PROJECT REPORT

SMART WASTE MANAGEMENT SYSTEM FOR METROPOLITAN CITIES

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ABSTRACT

One issue that most cities and municipalities are dealing with currently, is the degradation of environmental cleanliness with reference to waste management. This is a result of improper garbage collection management. Dumping garbage onto the streets and in public areas is a common synopsis found in all developing countries and this mainly ends up affecting the environment and creating several unhygienic conditions. To avoid improper garbage management and to create a hygienic environment, the concept of automation is used in waste management system. Any city being referred to as a "smart city" is because of its orderly and tidy surroundings. But currently, many issues including those related to smart grids, smart environments, and smart living are faced. Today, cities and metropolitan areas' top priority is proper garbage management.

Traditional waste management techniques are too simplistic to create an effective and reliable waste management. The ideology put forward includes hardware and software technologies i.e. connecting Wi-Fi system to the normal dustbin in order to provide free internet facilities to the user for a particular period of time. The technology awards the user for keeping the surrounding clean and thus work hand in hand for the proper waste management in a locality. The smart bin uses multiple technologies - firstly the technology for measuring the amount of trash dumped and secondly the movement of the waste and lastly sending necessary signals and connecting the user to the Wi-Fi system. The proposed system will function on client server model, a cause that will assure clean environment, good health, and pollution free society.

1. INTRODUCTION

1.1 Project Overview

Our waste generation is constantly growing to form a global garbage crisis. Even though we indulge in creating a more sustainable and greener, we still fail to handle our waste generation and management. Combining technology support with a vision of social, economic and environmental sustainability is the best way out of this problem. It is done in the following manner. The smart bin system undergoes a thorough system check and battery level monitoring in order to function efficiently. If the battery level is found to be low, it has to be recharged immediately, else it can proceed to the next step. The threshold level levels of the bin are indicated my multiple sensors attached to bin. If the garbage exceeds the level, then an alert message is sent to the garbage collectors as well as to the municipality or area administration. The area in which garbage is found to overflow is allocated to respective garbage collectors in the form of messages through GSM system. Once the waste bin is emptied, an information update is sent to the municipality and server is updated. This is how the waste from bins can be efficiently handled and managed using technology which in turn keeps the environment clean and healthy.

1.2 Purpose

We amalgamate technology along with waste management in order to effectively create a safe and a hygienic environment. Smart waste management is about using technology and data to create a more efficient waste industry. Based on IoT (Internet of Things) technology, smart waste management aims to optimize resource allocation, reduce running costs, and increase the sustainability of waste services. This makes it possible to plan more efficient routes for the trash collectors who empty the bins, but also lowers the chance of any bin being full for over a week. A good level of coordination exists between the garbage collectors and the information supplied via technology. This makes them well aware of the existing garbage level and instigate them whenever the bins reach the threshold level. They are sent with alert messages so that they can collect the garbage on time without littering the surrounding area. The fill

patterns of specific containers can be identified by historical data and managed accordingly in

the long term. In addition to hardware solutions, mobile applications are used to overcome the challenges in the regular waste management system, such as keeping track of the drivers while they are operating on the field. Thus, smart waste management provides us with the most optimal way of managing the waste in an efficient manner using technology.

2. LITERATURE SURVEY

2.1 Existing problem

Around 80% of waste collections happen at the wrong time. Late waste collections lead to overflowing bins, unsanitary environments, citizen complaints, illegal dumping, and increased cleaning and collection costs. Early waste collections mean unnecessary carbon emissions, more traffic congestion, and higher running costs. The old way of doing waste management is highly inefficient. And in today's ever-technological world, an innovative and data-driven approach is the only way forward. Traditionally, municipalities and waste management companies would operate on a fixed collection route and schedule. This means that waste collection trucks would drive the same collection route and empty every single waste container – even if the waste container did not need emptying. This means high labour and fuel costs – which residents ultimately foot the bill for.

2.2 Reference

SI.	Title	Year	Author	Inference
No				
1.	IOT-Based route Recommendation for an Intelligent Waste Management System	2022	Mohammad Hossein ghahramani	It also maintains a good diversity in a newly generated population. The main drawback of the state of art was that it cannot appropriately model the association among spatial objects,

				consequently find an optimal route.
2.	Smart waste bin Management	2022	Parthasarathi Manickaraja	Uses the Ultrasonic sensor to level the dustbin and also uses the GSM module. Provides an alert message once the level has reached to the authority.
3.	Smart waste management using IOT	2020	Tejashree Kadus	Technology used is a load cell and a Wi-Fi module Segregate the waste in the dustbin and provides and alert message.
4.	Real time solid waste bin monitoring system framework using wireless sensor network	2019	Thiyagapriyadharshini	Smart bin based on a microcontroller based platform Arduino which is interfaced with GSM module. Waste management efficiency and it avoids lumping of wastes.
5.	Smart waste collection system	2018	Muhamad JavedRamzan	Technology based on sensor based collection and uses route algorithm. It identifies the status of waste bin levels along with the location to replace the bin.
6.	Waste management and tracking	2017	B Keerthana	Technology based on ZigBee. Less expensive Lock based System with acknowledgment alert system.

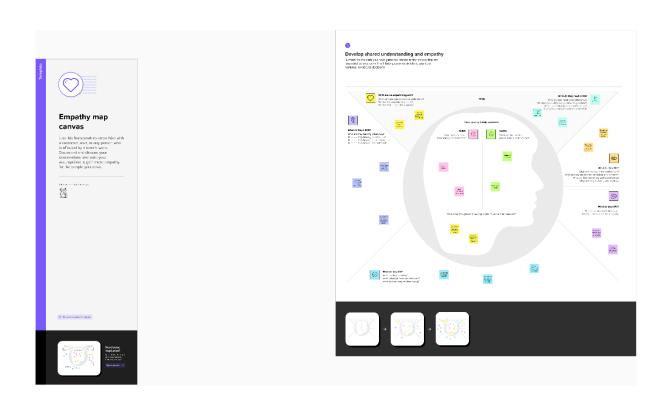
7.	Smart Waste	2016	T. P. Fei	The system is based on
	Management for			Bootstrap platform. This
	Green Environment			system works on the
				waterfall methodology
				which has 4 crucial
				phases: planning and
				analysis, system design,
				system implementation
				and system testing.
				Using this system,
				operators can get the
				information regarding
				collection from trash
				bins. The limitations of
				this approach are that
				the resultant product has
				a short life and
				uniformity is lost after a
				certain period.

