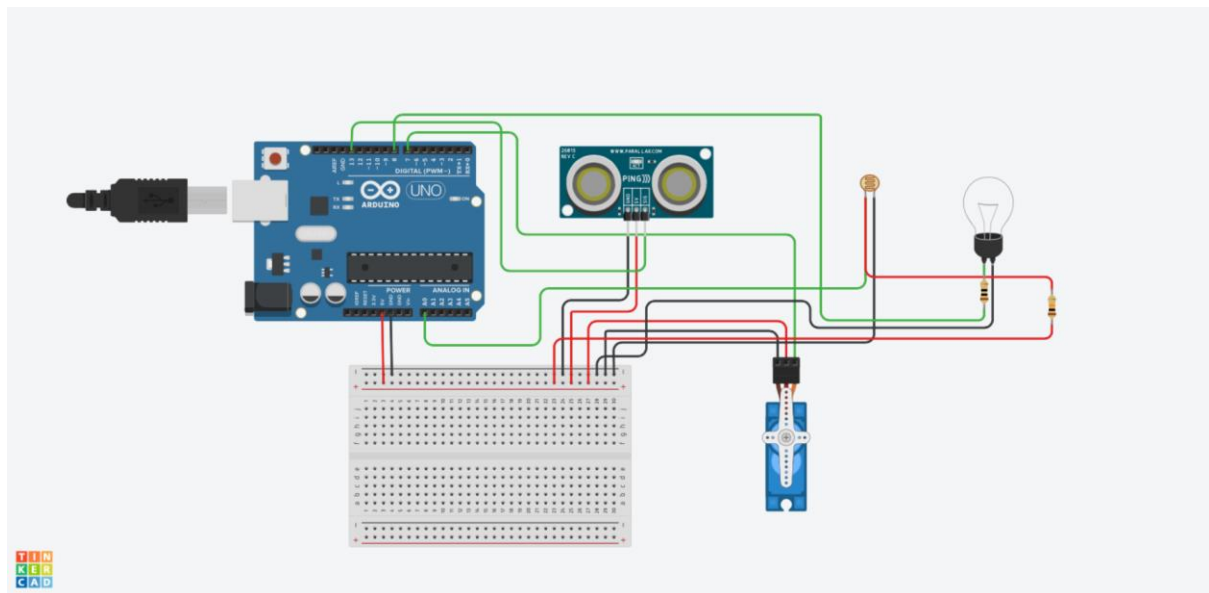


Assignment Date	14 September 2022
Student Name	Abishek R
Student Roll Number	2019504503
Maximum Marks	2 Marks

## ASSIGNMENT-1

### SMART HOME AUTOMATION

**Circuit Design:**



**Source code:**

```
#include <Servo.h>

int output1Value = 0;
int sen1Value = 0;
int sen2Value = 0;
int const LDR = A0;

int USdis(int triggerPin, int echoPin)
{
```

```

        pinMode(triggerPin, OUTPUT);
        digitalWrite(triggerPin, LOW);
        delayMicroseconds(2);
        digitalWrite(triggerPin, HIGH);
        delayMicroseconds(10);
        digitalWrite(triggerPin, LOW);
        pinMode(echoPin, INPUT);
        return pulseIn(echoPin, HIGH);
    }

    Servo servo_7;

    void setup()
    {
        Serial.begin(9600);
        pinMode(A0, INPUT);
        pinMode(13, INPUT);
        servo_7.attach(7, 500, 2500);
        pinMode(8, OUTPUT);
    }

    void loop()
    {
        int val1 = analogRead(LDR);
        if (val1 > 90)
        {
            digitalWrite(8, HIGH);
            Serial.print("Bulb OFF = ");
            Serial.print(val1);
        }
        else
        {
            digitalWrite(8, LOW);
            Serial.print("Bulb ON = ");
            Serial.print(val1);
        }

        sen1Value = 0.01723 * USdis(6, 6);
        if (sen1Value < 100)
        {
            servo_7.write(90);
            Serial.print("Door is Open: Distance = ");
            Serial.print(sen1Value);
            Serial.print("\n");
            delay(1000);
            servo_7.write(0);
        }
    }

```

```
Serial.print("Door is Closed: Distance = ");
Serial.print(sen1Value);
Serial.print("\n");
}
else
{
servo_7.write(0);
Serial.print("          || Door Closed! ; Distance = ");
Serial.print(sen1Value);
Serial.print("\n");
}
delay(10);
```