Assignment -4

Assignment Date	25 October 2022
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Question-1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cm send "alert" to ibm cloud and display in device recent events.

Code:

long duration;

```
#include <WiFi.h>
#include
<PubSubClient.h>
WiFiClient wifiClient;
String data3;
#define ORG ""
#define DEVICE_TYPE
"Distance" #define DEVICE ID
"Ultrasonic" #define TOKEN
"WD6Mb(-d2F+X0xWqnB"
#define speed 0.034
#define led 14
char server[] = ORG
".messaging.internetofthings.ibmcloud.com";char
publishTopic[] = "iot-2/evt/event2/fmt/json";
char topic[] = "iot-2/cmd/home/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);
const int trigpin=5;
const int echopin=18;
String command;
String data="";
```

```
roid setup()
{
Serial.begin(115200);
pinMode(led, OUTPUT);
pinMode(trigpin,
OUTPUT);
pinMode(echopin,
INPUT);
```

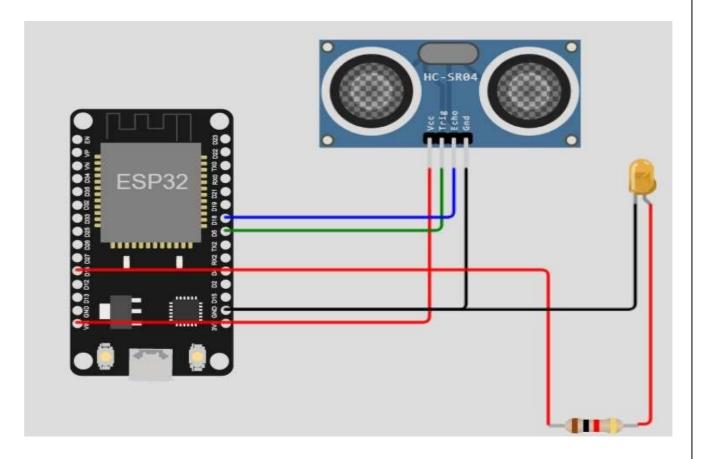
```
wifiConnect()
 mqttConnect()
void loop() {
 bool is Nearby = dist < 100;
  digitalWrite(led, isNearby);
  publishData();
  delay(500);
 if (!client.loop()) {
    mqttConnect();
}
void wifiConnect() {
  Serial.print("Connecting to "); Serial.print("Wifi");
  WiFi.begin("Wokwi-GUEST", "", 6);
  while (WiFi.status() !=
    WL_CONNECTED) {delay(500);
   Serial.print(".");
  Serial.print("WiFi connected, IP address: ");
Serial.println(WiFi.localIP());
void mqttConnect() {
  if (!client.connected()) {
   Serial.print("Reconnecting MQTT client to "); Serial.println(server);
    while (!client.connect(clientId, authMethod, token)) {
      Serial.print(".");
      delay(500);
   initManagedDevice();
   Serial.println();
}
```