2.3 Problem Statement Definition

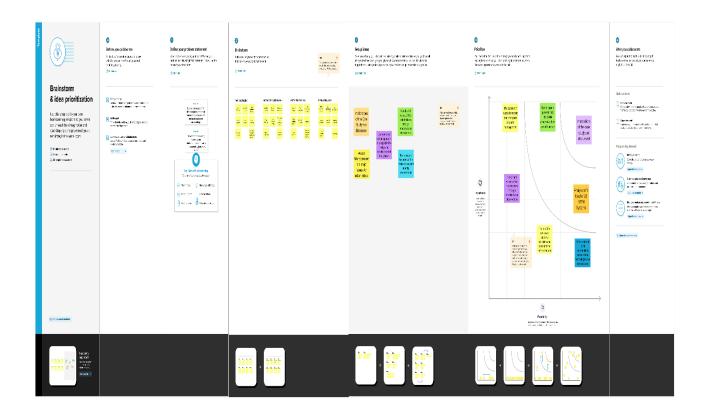
Problem Statement (PS)	I am (Customer)	I'm trying to	But	Because	Which makes me feel
PS-1	Householder	Dispose the vegetable waste and other household wastes.	It increases the land pollution and contaminate ground water.	To keep the surrondings clean and healthy.	Difficult
PS-2	Industrialist	Dispose the chemical wastes and recycle for future use	It contaminates wildlife's habitats and endangers the life of people at large.	To avoid risk for both environment and human health.	Unpleasant

3. IDEATION & PROPOSED SOLUTION

3.1 Empathy map canvas



3.2 IDEATION AND BRAINSTROMING

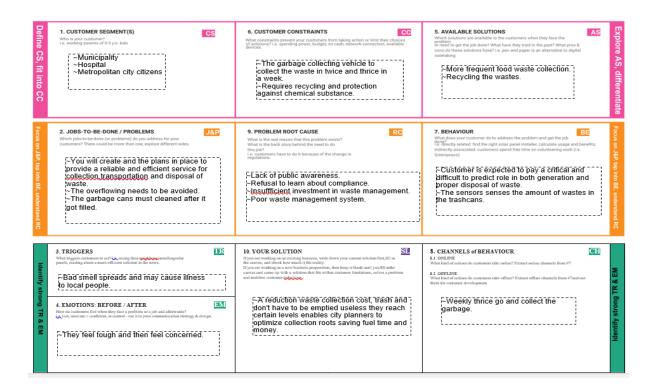


3.3 PROPOSED SOLUTION

S.No.	Parameter	Description
1.	Problem Statement (Problem to be solved)	❖Rubbish and waste can cause air and water pollution.
		Rotting garbage is also known to produce harmful gases mix with the air and cause breathing problem in people.
		❖ Due to improper waste disposal, we may face several problems like unpleasant odor and health problems.
2.	Idea / Solution description	❖ Using sensors when a trash bin is about to fill, the authorities are immediately notified and collection trucks can be scheduled for a picup even before the pre-scheduled time.
		❖ Collect and analyse area-specific

		data on waste volumes for better planning.
3.	Novelty / Uniqueness	❖ Identify potential waste streams.
		Create a waste management- focused community outreach plane.
4.	Social Impact / Customer Satisfaction	❖ Monitoring the amount of waste and periodic collection reduce the environmental damage and improve street sanitation.
		* Raise public awarness of utilizing renewable resources.
5.	Business Model (Revenue Model)	❖ It generates revenue through the provision of various waste management and disposal services.
		* Recycling solutions to residential, commercial, industrial, and municipal clients
6.	Scalability of the Solution	❖ Selects the optimum routes for waste collection trucks.
		Installing more bins fir collecting recyclables like paper, glass, plastic.

3.4 PROBLEM SOLUTION FIT



4. REQUIREMENT ANALYSIS

4.1 Functional Requirement

FR	Functional Requirement	Sub Requirement (Story / Sub-Task)	
No.	(Epic)		
FR-1	Detailed bin inventory	Bins or stands are visible on the map as green,	
		orange, or red circles. You can see bin details	
		in the Dashboard – capacity, waste type, last	
		measurement, GPS location and collection	
		schedule or pick recognition.	
FR-2	Real time bin monitoring	The Dashboard displays which displays all the real-time data on filling levels of bins	
		monitored by smart sensors. Along to the	
		percentage of fill level, based on the previous	
		data, the tool predicts when the bin will	
		become full, one of the functionalities that are	
		not included even in the best waste	
		management software. Sensors recognize picks	
		as well; so you can check when the bin was	
		collected last.	
		With the help of real-time data and predictions,	
		you can eliminate the overflowing bins and	
		stop collecting half empty ones.	
FR-3	Expensive bins	We help you identify bins that drive up your	
		collection costs. The tool calculates a rating for	
		each bin in terms of collection costs.	
		The tool considers the average distance depo-	
		bin discharge in the area. The tool assigns bin a	
		rating (1 -10) and calculates distance from	
		depo-bin discharge.	
FR-4	Adjust bin distribution	Ensure that the most optimal distribution of	
		bins and Identify areas with either dense or	
		sparse bin distribution. Make sure that all trash	
		types are represented within a stand. Based on	
		the previous data, you can adjust bin capacity	
	T11 1 20 1	or location where ever necessary.	
FR-5	Eliminate inefficient	Removing the collection of half-empty bins.	
	picks	By using real time data on fill-levels and pick	
		recognition, we can show you how full the bins	
		can be collected.	

FR-6	Plan waste collection	The tool semi-automates waste collection route	
	routes	planning. Based on current bin fill-levels and	
		predictions of reaching full capacity, you are	
		ready to respond and schedule waste collection.	
		You can compare planned vs. executed routes	
		to identify any inconsistencies.	

