

Assignment -4

Assignment Date	26.10.2022
Student Name	Mr. Justinraj.J
Student Roll Number	821919104007
Maximum Marks	2 Marks

Question :

Write code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100 cms send an "alert" to the IBM cloud and display in the device recent events. Upload document with wokwi share link and images of IBM cloud.

Wokwi Link:

<https://wokwi.com/projects/322410731508073042>

Code:

```
#include <WiFi.h>
#include <PubSubClient.h>
WiFiClient wifiClient;
String data3;
#define ORG "jrb15n"
#define DEVICE_TYPE "Assignment4"
#define DEVICE_ID "12345"
#define TOKEN "12345678"
#define speed 0.034
#define led 14
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/data/fmt/json";
char topic[] = "iot-2/cmd/home/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);
void publishData();
const int trigpin = 5;
const int echopin = 18;
String command;
String data = "";
long duration;
float dist;

void setup()
```

```

{
  Serial.begin(115200);
  pinMode(led, OUTPUT);
  pinMode(trigpin, OUTPUT);
  pinMode(echopin, INPUT);
  wifiConnect();
  mqttConnect();
}

void loop() {
  bool isNearby = dist < 100;
  digitalWrite(led, isNearby);
  publishData();
  delay(500);
  if (!client.loop()) {
    mqttConnect();
  }
}

void wifiConnect() {
  Serial.print("Connecting to "); Serial.print("Wifi");
  WiFi.begin("Wokwi-GUEST", "", 6);
  while (WiFi.status() != WL_CONNECTED) {
    delay(500);
    Serial.print(".");
  }
  Serial.print("WiFi connected, IP address: ");
  Serial.println(WiFi.localIP());
}

void mqttConnect() {
  if (!client.connected()) {
    Serial.print("Reconnecting MQTT client to "); Serial.println(server);
    while (!client.connect(clientId, authMethod, token)) {
      Serial.print(".");
      delay(500);
    }
    initManagedDevice();
    Serial.println();
  }
}

void initManagedDevice() {
  if (client.subscribe(topic)) {
    // Serial.println(client.subscribe(topic));
    Serial.println("IBM subscribe to cmd OK");
  } else {
    Serial.println("subscribe to cmd FAILED");
  }
}

void publishData()
{

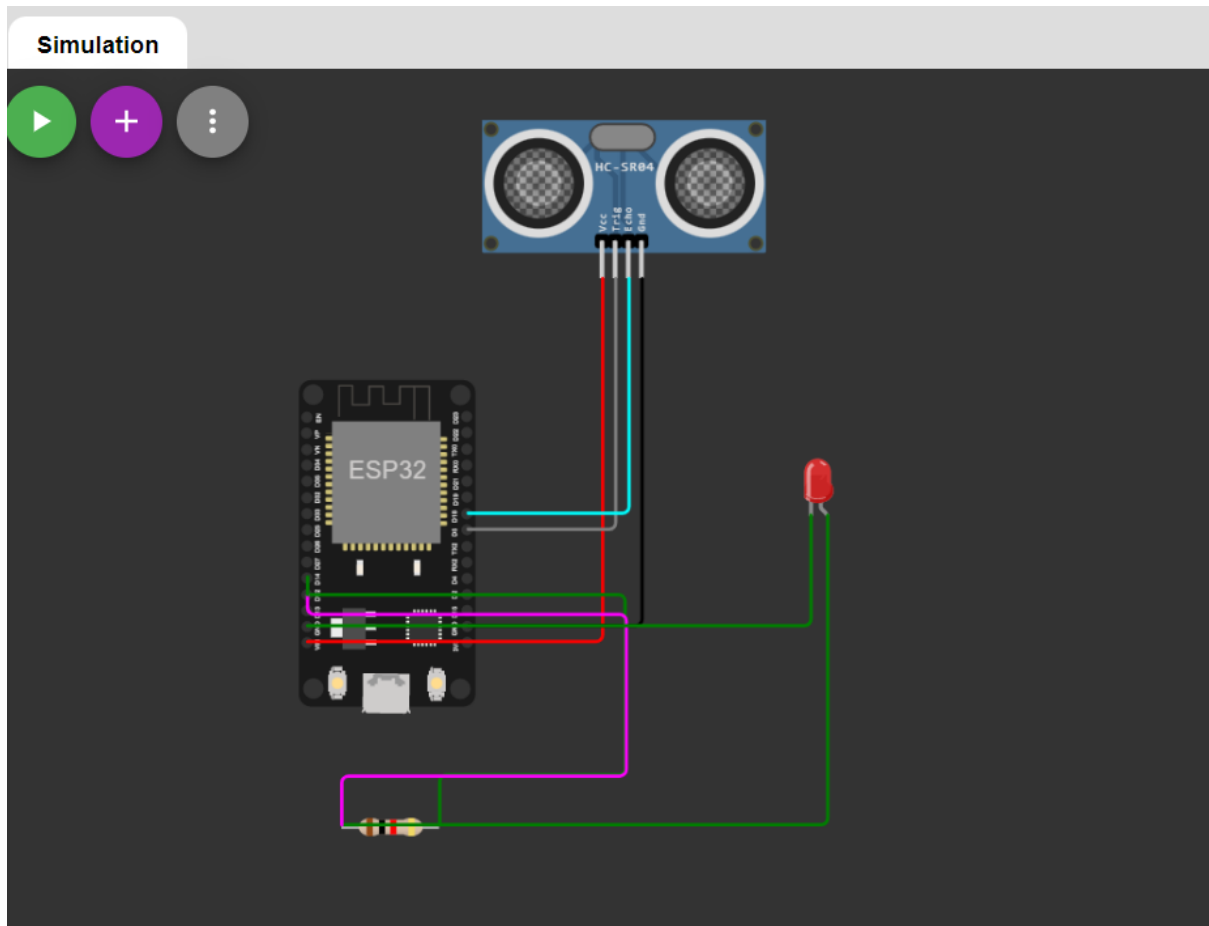
```

```

digitalWrite(trigpin, LOW);
digitalWrite(trigpin, HIGH);
delayMicroseconds(10);
digitalWrite(trigpin, LOW);
duration = pulseIn(echopin, HIGH);
dist = duration * speed / 2;
if (dist < 100) {
String payload = "{\"Normal Distance\":\"";
payload += dist;
payload += "\"}";
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c_str())) {
Serial.println("Publish OK");
}
}
if (dist > 101 ) {
String payload = "{\"Alert distance\":\"";
payload += dist;
payload += "\"}";
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c_str())) {
Serial.println("Warning crosses 110cm -- it automaticaly of the loop");
digitalWrite(led, HIGH);
} else {
Serial.println("Publish FAILED");
}
}
}
void callback(char* subscribeTopic, byte* payload, unsigned int payloadLength)
{
Serial.print("callback invoked for topic:");
Serial.println(subscribeTopic);
for (int i = 0; i < payloadLength; i++) {
dist += (char)payload[i];
}
Serial.println("data:" + data3);
if (data3 == "lighton") {
Serial.println(data3);
digitalWrite(led, HIGH);
}
data3 = "";
}

```

Circuit Diagram:



Output:

IBM Watson IoT Platform | esp32-dht22.ino - Wokwi Arduino |

wokwi.com/projects/322410731508073042

WOKWI | SAVE | SHARE | esp32-dht22.ino by urish | Docs

esp32-dht22.ino • diagram.json • libraries.txt • Library Manager

```
87 Serial.println(payload);
88 if (client.publish(publishTopic, (char*) payload.c_str())) {
89   Serial.println("Publish OK");
90 }
91 }
92 if (dist > 101) {
93   String payload = "{\"Alert distance\": ";
94   payload += dist;
95   payload += "}";
96   Serial.print("\n");
97   Serial.print("Sending payload: ");
98   Serial.println(payload);
99   if (client.publish(publishTopic, (char*) payload.c_str())) {
100     Serial.println("Warning crosses 110cm -- it automatically of the loop");
101     digitalWrite(led, HIGH);
102   } else {
103     Serial.println("Publish FAILED");
104   }
105 }
106 }
107 void callback(char* subscribeTopic, byte* payload, unsigned int payloadLength) {
108 {
109   Serial.print("callback invoked for topic:");
110   Serial.println(subscribeTopic);
111   for (int i = 0; i < payloadLength; i++) {
112     dist += (char)payload[i];
113   }
114   Serial.println("data:" + data3);
115   if (data3 == "lighton") {
116     Serial.println(data3);
117     digitalWrite(led, HIGH);
118   }
119 }
```

Simulation

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Sending payload: {"Normal Distance":25.94}
Publish OK

Sending payload: {"Normal Distance":25.94}
Publish OK

Sending payload: {"Normal Distance":25.94}
Publish OK

Sending payload: {"Normal Distance":25.94}
Publish OK

ENG INTL 2:30 PM 11/3/2022

IBM Watson IoT Platform

esp32-dht22.ino - Mikew Arduino

jrbl5n.internetofthings.ibmcloud.com/dashboard/devices/browse

821919104007@smartinternz.com
ID: jrbl5n

Browse

Action

Device Types

Interfaces

Add Device

Identity

Device Information

Recent Events

State

Logs

The recent events listed show the live stream of data that is coming and going from this device.

Event	Value	Format	Last Received
data	{"Normal Distance":25.94}	json	a few seconds ago
data	{"Normal Distance":25.94}	json	a few seconds ago
data	{"Normal Distance":25.94}	json	a few seconds ago
data	{"Normal Distance":25.94}	json	a few seconds ago
data	{"Normal Distance":25.94}	json	a few seconds ago

0 Simulations running

ENG
INTL

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11/5/2022