void initManagedDevice() {

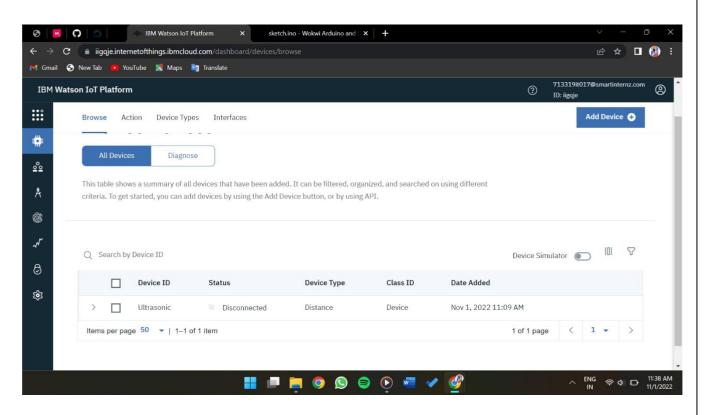
```
if (client.subscribe(topic)) {
    // Serial.println(client.subscribe(topic));
    Serial.println("IBM subscribe to cmd OK");
} else {
    Serial.println("subscribe to cmd FAILED");
}
void publishData()
```

```
{
 digitalWrite(trigpin,LOW);
 digitalWrite(trigpin,HIGH);
 delayMicroseconds(10);
 digitalWrite(trigpin,LOW);
 duration=pulseIn(echopin,HIGH
 );dist=duration*speed/2;
 if(dist<100){
   String payload = "{\"Alert!! Alert!! Distance\":";
   payload += dist;
   payload += "}";
   Serial.print("\n");
   Serial.print("Sending payload: ");
   Serial.println(payload);
   if (client.publish(publishTopic, (char*) payload.c_str())) {
     Serial.println("Publish OK");
    }
   if(dist>100){
   String payload = "{\"Distance\":";
   payload += dist;
   payload += "}";
   Serial.print("\n");
   Serial.print("Sending payload: ");
   Serial.println(payload);
    if(client.publish(publishTopic, (char*) payload.c_str())) {
     Serial.println("Publish OK");
    }else {
     Serial.println("Publish FAILED");
    }
```

Connections:

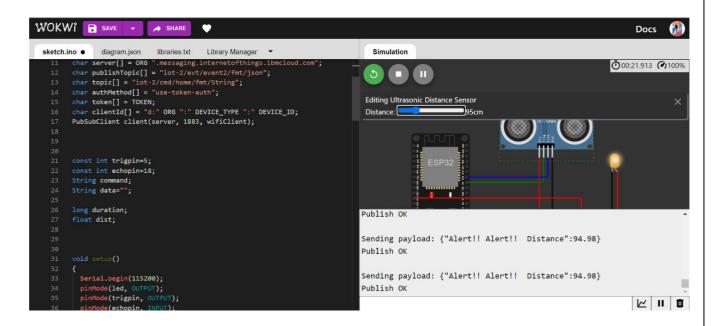


WOKWI AND IBM CLOUD CONNECTED:



OUTPUT:

Distance = 95 cm
 Status = Alert
 Message



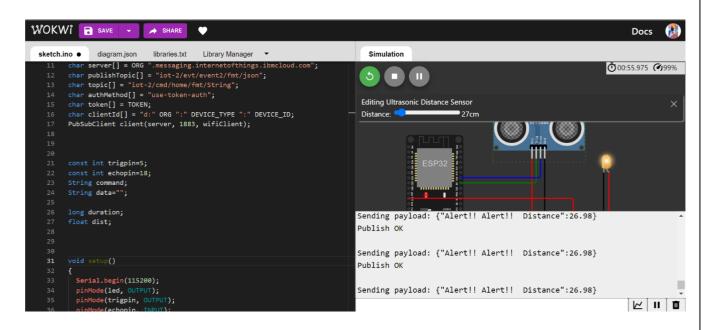
2. Distance = 162 cmStatus = Normal

```
WOKWI 🖥 SAVE 🔻

→ SHARE

                                                                                                                                                                                                               Docs
   sketch.ino ● diagram.json libraries.txt Library Manager ▼
                                                                                                                    Simulation
           char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/event2/fmt/json";
char topic[] = "iot-2/cmd/home/fmt/String";
char authMethod[] = "use-token-auth";
                                                                                                                                                                                                      Ō00:38.061 ⊘100%
           char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
            const int trigpin=5;
const int echopin=18;
            String command;
String data="";
            long duration;
float dist;
                                                                                                                 Publish OK
                                                                                                                 Sending payload: {"Distance":161.94}
                                                                                                                 Publish OK
                                                                                                                 Sending payload: {"Distance":161.96}
               Serial.begin(115200);
              pinMode(led, OUTPUT);
pinMode(trigpin, OUTPUT);
```

3. Distance = 27 cm Status = Alert Message



Reference link = https://wokwi.com/projects/347107058566300242