4.2 Non-Functional requirements

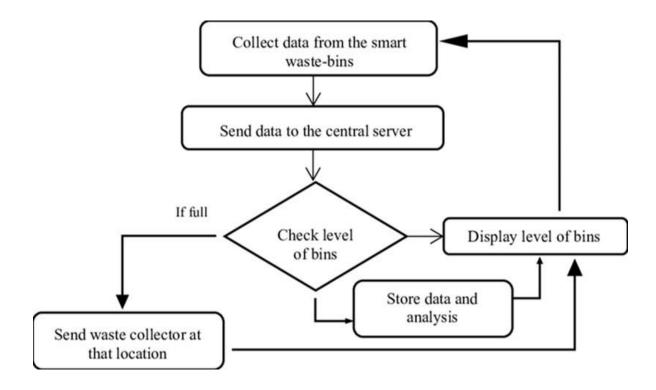
FR No.	Non-Functional Requirement	Description
NFR-1	Usability	IoT device verifies that usability is
INITIX-1	Csability	a special and important perspective
		to analyze user requirements,
		which can further improve the
		design quality. In the design
		process with user experience as the
		core, the analysis of users' product
		_
		usability can indeed help designers
		better understand users' potential
		needs in waste management,
NED 2	S	behavior and experience.
NFR-2	Security	Use a reusable bottles.
		Use reusable grocery bags.
		Purchase wisely and recycle.
		Avoid single use food and
MED 2	D 1: 1 11:4	drink containers.
NFR-3	Reliability	Smart waste management is also
		about creating
		better working conditions for waste
		collectors and drivers. Instead of
		driving the same collection routes
		and servicing empty bins, waste
		collectors will spend their time
		more efficiently, taking care of
3 TED 4	-	bins that need servicing.
NFR-4	Performance	The Smart Sensors use ultrasound
		technology to
		measure the fill levels (along with
		other data) in bins several times a
		day. Using a variety of loT
		networks ((NB - IoT, GPRS), the

		sensors send the data to Sensoneo's Smart Waste Management Software System, a powerful cloud-based platform, for data driven daily operations, available also as a waste management app. Customers are hence provided data-driven decision making, and optimization of waste collection routes, frequencies, and vehicle loads resulting in route reduction by at least 35%.
NFR-5	Availability	By developing & deploying resilient hardware and beautiful software we empower cities, businesses, and countries to manage waste smarter.
NFR-6	Scalability	Using smart bins may reduce the number of bins inside the cities because we monitor the garbage 24/7 more efficiently.

5. PROJECT DESIGN

5.1 Data Flow Diagram

A rapid rise in inhabitants across the globe has led to the inadmissible management of waste in various countries, giving rise to various health issues and environmental pollution. The waste-collecting trucks collect waste just once or twice in seven days. Due to improper waste collection practices, the waste in the dustbin is spread on the streets.



5.2 Technical Architecture

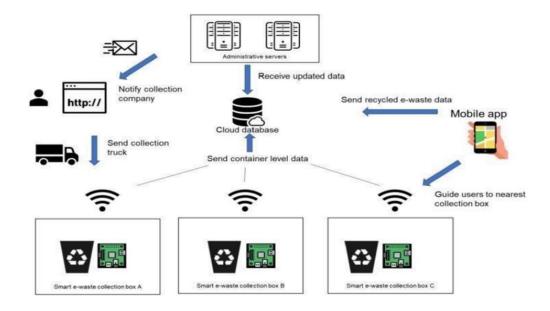


Table-1 : Components & Technologies

S.No	Component	Description	Technology
1.	User Interface	IOT cloud platform /WEB PORTAL	HTML, CSS, NODE RED, JAVASCRIPT/MQTT PROTOCOL
2.	Application Logic-1	The bin waste data's are collected using sensor	Python/Ultrasonic sensor
3.	Application Logic-2	The data which is collected are monitored using IOT	IBM Watson STT Service
4.	Application Logic-3	To Get the location of the garbage	GPS
5.	Database	MySQL is a relational database that is based on a tabular design. NoSQL is non-relational and has a document based design.	MySQL, NoSQL
6.	Cloud Database	Database service on cloud	IBM DB2, IBM Cloud etc
7.	File Storage	File storage requirements	IBM Block Storage, local file system
8.	External API-1	External APIs expose a project's internal resources to outside users or applications	IBM Weather API, etc
9.	External API-2	External API allow you to access third party resources that are available through RESTful web services	Aadhar API, etc
10.	Machine Learning Model	The proper algorithm makes planning good. It will guide the goodness character and which path should be taken and which garbage bin should be collected first	Python IDLE or Anaconda navigator or Jupiter
11.	Infrastructure (Server / Cloud)	Application Deployment on Local System / Cloud	
		Cloud Server Configuration: Cloud deployment is the process of deploying an application through one or more	Cloud server- MySQL

	hosting models-software as a service (SaaS), platform as a service (PaaS) and or infrastructure as a service (laaS) that leverage the cloud	Local server- HTTP
	Local Server Configuration: A local server gives you exclusive access to data and objects in a set of Windows folders called data directories	

Table-2: Application Characteristics:

S.No	Characteristics	Description	Technology
1.	Open-Source	Micro web framework,	Flask
	Frameworks	Written in Python	
2.	Security Implementations	Provides Security rules to	Fire base, fire walls
		allow asses to data	
3.	Scalable Architecture	New features can be added	Node RED
4.	Availability	Web application can be	IBM Watson IOT
		accessed from anywhere.	platform, HTML,CSS,
			JavaScript
5.	Performance	Provides real time data to	Cloudant DB IBM
		web application whichuses	Watson IOTplatform
		cloud platform and alerts	
		garbage collector.	
		All truck drivers can access	
		the application atsame time	

5.3 User Stories

User Type	Requirement (Epic) Number Number Number No Web server login USN-1 As a admin, I have my user name and		User Story / Task	Acceptance criteria	Priority	Release
Admin (who manage web server)			I can manage web account and direct workers.	High	Sprint-1	
Co-admin	Login	USN-2	As a co-admin, I'll manage other monitoring activities like garbage level monitoring, location accuracy, garbage separation and removal of waste within a scheduled time.		High	Sprint-2
Customer (Web user)	User	USN-3	Here comes the customer, he/she will have access to mobile apps or login web pages to view progress of bins and to report if any query found.	He/ she has the right to make a query if any.	High	Sprint-3
Customer Care Executive	Worker	USN-4	The customer care executive, will try to rectify the queries from customers by contacting co-admin. If case of any critical/ emergency situation query can be conveyed to higher authority.	I can attend calls and respond people by rectifying the problem.	High	Sprint-4
par who acc upo		Here, truck driver is a worker who has particular assignments that he has to report when and where the garbage has been picked according to the daily schedule. And should update the happenings in the given website (web page login).	I can update my activities on site when the given task has been completed.	Moderate	Sprint-5	

