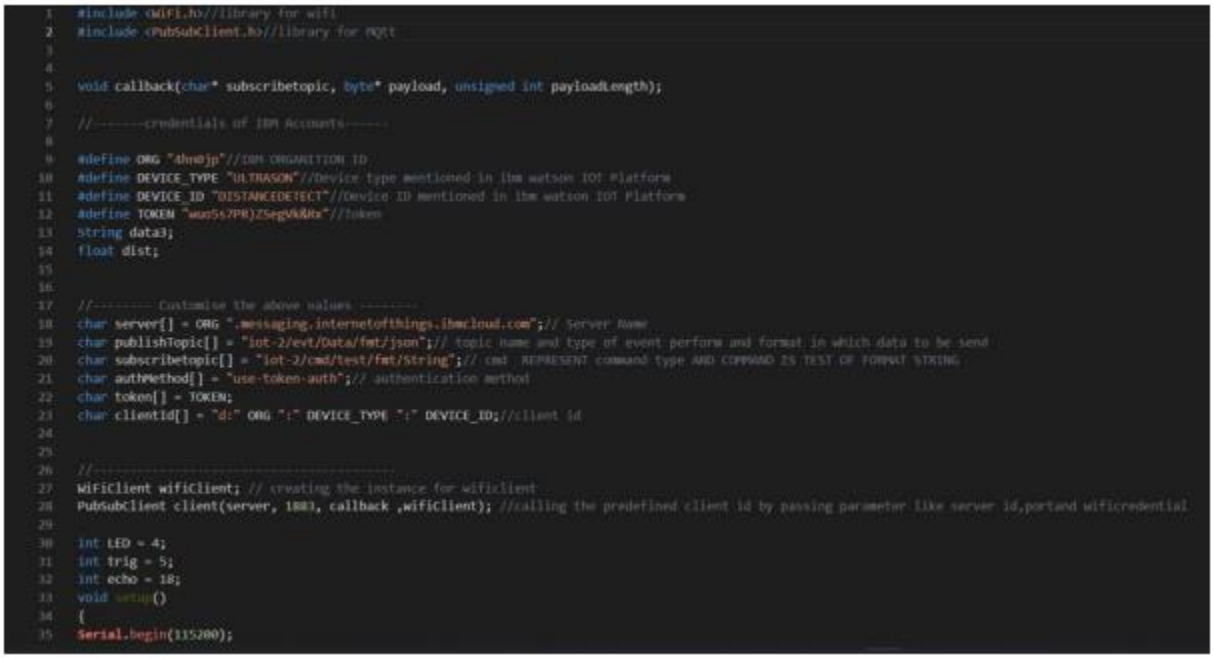
ASSIGNMENT-4

DISTANCE DETECTION USING ULTRASONIC SENSOR

Question: Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

Code:



```
#include <WiFi.h>//library for wifi
#include <PubSubClient.h>//library for MQTT


void callback(char* subscribetopic, byte* payload, unsigned int payloadLength);

//-------credentials of IBM Accounts------

#define ORG "4hn0jp"//IBM ORGANITION ID
#define DEVICE_TYPE "ULTRASON"//Device type mentioned in ibm watson IOT Platform
#define DEVICE_ID "DISTANCEDETECT"//Device ID mentioned in ibm watson IOT Platform
#define TOKEN "wuo5s?PR)ZSegVA&Rx"//Token
String data3;
float dist;


//-------- Customise the above values ---------
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";// Server Name
char publishTopic[] = "iot-2/evt/Data/fmt/json";// topic name and type of event perform and format in which data to be send
char subscribetopic[] = "iot-2/cmd/test/fmt/String";// cmd  REPRESENT command type AND COMMAND IS TEST OF FORMAT STRING
char authMethod[] = "use-token-auth";// authentication method
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;//client id


//-----------------------------------------
WiFiClient wifiClient; // creating the instance for wificlient
PubSubClient client(server, 1883, callback ,wifiClient); //calling the predefined client id by passing parameter like server id,portand wificredential

int LED = 4;
int trig = 5;
int echo = 18;
void setup()
{
Serial.begin(115200);
```

```
pinMode(trig,OUTPUT);
pinMode(echo,INPUT);
pinMode(LED, OUTPUT);
delay(10);
wificonnect();
mqttconnect();
}
void loop()// Recursive Function
{

 digitalWrite(trig,LOW);
  digitalWrite(trig,HIGH);
  delayMicroseconds(10);
  digitalWrite(trig,LOW);
  float dur = pulseIn(echo,HIGH);
  float dist = (dur * 0.0343)/2;
  Serial.print ("Distancein cm");
  Serial.println(dist);


  PublishData(dist);
  delay(1000);
  if (!client.loop()) {
    mqttconnect();
  }
}



/*.....retrieving to Cloud.....*/

void PublishData(float dist) {
  mqttconnect();//function call for connecting to ibm
  /*
     creating the String in in form JSon to update the data to ibm cloud
```

```
    creating the String in in form JSon to update the data to ibm cloud
  */
  String object;
  if (dist <100)
  {
    digitalWrite(LED,HIGH);
    Serial.println("object is near");
    object = "Near";
  }
  else
  {
    digitalWrite(LED,LOW);
    Serial.println("no object found");
    object = "No";
  }

  String payload = "{\"distance\":";
  payload += dist;
  payload += "," "\"object\":\"";
  payload += object;
  payload += "\"}";


  Serial.print("Sending payload: ");
  Serial.println(payload);
```

