulb_pin = 4;
int time;
int distance;
void setup()
{
    Serial.begin (9600);
    pinMode (trigger_pin, OUTPUT);
    pinMode (echo_pin, INPUT);
    pinMode (buzzer_pin, OUTPUT);
    pinMode (bulb_pin, OUTPUT);
}
void loop()
```

```
{
  digitalWrite (trigger_pin, HIGH);
  delayMicroseconds (10);
  digitalWrite (trigger_pin, LOW);
  time = pulseIn (echo_pin, HIGH);
  distance = (time * 0.034) / 2;
if (distance <= 15)
    Serial.println (" Door Open ");
    Serial.print (" Distance= ");
    Serial.println (distance);
    digitalWrite (buzzer_pin, HIGH);
     digitalWrite (bulb_pin, HIGH);
    delay (500);
else {
    Serial.println (" Door closed ");
    Serial.print (" Distance= ");
    Serial.println (distance);
    digitalWrite (buzzer_pin, LOW);
     digitalWrite (bulb_pin, LOW);
    delay (500);
}
```

### **CIRCUIT**:



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