6. PROJECT PLANNING & SCHEDULING

6.1 Sprint Planning & Estimation

Sprint	Functional Requirement (Epic)	User Story Number	User Story / Task	Story Points	Priority	Team Members	
Sprint-1	Registration	USN-1	As a user, I can register for the application by entering my email, password and confirming my password.	10	High	Ravishankar	
Sprint-1	Login	USN-2	As a user, I will receive confirmation emailonce I have registered for the application.	10	High	Navaneethakr -ishnan	
Sprint-2	Dashboard	USN-4	As a user, I'll control the waste level by monitoring them via real time web portal.	10	High	Mothiprasath	
Sprint-2	Notification	USN-4	As a user, once the bin gets filled, I'll notifytrash truck with location of bin with bin ID.	10	High	Pradeeprajan	
Sprint-3	Dashboard	USN-5	As a user, I'II gather all the waste from the garbage bin and load it onto a truck	10	Medium	Navaneethakr -ishnan	
Sprint-3	Dashboard	USN-6	As a user, I can specify the location to bemonitored and to reach the landfills in optimized routes to save time.	10	Medium	Ravishankar	
Sprint-4	Dashboard	USN-7	As a user, I'll make sure everything is proceeding as planned and without any problems.	20	High	Mothiprasath	

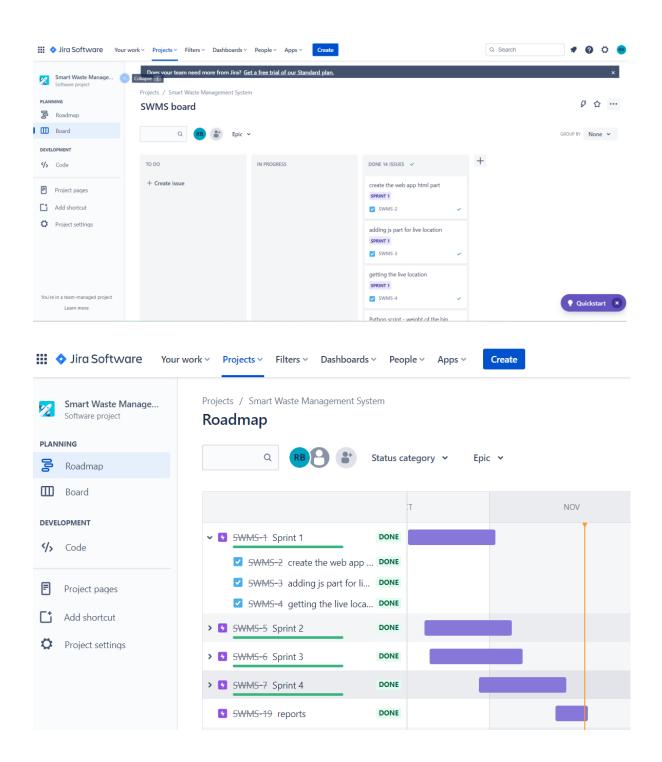
Sprint	Total Story Points	Duration	Sprint Start Date	Sprint End Date (Planned)	Story Points Completed (as on Planned End Date)	Sprint Release Date (Actual)
Sprint-1	20	6 Days	24 Oct 2022	29 Oct 2022	20	29 Oct 2022
Sprint-2	20	6 Days	31 Oct 2022	05 Nov 2022	20	05 Nov 2022
Sprint-3	20	6 Days	07 Nov 2022	12 Nov 2022	20	12 Nov 2022
Sprint-4	20	6 Days	14 Nov 2022	19 Nov 2022	20	19 Nov 2022

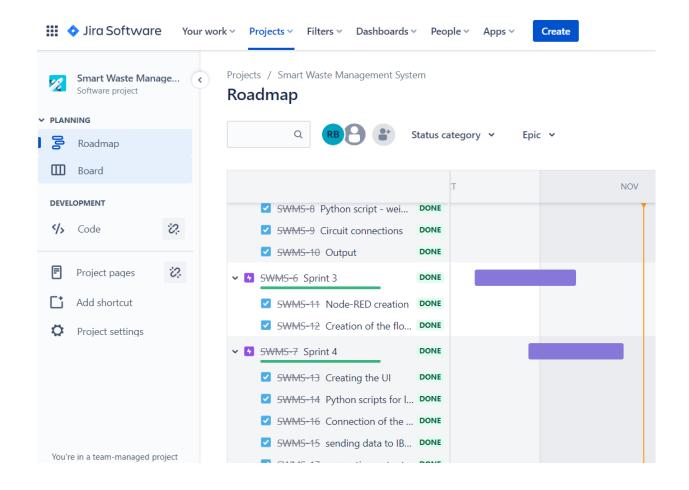
6.2 Sprint Delivery Schedule

Title	Description	Details
Literature Survey & Information Gathering	Literature survey on the selected project & gathering information by referring the, technical papers, research publication etc	28 SEPTEMBER 2022
Prepare Empathy Map	Prepare Empathy Map Canvasto capture the user Pains & Gains, Prepare list of problem Statements.	24 SEPTEMBER 2022
Ideation	List the by organizing the brainstorming session and prioritize the top 3 ideas based on the feasibility & importance.	25 SEPTEMBER 2022
Proposed Solution	Prepare the proposed solution document, which includes the novelty, feasibility of idea, business model, social impact, scalability of solution, etc.	23 SEPTEMBER 2022
Problem Solution Fit	Prepare problem - solution fit Document.	30 SEPTEMBER 2022
Solution Architecture	Prepare solution architecture Document.	28 SEPTEMBER 2022
Customer Journey	Prepare the customer journey maps to understand the user interactions & experiences with the application (entry to exit).	20 OCTOBER 2022

Functional Requirements	Prepare the functional requirement document.	26 OCTOBER 2022		
Data Flow Diagrams	Draw the data flow diagrams and submit for review.	27 OCTOBER 2022		
Technology Architecture	Prepare the technology architecture diagram.	28 OCTOBER 2022		
Prepare Milestone & Activity List	Prepare the milestones & activity list of the project.	04 November 2022		
Project Development - Delivery of Sprint-1, 2, 3 & 4	Develop & submit the developed code by testing it.	10 November 2022		