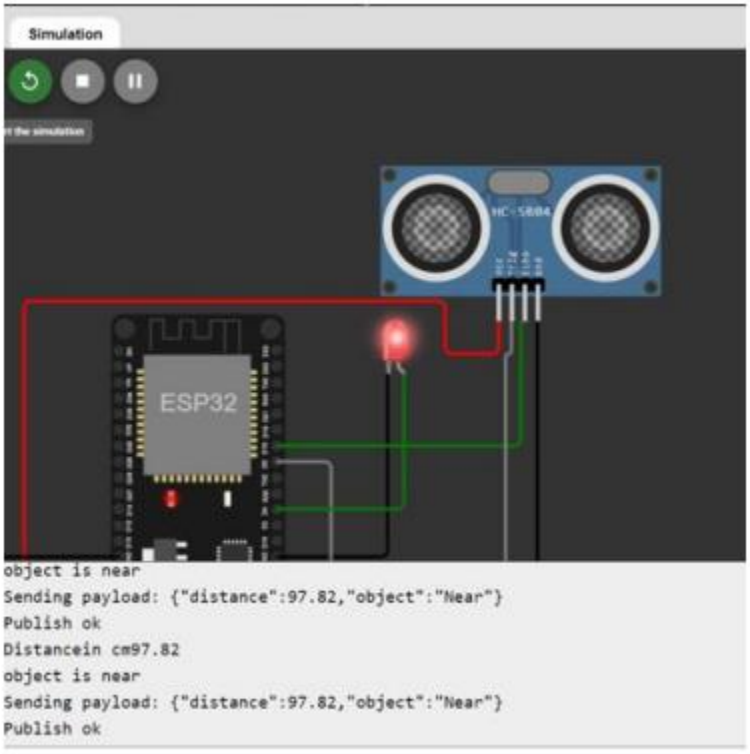
```
  if (client.publish(publishTopic, (char*) payload.c_str())) {
    Serial.println("Publish ok");// if it successfully upload data on the cloud then it will print publish ok in Serial monitor or else it will print publish failed
  } else {
    Serial.println("Publish failed");
  }

}
void mqttconnect() {
  if (!client.connected()) {
    Serial.print("Reconnecting client to ");
    Serial.println(server);
    while (!!!client.connect(clientId, authMethod, token)) {
      Serial.print(".");
      delay(500);
    }

    initManagedDevice();
    Serial.println();
  }
}
void wificonnect() //function defination for wificonnect
{
  Serial.println();
  Serial.print("Connecting to ");

  WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
  while (WiFi.status() != WL_CONNECTED) {
    delay(500);
    Serial.print(".");
  }
  Serial.println("");
  Serial.println("WiFi connected");
  Serial.println("IP address: ");
  Serial.println(WiFi.localIP());
```

```
  Serial.println("WiFi connected");
  Serial.println("IP address: ");
  Serial.println(WiFi.localIP());
}

void initManagedDevice() {
  if (client.subscribe(subscribetopic)) {
    Serial.println((subscribetopic));
    Serial.println("subscribe to cmd OK");
  } else {
    Serial.println("subscribe to cmd FAILED");
  }
}

void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
{

  Serial.print("callback invoked for topic: ");
  Serial.println(subscribetopic);
  for (int i = 0; i < payloadLength; i++) {
    //Serial.print((char)payload[i]);
    data3 += (char)payload[i];
  }

//   Serial.println("data: "+ data3);
//   if(data3=="Near")
//   {
// Serial.println(data3);
```

