DELIVERY OF SPRINT-2

DATE	11 November 2022
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PROJECT NAME	SMART WASTE MANAGEMENT FOR METROPOLITAN CITIES-IOT

Code for Data Transfer from Sensors

```
#include <WiFi.h> // library for wifi
#include <PubSubClient.h> // library for MQTT
#include <LiquidCrystal_I2C.h>
LiquidCrystal_I2C lcd(0x27, 20, 4);
//---------------------- credentials of IBM Accounts ------------------------------------
------
#define ORG "fd7fvs" // IBM organisation id
#define DEVICE_TYPE "Smart_Management" // Device type mentioned in ibm watson
iot platform
#define DEVICE_ID "113355" // Device ID mentioned in ibm watson iot platform
#define TOKEN "1122334455" // Token
//---------------------- customise above values ----------------------------------------
------------------------
char server[] = ORG ".messaging.internetofthings.ibmcloud.com"; // server name
char publishTopic[] = "iot-2/evt/data/fmt/json";
char topic[] = "iot-2/cmd/led/fmt/String"; // cmd Represent type and command
is test format of strings
char authMethod[] = "use-token-auth"; // authentication method
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID; //Client id
//---------------------------------------------------------------------------------------
---------------------------------------
WiFiClient wifiClient; // creating instance for wificlient
PubSubClient client(server, 1883, wifiClient);
#define ECHO_PIN 12
#define TRIG_PIN 13
float dist;
void setup()
{
Serial.begin(115200);
pinMode(LED_BUILTIN, OUTPUT);
pinMode(TRIG_PIN, OUTPUT);
pinMode(ECHO_PIN, INPUT);
//pir pin
pinMode(4, INPUT);
//ledpins
pinMode(23, OUTPUT);
```

```
pinMode(2, OUTPUT);
pinMode(4, OUTPUT);
pinMode(15, OUTPUT);
lcd.init();
lcd.backlight();
lcd.setCursor(1, 0);
lcd.print("");
wifiConnect();
mqttConnect();
}
float readcmCM()
{
digitalWrite(TRIG_PIN, LOW);
delayMicroseconds(2);
digitalWrite(TRIG_PIN, HIGH);
delayMicroseconds(10);
digitalWrite(TRIG_PIN, LOW);
int duration = pulseIn(ECHO_PIN, HIGH);
return duration * 0.034 / 2;
}
void loop()
{
lcd.clear();
publishData();
delay(500);
if (!client.loop())
{
mqttConnect(); // function call to connect to IBM
}
}
/* ------------------------------------------------------------retrieving to
cloud-----------------------------------------------------------*/
void wifiConnect()
{
Serial.print("Connecting to ");
Serial.print("Wifi");
WiFi.begin("Wokwi-GUEST", "", 6);
while (WiFi.status() != WL_CONNECTED)
{
delay(500);
Serial.print(".");
}
Serial.print("WiFi connected, IP address: ");
Serial.println(WiFi.localIP());
}
void mqttConnect()
{
if (!client.connected())
```

```
{
Serial.print("Reconnecting MQTT client to ");
Serial.println(server);
while (!client.connect(clientId, authMethod, token))
{
Serial.print(".");
delay(500);
}
initManagedDevice();
Serial.println();
}
}
void initManagedDevice()
{
if (client.subscribe(topic))
{
Serial.println("IBM subscribe to cmd OK");
}
else
{
Serial.println("subscribe to cmd FAILED");
}
}
void publishData()
{
float cm =  readcmCM();
if(digitalRead(34)) //PIR motion detection
{
Serial.println("Motion Detected");
Serial.println("Lid Opened");
digitalWrite(15, HIGH);
}
else
{
digitalWrite(15, LOW);
}
if(digitalRead(34)== true)
{
if(cm <= 100) //Bin level detection
{
digitalWrite(2, HIGH);
Serial.println("High Alert!!!,Trash bin is about to be full");
Serial.println("Lid Closed");
lcd.print("Full! Don't use");
delay(2000);
lcd.clear();
digitalWrite(4, LOW);
digitalWrite(23, LOW);
```