6.3 Reports from JIRA





7. CODING AND SOLUTIONING

7.1 Feature 1

```
#include <WiFi.h> // library for wifi
#include <PubSubClient.h> // library for MQTT
#include <LiquidCrystal_I2C.h>
#include <mjson.h>
LiquidCrystal_I2C lcd(0x27, 20, 4);
//----- credentials of IBM Accounts -----
#define ORG "9gbe4w" // IBM organisation id
#define DEVICE_TYPE "SWMSMC" // Device type mentioned in ibm watson iot platform
#define DEVICE_ID "ibmproject" // Device ID mentioned in ibm watson iot platform
#define TOKEN "sUNA41tG6-Pq)0rk5X" // Token
//----- customise above values -----
char server[] = ORG ".messaging.internetofthings.ibmcloud.com"; // server name
char publishTopic[] = "iot-2/evt/data/fmt/json"; // topic name and type of event perform and
format in which data to be send
char topic[] = "iot-2/cmd/led/fmt/String"; // cmd Represent type and command is test format of
strings
```

```
char authMethod[] = "use-token-auth"; // authentication method
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID; //Client id
WiFiClient wifiClient; // creating instance for wificlient
PubSubClient client(server, 1883, wifiClient);
#define ECHO_PIN 12
#define TRIG_PIN 13
float dist;
String data3;
bool SealBin = true;
void setup()
Serial.begin(115200);
pinMode(LED_BUILTIN, OUTPUT);
pinMode(TRIG_PIN, OUTPUT);
pinMode(ECHO_PIN, INPUT);
//pir pin
pinMode(34, INPUT);
//ledpins
pinMode(23, OUTPUT);
pinMode(2, OUTPUT);
pinMode(4, OUTPUT);
pinMode(15, OUTPUT);
lcd.init();
lcd.backlight();
lcd.setCursor(1, 0);
lcd.print("");
wifiConnect();
mqttConnect();
float readcmCM()
digitalWrite(TRIG_PIN, LOW);
delayMicroseconds(2);
digitalWrite(TRIG_PIN, HIGH);
delayMicroseconds(10);
digitalWrite(TRIG_PIN, LOW);
int duration = pulseIn(ECHO PIN, HIGH);
return duration * 0.034 / 2;
void loop()
lcd.clear();
```

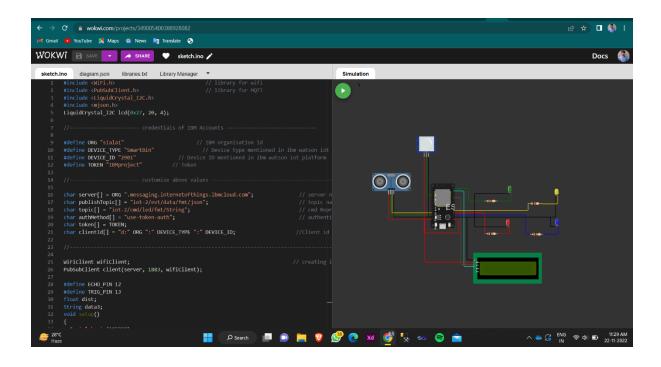
```
publishData();
delay(500);
if (!client.loop())
mqttConnect(); // function call to connect to IBM
}
/* -----*/
void wifiConnect()
Serial.print("Connecting to ");
Serial.print("Wifi");
WiFi.begin("Wokwi-GUEST", "", 6);
while (WiFi.status() != WL_CONNECTED)
delay(500);
Serial.print(".");
Serial.print("WiFi connected, IP address: ");
Serial.println(WiFi.localIP());
void mqttConnect()
if (!client.connected())
Serial.print("Reconnecting MQTT client to ");
Serial.println(server);
while (!client.connect(clientId, authMethod, token))
Serial.print(".");
delay(500);
initManagedDevice();
Serial.println();
}
void initManagedDevice()
if (client.subscribe(topic))
Serial.println("IBM subscribe to cmd OK");
else
Serial.println("subscribe to cmd FAILED");
```

```
}
void publishData()
float cm = readcmCM();
if(digitalRead(34)) //pir motion detection
Serial.println("Motion Detected");
Serial.println("Lid Opened");
digitalWrite(15, HIGH);
if(digitalRead(34)== true)
if(cm <= 100) //Bin level detection
digitalWrite(2, HIGH);
Serial.println("High Alert!!!,Trash bin is about to be full");
Serial.println("Lid Closed");
lcd.print("Full! Don't use");
delay(2000);
lcd.clear();
digitalWrite(4, LOW);
digitalWrite(23, LOW);
else if(cm > 100 \&\& cm < 180)
digitalWrite(4, HIGH);
Serial.println("Warning!!, Trash is about to cross 50% of bin level");
digitalWrite(2, LOW);
digitalWrite(23, LOW);
else if(cm > 180)
digitalWrite(23, HIGH);
Serial.println("Bin is available");
digitalWrite(2,LOW);
digitalWrite(4, LOW);
delay(10000);
Serial.println("Lid Closed");
else
Serial.println("No motion detected");
digitalWrite(2, LOW);
digitalWrite(15, LOW);
digitalWrite(4, LOW);
digitalWrite(23, LOW);
```

```
}
else
digitalWrite(15, LOW);
if(cm \le 100)
digitalWrite(21,HIGH);
String payload = "{\"High_Alert\":";
payload += cm;
payload += " }";
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c_str())) // if data is uploaded to cloud
successfully, prints publish ok else prints publish failed
Serial.println("Publish OK");
else if(cm \le 180)
digitalWrite(22,HIGH);
String payload = "{\"Warning\":";
payload += cm;
payload += " }";
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if(client.publish(publishTopic, (char*) payload.c_str()))
Serial.println("Publish OK");
}
Else
Serial.println("Publish FAILED");
else if(cm > 180)
digitalWrite(23,HIGH);
String payload = "{";
payload += cm;
payload += " }";
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c_str())) // if data is uploaded to cloud
```

```
successfully, prints publish ok else prints publish failed
Serial.println("Publish OK");
float inches = (cm / 2.54); //print on lcd
lcd.setCursor(0,0);
lcd.print("Inches");
lcd.setCursor(4,0);
lcd.setCursor(12,0);
lcd.print("cm");
lcd.setCursor(1,1);
lcd.print(inches, 1);
lcd.setCursor(11,1);
lcd.print(cm, 1);
lcd.setCursor(14,1);
delay(1000);
lcd.clear();
//handles commands from user side
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
Serial.print("callback invoked for topic: ");
Serial.println(subscribetopic);
for (int i = 0; i < payloadLength; i++) {
data3 += (char)payload[i];
Serial.println("data: "+ data3);
const char s =(char) data3.c_str();
double pincode = 0;
const char *buf;
int len;
if (mjson_find(s, strlen(s), "$.command", &buf, &len)) // And print it
String command(buf,len);
if(command=="\"SealBin\"")
SealBin = true;
}
data3="";
```

7.2 Feature 2



7.3 Feature 3
WEBPAGE CODE:
html
<html lang="en"></html>
<head></head>
<title>Smart Waste Management System For Metropolitan Cities</title>
<meta charset="utf-8"/>
<meta content="width=device-width, initial-scale=1" name="viewport"/>
</td
======================================
=====================>
<pre><link href="/static/images/icons/favicon.ico" rel="icon" type="image/png"/></pre>
</td

