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import requests
import json
import ibmiotf.application
import ibmiotf.device
import time
import random
import sys

# watson device details

organization = "7tbb1b"
devicType = "Trashbin2"
deviceId = "Trashbinid2"
authMethod= "token"
authToken= "123456789"

#generate random values for randomo variables (temperature&humidity)

def myCommandCallback(cmd):
    global a
    print("command recieved:%s" %cmd.data['command'])
    control=cmd.data['command']
    print(control)

try:
    deviceOptions={"org": organization, "type": devicType,"id": deviceId,"auth-
method":authMethod,"auth-token":authToken}
    deviceCli = ibmiotf.device.Client(deviceOptions)
except Exception as e:
    print("caught exception connecting device %s" %str(e))
    sys.exit()

deviceCli.connect()

while True:

    ultrasonic= random.randint(10,70)
    loadcell= random.randint(5,15)
    data= {'dist':ultrasonic,'load':loadcell}

    if loadcell < 13 and loadcell > 15:
        load = "90 %"

    elif loadcell < 8 and loadcell > 12:
        load = "60 %"

    elif loadcell < 4 and loadcell > 7:
        load = "40 %"
    else:
        load = "0 %"

    if ultrasonic < 10:
        dist = ' 90 %'

    elif ultrasonic < 20 and ultrasonic >11:
        dist = '60%'

    elif ultrasonic < 60 and ultrasonic > 41:
        dist = '40 %'
    elif ultrasonic < 80 and ultrasonic > 61:
        dist = '20 %'

    if load == "90 %" or ultrasonic == "90 %":
        warn = 'alert :' ' Dumpster poundage getting high, Time to collect :)'

    elif load == "60 %" or ultrasonic == "60 %":

        warn = 'alert :' ' dumpster is above 60%'
    else :
        warn = 'alert :' 'No need to collect right now '
    def myOnPublishCallback(lat=10.678991,long=78.177731):
        print("")
        print("published distance = %s " %ultrasonic,"loadcell:%s " %loadcell,"lon = %s " %long,"lat
= %s" %lat)

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        print(load)
        print(dist)
        print(warn)

time.sleep(5)

success=deviceCli.publishEvent ("IoTSensor","json",warn,qos=0,on_publish= myOnPublishCallback)

success=deviceCli.publishEvent ("IoTSensor","json",data,qos=0,on_publish= myOnPublishCallback)


if not success:
    print("not connected to ibmiot")
time.sleep(5)


deviceCli.commandCallback=myCommandCallback
#disconnect the device
deviceCli.disconnect()
```