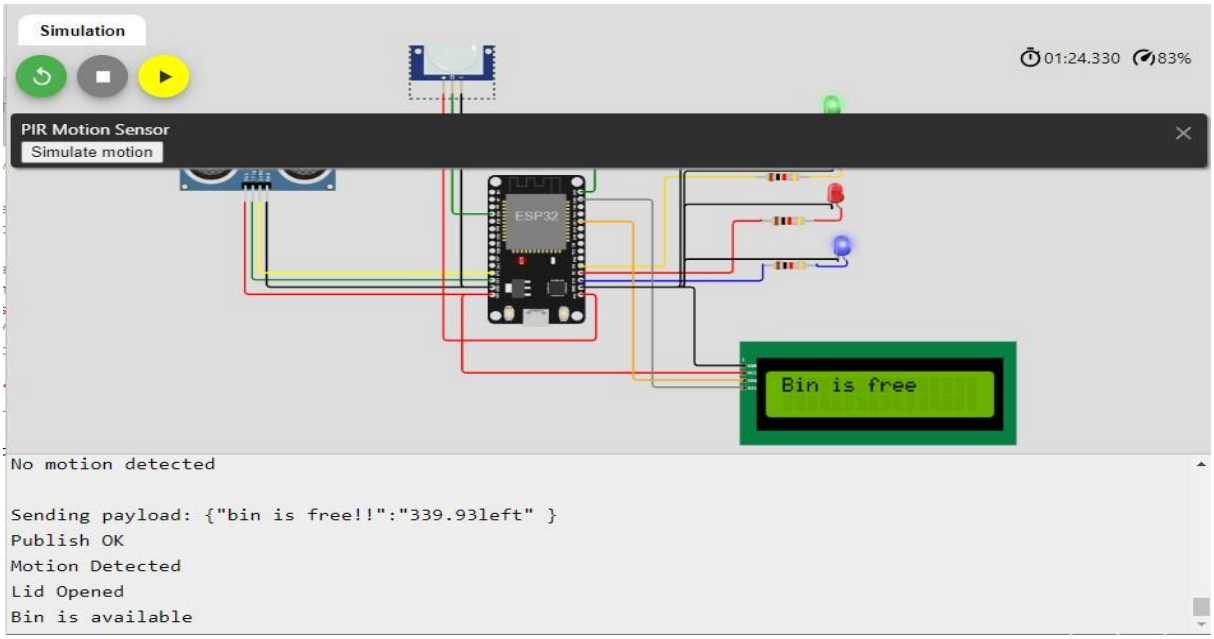
```
}
else if(cm > 150 && cm < 250)
{
digitalWrite(4, HIGH);
Serial.println("Warning!!,Trash is about to cross 50% of bin level");
lcd.print("50% is filled");
delay(2000);
lcd.clear();
digitalWrite(2, LOW);
digitalWrite(23, LOW);
}
else if(cm > 250 && cm <=400)
{
digitalWrite(23, HIGH);
Serial.println("Bin is available");
lcd.print("Bin is free");
delay(2000);
lcd.clear();
digitalWrite(2,LOW);
digitalWrite(4, LOW);
}
delay(10000);
Serial.println("Lid Closed");
}
else
{
Serial.println("No motion detected");
}
if(cm <= 100)
{
digitalWrite(21,HIGH);
String payload = "{\"High Alert!!\":\"";
payload += cm;
payload += "left\" }";
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c_str())) // if data is
uploaded to cloud successfully,prints publish ok or prints publish failed
{
Serial.println("Publish OK");
}
}
if(cm >= 100 && cm <= 250)
{
digitalWrite(22,HIGH);
String payload = "{\"50% Warning!!\":\"";
payload += cm;
```

```
payload += "left\" }";
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if(client.publish(publishTopic, (char*) payload.c_str()))
{
Serial.println("Publish OK");
}
else
{
Serial.println("Publish FAILED");
}
}
if(cm >= 250 && cm <= 400)
{
digitalWrite(22,HIGH);
String payload = "{\"bin is free!!\":\"";
payload += cm;
payload += "left\" }";
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if(client.publish(publishTopic, (char*) payload.c_str()))
{
Serial.println("Publish OK");
}
else
{
Serial.println("Publish FAILED");
}
}
float inches = (cm / 2.54); //print on LCD
lcd.setCursor(0,0);
lcd.print("Inches");
lcd.setCursor(4,0);
lcd.setCursor(12,0);
lcd.print("cm");
lcd.setCursor(1,1);
lcd.print(inches, 1);
lcd.setCursor(11,1);
lcd.print(cm, 1);
lcd.setCursor(14,1);
delay(1000);
lcd.clear();
}
```