=======================================	
<pre>k</pre> rel="stylesheet" href="/static/vendor/bootstrap/css/bootstrap.min.css">	type="text/css"
</td <td></td>	
	=======================================
======================================	onts/font-awesome-
4.7.0/css/font-awesome.min.css"> </td <td></td>	
	=========
<pre>====================================</pre>	s/Linearicons-Free-
</td <td></td>	
====================>	
rel="stylesheet" href="/static/vendor/animate/animate.css">	type="text/css"
========= <link href='hamburgers/hamburgers.min.css"' rel="stylesheet" type="text/css"/>	="/static/vendor/css-
========== >	
rel="stylesheet"href="/static/vendor/animsition/css/animsition.min.css">	type="text/css"
</td <td></td>	
	=======================================
===================>	

```
link
                          rel="stylesheet"
                                                               type="text/css"
href="/static/vendor/select2/select2.min.css">
                                                               type="text/css"
link
                          rel="stylesheet"
href="/static/vendor/daterangepicker/daterangepicker.css">
<link href="{{ url_for('static', path='/css/main.css') }}"</pre>
rel="stylesheet">
<link href="{{ url_for('static', path='/css/util.css') }}"</pre>
rel="stylesheet">
<!-- ==========>
</head>
<body>
<div class="limiter">
<div
         class="container-login100"
                                         style="background-image:
                                                                        url({{
url_for('static', path='/images/bg1.jpg') }});">
<div class="wrap-login100 p-l-110 p-r-110 p-t-62 p-b-33">
<form class="login100-form validate-form flex-sb flex-w">
<span class="login100-form-title p-b-53"> Sign In With
</span>
<a href="#" class="btn-face m-b-20">
<i class="fa fa-facebook-official"></i> Facebook
</a>
<a href="#" class="btn-google m-b-20">
<img src="static/icons/icon-google.png" alt="GOOGLE"> Google
</a>
<div class="p-t-31 p-b-9">
<span class="txt1"> Username
</span>
</div>
```

```
<div class="wrap-input100 validate-input" data-validate = "Username is</pre>
required">
<input class="input100" type="text" name="username" >
<span class="focus-input100"></span>
</div>
<div class="p-t-13 p-b-9">
<span class="txt1"> Password
</span>
<a href="#" class="txt2 bo1 m-1-5"> Forgot?
</a>
</div>
<div class="wrap-input100 validate-input" data-validate = "Password is</pre>
required">
<input class="input100" type="password" name="pass" >
<span class="focus-input100"></span>
</div>
<div class="container-login100-form-btn m-t-17">
<br/>
<br/>
dutton class="login100-form-btn"> Login
</button>
</div>
<div class="w-full text-center p-t-55">
<span class="txt2"> Not a member?
</span>
<a href="#" class="txt2 bo1"> Sign up now
</a>
</div>
</form>
</div>
```

<div id="dropDownSelect1"></div>
</td
============================>
<pre><script src="/static/vendor/jquery/jquery-3.2.1.min.js"></script></pre>
</td
===========================>
<pre><script src="/static/vendor/animsition/js/animsition.min.js"></script></pre>
</td
=======================================
=====================>
<pre><script src="/static/vendor/bootstrap/js/popper.js"></script></pre>
<pre><script src="/static/vendor/bootstrap/js/bootstrap.min.js"></script></pre>
</td
=========================>> ***********
<pre><script src="/static/vendor/select2/select2.min.js"></script></pre>
</td
=======================================
===========================>
<pre><script src="/static/vendor/daterangepicker/moment.min.js"></script></pre>
<pre><script src="/static/vendor/daterangepicker/daterangepicker.js"></script></pre>
</td

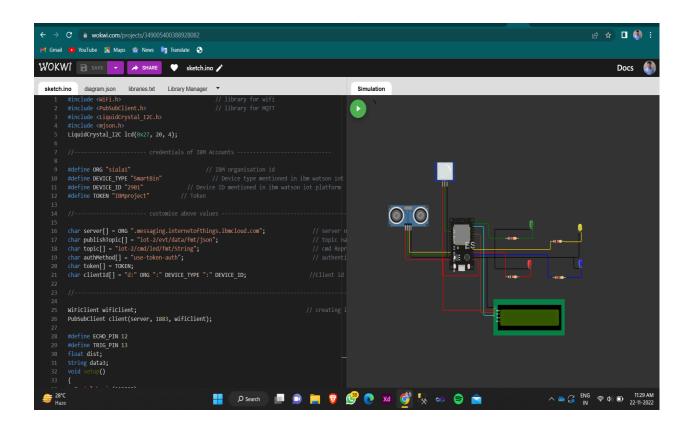
======================================
===============>
<pre><script src="/static/vendor/countdowntime/countdowntime.js"></script></pre>
</th
==============>
<pre><script src="/static/js/main.js"></script></pre>

WORKING MODEL



8. TESTING

8.1 TEST CASES



Component	Test Case Scenario	Pre-Requisite	Availability	Test Condition	Expected Result	Actual Result	Status	Comments	Accessed B
Ultrasonic Sensor	When Bin is empty	Ultrasoncic sensor PIR Motion Sensor Garbage Bins	Bin is accessible to users	Bin Level == 0	Displays Bin level and space left	Working as expected	Pass		User
Ultrasonic Sensor	When bin level is below 50 %	Ultrasoncic sensor , PIR Motion Sensor , Garbage Bins	Bin is accessible to users	Bin Level < 50	Displays Bin level and space left	Working as expected	Pass		User
Ultrasonic Sensor	When bin level is above 50	Motion sensor,	Bin is accessible to users and the admin gets warning about the bin level	Bin Level > 50	Displays Bin level and space left	Working as expected	Pass		User
Ultrasonic Sensor	When bin level is below 75 %	Motion sensor,	Bin is accessible to users and the admin gets warning about the bin level	Bin Level < 75	Displays Bin level and space left	Working as expected	Pass		User
Ultrasonic Sensor	When bin level is above 75 %	Motion sensor , PIR Motion sensor , Garbage Bins	Bin is not accessible to the users, the admin recieves High alert and seals the the bin to avoid overflow.	Bin Level > 75	Displays Bin is FULL and Seals the bin.	Working as expected	Pass	The system starts to sense the level once the Bin is emptied partially or fully	User/Admir

8.2 USER ACCEPTANCE TESTING

1. Purpose of Document

The purpose of this document is to briefly explain the test coverage and open issues of the Smart Waste Management System project at the time of the release to User Acceptance Testing (UAT).

