

#### Assignment -4

Assignment Date	19 September 2022
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Maximum Marks	2 Marks

Reference link:

<https://wokwi.com/projects/312346565007114818>

```
#include "Ultrasonic.h"
```

```
Ultrasonic::Ultrasonic(uint8_t trigPin, uint8_t echoPin, unsigned long timeOut) {  
    trig = trigPin;  
    echo = echoPin;  
    threePins = trig == echo ? true : false;  
    pinMode(trig, OUTPUT);  
    pinMode(echo, INPUT);  
    timeout = timeOut;  
}
```

```
unsigned int Ultrasonic::timing() {
```

```
    if (threePins)  
        pinMode(trig, OUTPUT);
```

```
    digitalWrite(trig, LOW);  
    delayMicroseconds(2);  
    digitalWrite(trig, HIGH);  
    delayMicroseconds(10);  
    digitalWrite(trig, LOW);
```

```
    if (threePins)  
        pinMode(trig, INPUT);
```

```
    previousMicros = micros();  
    while(!digitalRead(echo) && (micros() - previousMicros) <= timeout); // wait for the echo pin HIGH  
    or timeout
```

```
    previousMicros = micros();  
    while(digitalRead(echo) && (micros() - previousMicros) <= timeout); // wait for the echo pin LOW or  
    timeout
```

```
    return micros() - previousMicros; // duration  
}
```

```
/*
```

```
* If the unit of measure is not passed as a parameter,
```

```

* sby default, it will return the distance in centimeters.
* To change the default, replace CM by INC.
*/
unsigned int Ultrasonic::read(uint8_t und) {
    return timing() / und / 2; //distance by divisor
}

/*
* This method is too verbal, so, it's deprecated.
* Use read() instead.
*/
unsigned int Ultrasonic::distanceRead(uint8_t und) {
    return read(und);
}
class Ultrasonic {
public:
    Ultrasonic(uint8_t sigPin) : Ultrasonic(sigPin, sigPin) {};
    Ultrasonic(uint8_t trigPin, uint8_t echoPin, unsigned long timeOut = 20000UL);
    unsigned int read(uint8_t und = CM);
    unsigned int distanceRead(uint8_t und = CM) __attribute__((deprecated ("This method is
deprecated, use read() instead.")));
    void setTimeout(unsigned long timeOut) {timeout = timeOut;}
    void setMaxDistance(unsigned long dist) {timeout = dist*CM*2;}

private:
    uint8_t trig;
    uint8_t echo;
    boolean threePins = false;
    unsigned long previousMicros;
    unsigned long timeout;
    unsigned int timing();
};

```

