

<b>Team ID</b>	<b>PNT2022TMID19620</b>
<b>Project Name</b>	<b>Project –Smart Farming Using IOT</b>
<b>Reg No</b>	<b>722819106304</b>
<b>Name</b>	<b>Kamaleswaran N</b>

Code:

```
#include "Ultrasonic.h" Ultrasonic
ultrasonic(12, 13); int distance;

void setup() {
  Serial.begin(9600);
}

void loop() {
  // Pass INC as a parameter to get the distance in inches
  distance = ultrasonic.read(CM);
  Serial.print("Distance in CM: ");
  Serial.println(distance);
  if (distance < 100)
    Serial.print("alert");
  Serial.println();
  delay(1000);
}
```

Output:

The screenshot displays the Wokwi IDE interface. On the left, the 'sketch.ino' file is open, showing the following code:

```
1 #include "Ultrasonic.h"
2 Ultrasonic ultrasonic(12, 13);
3 int distance;
4
5 void setup() {
6   Serial.begin(9600);
7 }
8
9 void loop() {
10  // Pass INC as a parameter to get the distance in inches
11
12  distance = ultrasonic.read(CM);
13
14  Serial.print("Distance in CM: ");
15  Serial.println(distance);
16  if (distance < 100)
17    Serial.print("alert");
18  Serial.println();
19  delay(1000);
20 }
21
```

On the right, the 'Simulation' tab is active, showing a virtual Arduino Uno board with an ultrasonic sensor module connected. Below the simulation, the serial output is displayed:

```
Distance in CM: 30
alert
Distance in CM: 113
Distance in CM: 113
Distance in CM: 113
```

The simulation status bar at the top right indicates a runtime of 00:28.766 and 56% battery level.