2. Defect Analysis

This report shows the number of resolved or closed bugs at each severity level, and how they were resolved.

Resolution	Severity 1	Severity 2	Severity 3	Severity 4	Subtotal
By Design	10	4	3	3	20
Duplicate	1	0	3	0	4
External	2	3	0	1	6
Fixed	11	2	4	20	37
Not Reproduced	0	0	1	0	1
Skipped	0	0	1	1	2
Won't Fix	0	5	2	1	8
Totals	24	14	13	26	78

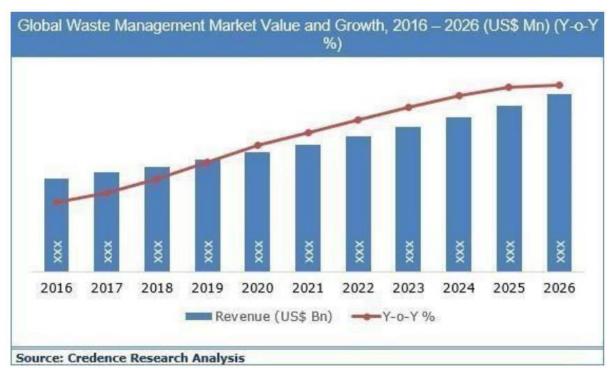
3. TEST CASE ANALYSIS

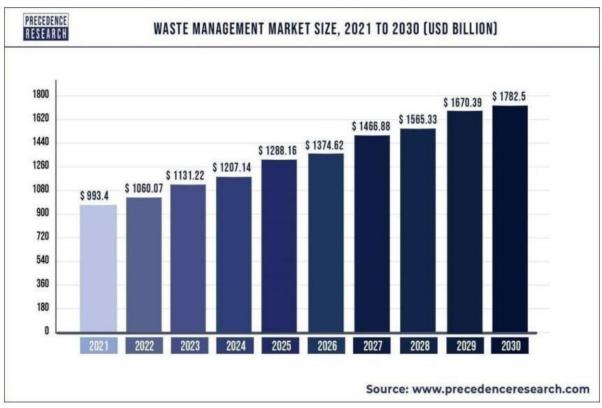
This report shows the number of test cases that have passed, failed and untested.

Section	Total Cases	Not Tested	Fail	Pass
Print Engine	7	0	0	7
Client Application	51	0	0	51

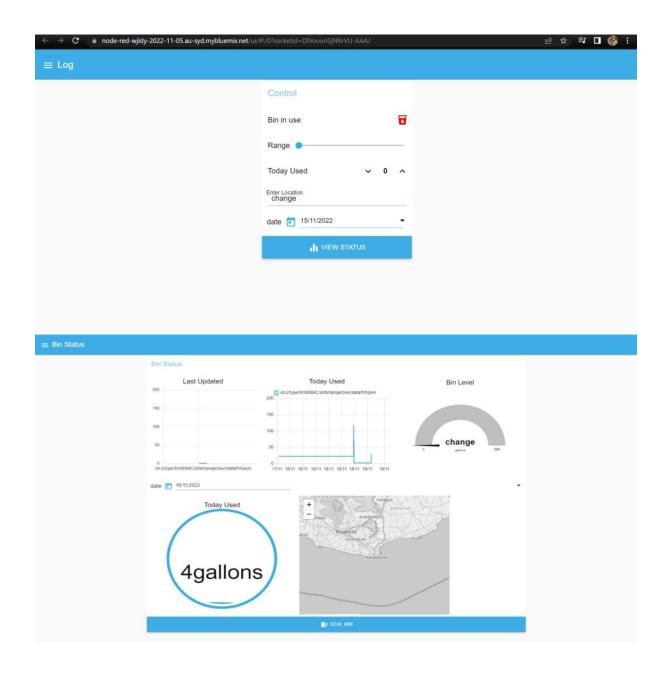
9. RESULTS

9.1 PERFORMANCE METRICS





9.2 ADMIN WEB UI



10. ADVANTAGES & DISADVANTAGES

Advantages:

- People can easily identify the location of the dustbins.
- People can also check for the level of the bin that is being filled.
- Monkeys and other animals would not disturb as we have placed appropriate sensors.
- Reduction in Collection Cost.
- No Missed Pickups
- Reduced Overflows
- Waste Generation Analysis
- CO2 Emission Reduction

Disadvantages:

- Accuracy may be differ due to some unavoidable conditions
- Not at all the features that are impact the production be taken
- System requires a greater number of waste bins for separate waste collection as per population in the city.
- This results in high initial cost due to expensive smart dustbins compared to other methods.
- Sensor nodes used in the dustbins have limited memory size.

11. CONCLUSION

Improper disposal and improper maintenance of domestic waste create issues in public health and environment pollution thus this paper attempts to provide practical solution towards managing the waste collaborating it with the use of IOT by using the smart waste management system, we can manage waste properly we are also able to sort the Bio-degradable and non-Biodegradable waste properly which reduces the pollution in the environment. Various waste management initiatives taken for human well-being and to improve the TWM practices were broadly discussed in this chapter. The parameters that influence the technology and economic aspects of waste management were also discussed clearly. Different types of barriers in TWM, such as economic hitches, political

issues, legislative disputes, informative and managerial as well as solutions and success factors for implementing an effective management of toxic organic waste within a globular context, were also discussed giving some real examples. The effect of urbanization on the environmental degradation and economic growth was also discussed. The proposed system will help to overcome all the serious issues related to waste and keep the environment clean.

12. FUTURE WORK

Based on the real-time and historical data collected and stored in the cloud waste collection schedules and routes can be optimized. Predictive analytics could be used to make decisions ahead of time and offers insight into waste bin locations. Graph theory optimization algorithms can be used to manage waste collection strategies dynamically and efficiently. Every day, the workers can receive the newly calculated routes in their navigation devices. The system can be designed to learn from experience and to make decisions not only on the daily waste level status but also on future state forecast, traffic congestion, balanced cost-efficiency functions, and other affecting factors that a priori humans cannot foresee.

Garbage collectors could access the application on their mobile phone/tablets using the internet. Real-time GPS assistance can be used to direct them to the pre-decided route. As they go collecting the garbage from the containers, the management is also aware of the progress as the vehicle, as well as the garbage containers, are traced in real-time. The management staff gets their own personalized administration panel over a computer/tablet which gives them a bird eye view over the entire operations.

