### **ASSIGNMENT 4**

Team ID	PNT2022TMID46688
Project Name	Real time river water quality
	monitoring and Control System

Project Title: Real Time River water quality monitoring and Control system

Team ID: PNT2022TMID46688

### **OUESTION:**

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

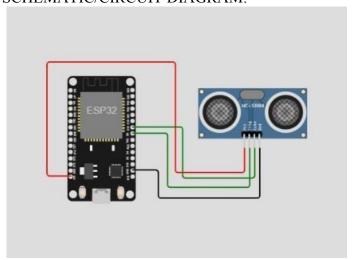
```
CODE:
#include <WiFi.h>
#include
<PubSubClient.h>
void callback(char*
                      subscribe topic, byte*
                                               payload,
                                                          unsigned
payloadLength);
//----credentials of IBM Accounts-----
#define ORG "Ashfaq1824"//IBM ORGANITION ID
#define DEVICE TYPE "ESP32"//Device type mentioned in ibm watson IOT Platform
#define DEVICE ID "12345"//Device ID mentioned in ibm watson IOT Platform
#define TOKEN "12345678" //Token
String data3;
char
                                                     ORG
                 server[]
".messaging.internetofthings.ibmcloud.com";
                                                      char
publishTopic[] = "iot-2/evt/Data/fmt/json"; charsubscribetopic[]
= "iot-2/cmd/test/fmt/String"; char authMethod[] = "use-token-
auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE TYPE ":" DEVICE ID;
WiFiClient wifiClient;
PubSubClient client(server, 1883, callback, wifiClient);
const int trigPin = 5;
const int echoPin = 18;
```

```
#define
            SOUND SPEED
0.034 long duration; float
distance;
           void
                 setup()
        {Serial.begin(115200);
pinMode(trigPin, OUTPUT);
pinMode(echoPin,
                   INPUT);
wificonnect(); mqttconnect();
       void
                loop()
       {digitalWrite(trigPin,
       LOW);
delayMicroseconds(2);
digitalWrite(trigPin, HIGH);
delayMicroseconds(10);
digitalWrite(trigPin,
                      LOW);
duration = pulseIn(echoPin,
HIGH); distance = duration *
SOUND_SPEED/2;
Serial.print("Distance (cm): ");
Serial.println(distance);
if(distance<100)
Serial.println("ALERT!!"
); delay(1000);
PublishData(distance);
delay(1000); if
(!client.loop())
{ mqttconnect();
} }
delay(1000
); }
void
         PublishData(float
                               dist)
         {mqttconnect();
String payload = "{\"Distance\":";
payload += dist;
payload += ",\"ALERT!!\":""\"Distance less than 100cms\"";
payload += "}";
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c str())) {
Serial.println("Publish ok");
} else {
Serial.println("Publish failed");
} void mgttconnect() {
                                  if
(!client.connected())
Serial.print("Reconnecting client to
");
Serial.println(server);
while (!!!client.connect(clientId, authMethod, token)) {
Serial.print(".");
delay(500);
}
```

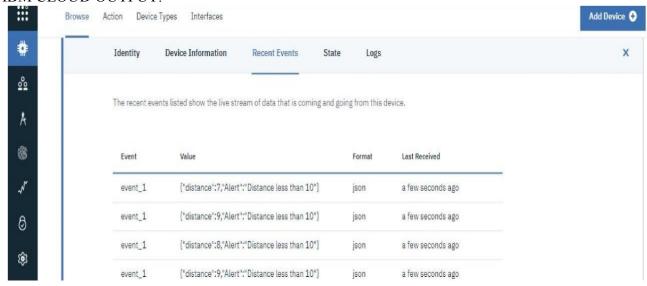
initManagedDevice();

```
Serial.println();
} }
void wificonnect()
Serial.println();
Serial.print("Connecting to ");
WiFi.begin("Wokwi-GUEST", "", 6);
while (WiFi.status() != WL CONNECTED) {delay(500);
Serial.print(".");
Serial.println("");
Serial println("WiFi connected");
Serial.println("IP address: ");
Serial.println(WiFi.localIP());
void initManagedDevice() { if
(client.subscribe(subscribetopic))
{ Serial.println((subscribetopic));
Serial.println("subscribe to cmd OK");
} else {
Serial.println("subscribe to cmd FAILED");
} }
void callback(char*
                        subscribetopic,
                                          byte*
                                                  payload,
                                                             unsigned
payloadLength) {
Serial.print("callback invoked for topic:
"); Serial.println(subscribetopic); for (int
i = 0; i < payloadLength; i++) {
//Serial.print((char)payload[i]); data3 +=
(char)payload[i];
Serial.println("data:
                               data3);
data3="";
}
```

# SCHEMATIC/CIRCUIT DIAGRAM:



# IBM CLOUD OUTPUT:



# WOKWI LINK:

https://wokwi.com/projects/346419220039336530