#### **Assignment -4**

Assignment Date	25 October 2022
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# **Question-1:**

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cm send "alert" to ibm cloud and display in device recent events.

#### Code:

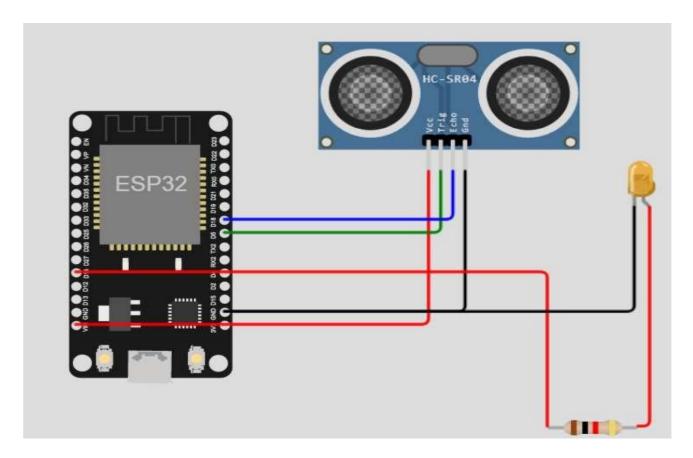
```
#include <WiFi.h> #include
<PubSubClient.h>WiFiClient
wifiClient; String data3;
#define ORG ""
#define DEVICE_TYPE "Distance" #define
DEVICE_ID "Ultrasonic" #define TOKEN
"WD6Mb(-d2F+X0xWqnB"#define speed
0.034
#define led 14
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";char publishTopic[]
= "iot-2/evt/event2/fmt/json";
char topic[] = "iot-2/cmd/home/fmt/String";char
authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);
const int trigpin=5; const int
echopin=18;String
command; <a href="String data="";</a>
long duration;float
dist;
void setup()
  Serial.begin(115200);
  pinMode(led, OUTPUT);
  pinMode(trigpin, OUTPUT);
  pinMode(echopin, INPUT);
```

```
wifiConnect();
  mqttConnect();
}
void loop() {
  bool is Nearby = dist < 100;
  digitalWrite(led, isNearby);
  publishData();
  delay(500);
  if (!client.loop()) {
     mqttConnect();
  }
}
void wifiConnect() {
  Serial.print("Connecting to "); Serial.print("Wifi");
  WiFi.begin("Wokwi-GUEST", "", 6);
  while (WiFi.status() != WL_CONNECTED) {
     delay(500);
     Serial.print(".");
  }
  Serial.print("WiFi connected, IP address: ");
Serial.println(WiFi.localIP());
}
void mqttConnect() {
  if (!client.connected()) {
     Serial.print("Reconnecting MQTT client to "); Serial.println(server); while
     (!client.connect(clientId, authMethod, token)) {
        Serial.print(".");
        delay(500);
     }
     initManagedDevice();
     Serial.println();
  }
}
void initManagedDevice() {
  if (client.subscribe(topic)) {
     // Serial.println(client.subscribe(topic));
     Serial.println("IBM subscribe to cmd OK");
  } else {
     Serial.println("subscribe to cmd FAILED");
  }
void publishData()
```

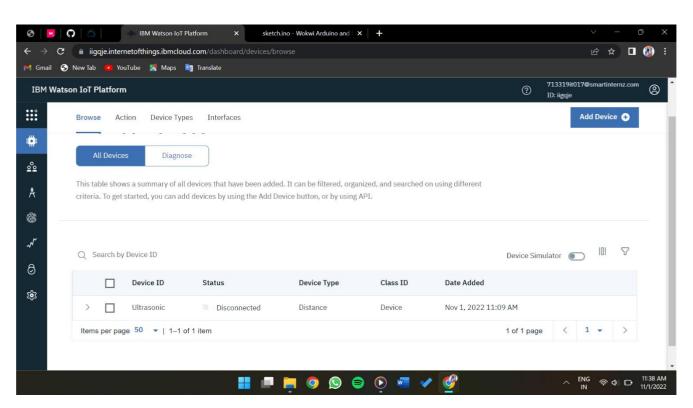
```
digitalWrite(trigpin,LOW);
digitalWrite(trigpin,HIGH);
delayMicroseconds(10);
digitalWrite(trigpin,LOW);
duration=pulseIn(echopin,HIGH);
dist=duration*speed/2; if(dist<100){
  String payload = "{\"Alert!! Alert!! Distance\":";payload += dist;
  payload += "}";
  Serial.print("\n"); Serial.print("Sending
  payload: ");Serial.println(payload);
  if (client.publish(publishTopic, (char*) payload.c_str())) {
     Serial.println("Publish OK");
  }
}
  if(dist>100){
  String payload = "{\"Distance\":";payload +=
  payload += "}";
  Serial.print("\n"); Serial.print("Sending
  payload: ");Serial.println(payload);
   if(client.publish(publishTopic, (char*) payload.c_str())) {
     Serial.println("Publish OK");
  }else {
     Serial.println("Publish FAILED");
  }
}
}
```

{

### **Connections:**

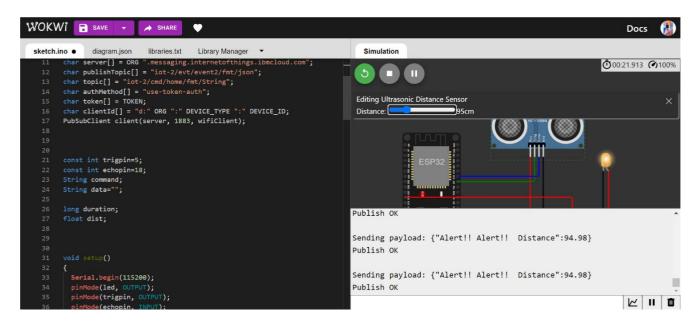


## **WOKWI AND IBM CLOUD CONNECTED:**

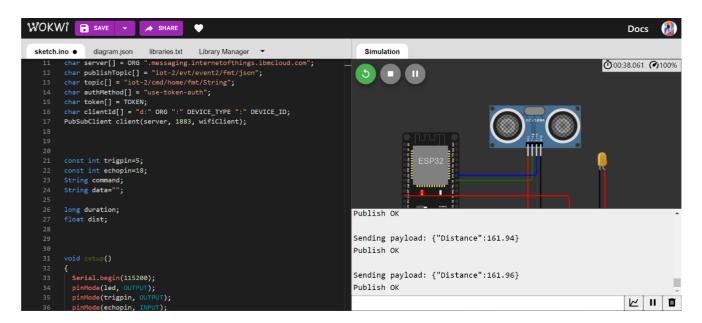


#### **OUTPUT:**

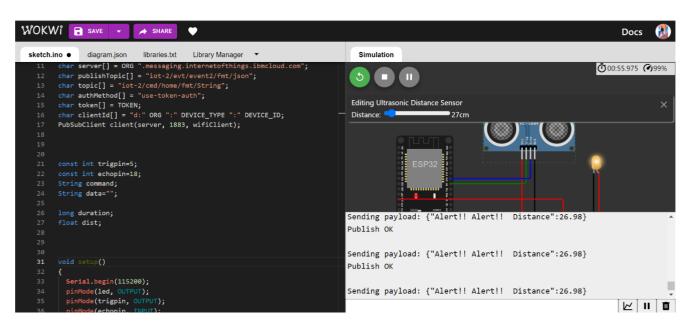
 Distance = 95 cm Status = Alert Message



2. Distance = 162 cmStatus = Normal



3. Distance = 27 cm Status = Alert Message



Reference link = https://wokwi.com/projects/347107058566300242