An alternative solution using image processing and camera as a passive

sensor could be used. But, the cost of those image processing cameras is higher as compared to the ultrasonic sensors, which leads to high solution implementation cost.

13. APPENDIX

13.1 Source Code

```
#include <WiFi.h> // library for wifi
#include <PubSubClient.h> // library for MQTT
#include <LiquidCrystal_I2C.h>
#include <mjson.h>
LiquidCrystal I2C lcd(0x27, 20, 4);
//----- credentials of IBM Accounts -----
#define ORG "9gbe4w" // IBM organisation id
#define DEVICE_TYPE "SWMSMC" // Device type mentioned in ibm watson iot platform
#define DEVICE_ID "ibmproject" // Device ID mentioned in ibm watson iot platform
#define TOKEN "sUNA41tG6-Pq)0rk5X" // Token
//----- customise above values -----
char server[] = ORG ".messaging.internetofthings.ibmcloud.com"; // server name
char publishTopic[] = "iot-2/evt/data/fmt/json"; // topic name and type of event perform and
format in which data to be send
char topic[] = "iot-2/cmd/led/fmt/String"; // cmd Represent type and command is test format of
char authMethod[] = "use-token-auth"; // authentication method
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID; //Client id
WiFiClient wifiClient; // creating instance for wificlient
PubSubClient client(server, 1883, wifiClient);
#define ECHO_PIN 12
#define TRIG PIN 13
float dist;
String data3;
bool SealBin = true;
void setup()
Serial.begin(115200);
pinMode(LED_BUILTIN, OUTPUT);
pinMode(TRIG_PIN, OUTPUT);
pinMode(ECHO_PIN, INPUT);
//pir pin
pinMode(34, INPUT);
```

```
//ledpins
pinMode(23, OUTPUT);
pinMode(2, OUTPUT);
pinMode(4, OUTPUT);
pinMode(15, OUTPUT);
lcd.init();
lcd.backlight();
lcd.setCursor(1, 0);
lcd.print("");
wifiConnect();
mqttConnect();
float readcmCM()
digitalWrite(TRIG_PIN, LOW);
delayMicroseconds(2);
digitalWrite(TRIG_PIN, HIGH);
delayMicroseconds(10);
digitalWrite(TRIG_PIN, LOW);
int duration = pulseIn(ECHO_PIN, HIGH);
return duration * 0.034 / 2;
void loop()
lcd.clear();
publishData();
delay(500);
if (!client.loop())
mqttConnect(); // function call to connect to IBM
}
/* -----*/
void wifiConnect()
Serial.print("Connecting to ");
Serial.print("Wifi");
WiFi.begin("Wokwi-GUEST", "", 6);
while (WiFi.status() != WL_CONNECTED)
delay(500);
Serial.print(".");
```

```
Serial.print("WiFi connected, IP address: ");
Serial.println(WiFi.localIP());
void mqttConnect()
if (!client.connected())
Serial.print("Reconnecting MQTT client to ");
Serial.println(server);
while (!client.connect(clientId, authMethod, token))
Serial.print(".");
delay(500);
initManagedDevice();
Serial.println();
void initManagedDevice()
if (client.subscribe(topic))
Serial.println("IBM subscribe to cmd OK");
else
Serial.println("subscribe to cmd FAILED");
void publishData()
float cm = readcmCM();
if(digitalRead(34)) //pir motion detection
Serial.println("Motion Detected");
Serial.println("Lid Opened");
digitalWrite(15, HIGH);
if(digitalRead(34)== true)
if(cm <= 100) //Bin level detection
digitalWrite(2, HIGH);
Serial.println("High Alert!!!,Trash bin is about to be full");
Serial.println("Lid Closed");
lcd.print("Full! Don't use");
delay(2000);
lcd.clear();
```

```
digitalWrite(4, LOW);
digitalWrite(23, LOW);
else if(cm > 100 \&\& cm < 180)
digitalWrite(4, HIGH);
Serial.println("Warning!!,Trash is about to cross 50% of bin level");
digitalWrite(2, LOW);
digitalWrite(23, LOW);
else if(cm > 180)
digitalWrite(23, HIGH);
Serial.println("Bin is available");
digitalWrite(2,LOW);
digitalWrite(4, LOW);
delay(10000);
Serial.println("Lid Closed");
else
Serial.println("No motion detected");
digitalWrite(2, LOW);
digitalWrite(15, LOW);
digitalWrite(4, LOW);
digitalWrite(23, LOW);
}
else
digitalWrite(15, LOW);
if(cm \le 100)
digitalWrite(21,HIGH);
String payload = "{\"High_Alert\":";
payload += cm;
payload += " }";
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c_str())) // if data is uploaded to cloud
successfully, prints publish ok else prints publish failed
Serial.println("Publish OK");
}
```

```
else if(cm \le 180)
digitalWrite(22,HIGH);
String payload = "{\"Warning\":";
payload += cm;
payload += " }";
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if(client.publish(publishTopic, (char*) payload.c_str()))
Serial.println("Publish OK");
Else
Serial.println("Publish FAILED");
}
else if(cm > 180)
digitalWrite(23,HIGH);
String payload = "{";
payload += cm;
payload += " }";
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c_str())) // if data is uploaded to cloud
successfully, prints publish ok else prints publish failed
Serial.println("Publish OK");
float inches = (cm / 2.54); //print on lcd
lcd.setCursor(0,0);
lcd.print("Inches");
lcd.setCursor(4,0);
lcd.setCursor(12,0);
lcd.print("cm");
lcd.setCursor(1,1);
lcd.print(inches, 1);
lcd.setCursor(11,1);
lcd.print(cm, 1);
lcd.setCursor(14,1);
delay(1000);
lcd.clear();
//handles commands from user side
```

```
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
{
    Serial.print("callback invoked for topic: ");
    Serial.println(subscribetopic);
    for (int i = 0; i < payloadLength; i++) {
        data3 += (char)payload[i];
    }
    Serial.println("data: "+ data3);
    const char s = (char) data3.c_str();
    double pincode = 0;
    const char *buf;
    int len;
    if (mjson_find(s, strlen(s), "$.command", &buf, &len)) // And print it
    {
        String command(buf,len);
    if(command=="\"SealBin\"")
        {
            SealBin = true;
        }
        }
        data3="";
    }
}</pre>
```

GITHUB LINK - https://github.com/IBM-EPBL/IBM-Project-44690-1660726241#ibm-project-44690-1660726241

WOKWI LINK - https://wokwi.com/projects/349005400388928082