Assignment-4

BATCH NO: B9-3A5E

| Assignment Date | 19 October 2022 |
|---------------------|-----------------|
| Student Name | Akilan K |
| Student Roll Number | 962219205006 |
| Maximum Marks | 2 Marks |

WokWi Link: https://wokwi.com/projects/347843333031199315

```
Program:
#include <WiFi.h>
#include <PubSubClient.h>
#include <ArduinoJson.h>
WiFiClient wifiClient;
```

```
#define ORG "7h1uma"
#define DEVICE_TYPE "eps32"
#define DEVICE_ID "12345"
#define TOKEN "123456789"
#define speed 0.034
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Data/fmt/json";
char topic[] = "iot-2/cmd/home/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);
void publishData();
const int trigpin=5;
const int echopin=18;
String command;
String data="";
long duration;
int dist;
void setup()
 Serial.begin(115200);
 pinMode(trigpin, OUTPUT);
 pinMode(echopin, INPUT);
 wifiConnect();
```

mqttConnect();

}

```
void loop() {
  publishData();
  delay(500);
  if (!client.loop()) {
   mqttConnect();
  }
}
void wifiConnect() {
  Serial.print("Connecting to "); Serial.print("Wifi");
 WiFi.begin("Wokwi-GUEST", "", 6);
  while (WiFi.status() != WL_CONNECTED) {
    delay(500);
    Serial.print(".");
  }
  Serial.print("WiFi connected, IP address: ");
Serial.println(WiFi.localIP());
void mqttConnect() {
  if (!client.connected()) {
    Serial.print("Reconnecting MQTT client to "); Serial.println(server);
    while (!client.connect(clientId, authMethod, token)) {
      Serial.print(".");
      delay(1000);
    }
    initManagedDevice();
    Serial.println();
}
void initManagedDevice() {
  if (client.subscribe(topic)) {
    Serial.println(client.subscribe(topic));
    Serial.println("subscribe to cmd OK");
  } else {
    Serial.println("subscribe to cmd FAILED");
  }
}
void publishData()
  digitalWrite(trigpin,LOW);
  digitalWrite(trigpin,HIGH);
  delayMicroseconds(10);
  digitalWrite(trigpin,LOW);
  duration=pulseIn(echopin,HIGH);
  dist=duration*speed/2;
  if(dist<100){</pre>
    DynamicJsonDocument doc(1024);
```

```
String payload;
doc["AlertDistance:"]=dist;
serializeJson(doc, payload);
delay(3000);
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c_str())) {
    Serial.println("Publish OK");
} else {
    Serial.println("Publish FAILED");
}
}
```

Output:



