Sprint 01

Signs with Smart Connectivity for Better Road Safety

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Objective Sprint:

- 1. Make a python program ,finally the output is given input for location and weather
- 2. Open accounts in various public APIs like OpenWeather API.

Program Code:

> weather.txt

This file is a utility function that fetches the weather from OpenWeatherAPI. It returns only certain required parameters of the API response.

```
# Python code
import requests as reqs

def get(myLocation,APIKEY):
    apiURL =
f"https://api.openweathermap.org/data/2.5/weather?q={myLocation}&appid={APIKEY}"
    responseJSON = (reqs.get(apiURL)).json()
    returnObject = {
```

> brain.txt

This file is a utility function that returns only essential information to be displayed at the hardware side and abstracts all the unnecessary details. This is where the code flow logic is implemented.

```
# Python code
# IMPORT SECTION STARTS
import weather
from datetime import datetime as dt
# IMPORT SECTION ENDS
# UTILITY LOGIC SECTION STARTS
def processConditions(myLocation,APIKEY,localityInfo):
    weatherData = weather.get(myLocation,APIKEY)
    currentSpeed = localityInfo["usualSpeedLimit"] if "rain" not in weatherData else
localityInfo["usualSpeedLimit"]/2
    currentSpeed = currentSpeed if weatherData["visibility"]>35 else currentSpeed/2
    if(localityInfo["hospitalsNearby"]):
        # hospital zone
        doNotHonk = True
    else:
        if(localityInfo["schools"]["schoolZone"]==False):
            # neither school nor hospital zone
            work = False
        else:
            # school zone
            now = [dt.now().hour,dt.now().minute]
            activeTime = [list(map(int,_.split(":"))) for _ in
localityInfo["schools"]["activeTime"]]
            doNotHonk = activeTime[0][0] < = now[0] < = activeTime[1][0] and
activeTime[0][1]<=now[1]<=activeTime[1][1]</pre>
    return({
        "speed" : currentSpeed,
        "work" : work
    })
```

> main.txt

The code that runs in a forever loop in the micro-controller. This calls all the util functions from other python files and based on the return value transduces changes in the output hardware display.

```
# Python code
# IMPORT SECTION STARTS
import brain
# IMPORT SECTION ENDS
# -----
# USER INPUT SECTION STARTS
myLocation = "Erode,IN"
APIKEY = "9cd610e5fd400c74212074c7ace0d62c"
localityInfo = {
   "schools" : {
       "schoolZone" : True,
       "activeTime" : ["7:00","17:30"] # schools active from 7 AM till 5:30 PM
   "hospitalsNearby" : False,
   "usualSpeedLimit" : 40 # in km/hr
}
# USER INPUT SECTION ENDS
# MICRO-CONTROLLER CODE STARTS
print(brain.processConditions(myLocation,APIKEY,localityInfo))
MICRO CONTROLLER CODE WILL BE ADDED IN SPRINT 2 AS PER OUR PLANNED SPRINT SCHEDULE
# MICRO-CONTROLLER CODE ENDS
```

Output:

```
# Code Output
{'speed': 40, 'doNotHonk': False}
```