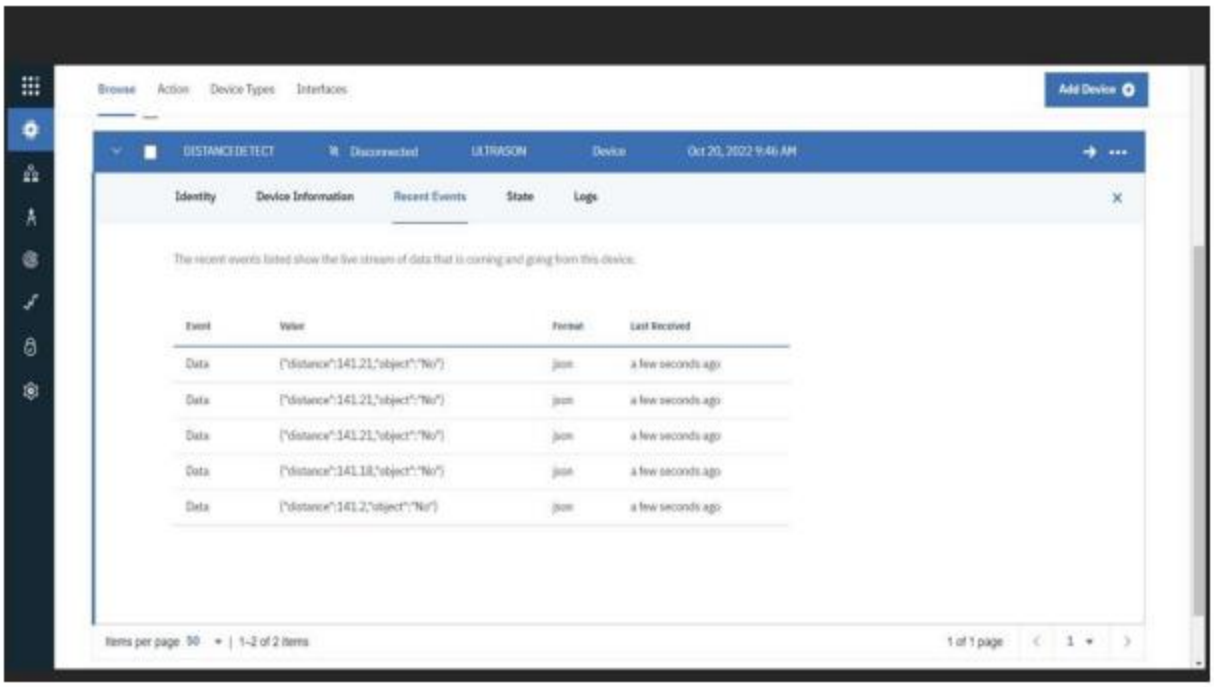
```
//   Serial.println("data: "+ data3);
//   if(data3=="Near")
//   {
// Serial.println(data3);
// digitalWrite(LED,HIGH);

//   }

//   else
//   {
// Serial.println(data3);
// digitalWrite(LED,LOW);

//   }
data3="";


}
```

Output:

When object is near to the ultrasonic sensor



Data sent to the IBM Cloud device when the object is near


Browse
Action
Device Types
Interfaces
Add Device
DISTANCE DETECT
Disconnected
ULTRASON
Device
Oct 20, 2022 9:46 AM
Identity
Device Information
Recent Events
State
Logs
The recent events listed show the live stream of data that is coming and going from this device.
Event
Value
Format
Last Received
Data
{"distance":141.21,"object":"No"}
json
a few seconds ago
Data
{"distance":141.21,"object":"No"}
json
a few seconds ago
Data
{"distance":141.21,"object":"No"}
json
a few seconds ago
Data
{"distance":141.18,"object":"No"}
json
a few seconds ago
Data
{"distance":141.2,"object":"No"}
json
a few seconds ago
Items per page: 50
1–2 of 2 items
1 of 1 page
1

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