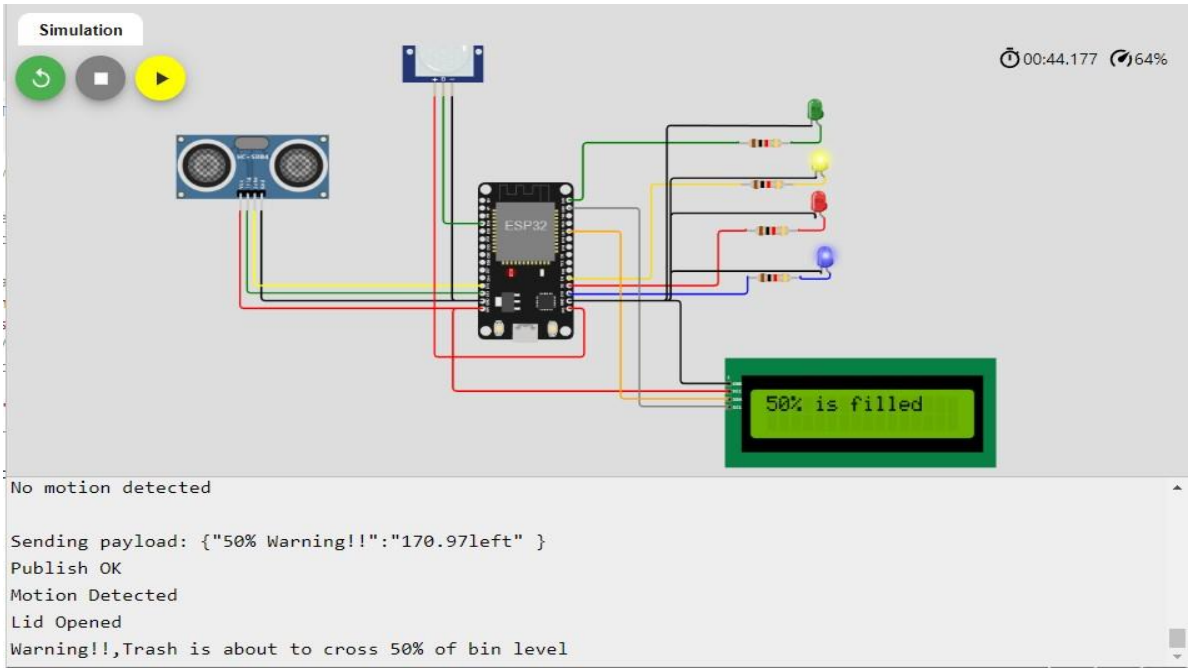
Connection Diagram

Wokwi output: **link(https://wokwi.com/projects/347871000559354450)**

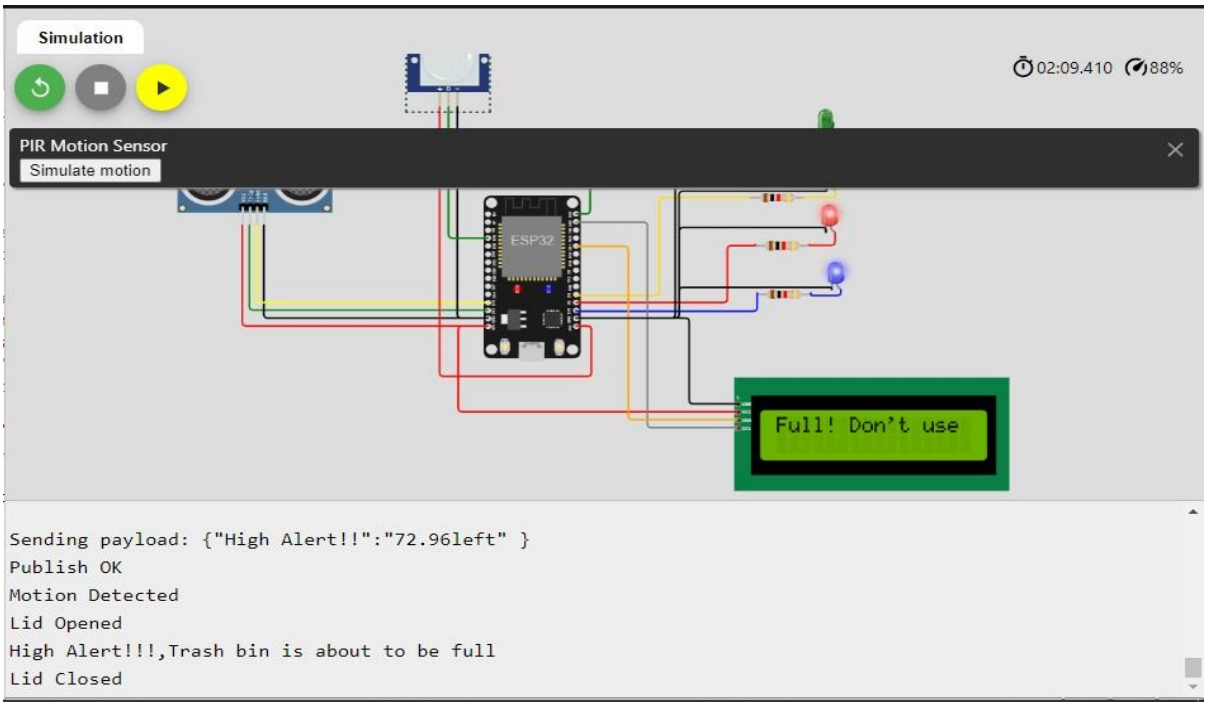
- When The Trash Bin Is Free Are Above 50% It Indicates Green Light.(That The User May Use The Bin To Put The Waste..)



- When The Trash Bin Is 50% and less than 50% It Indicates Yellow Light.

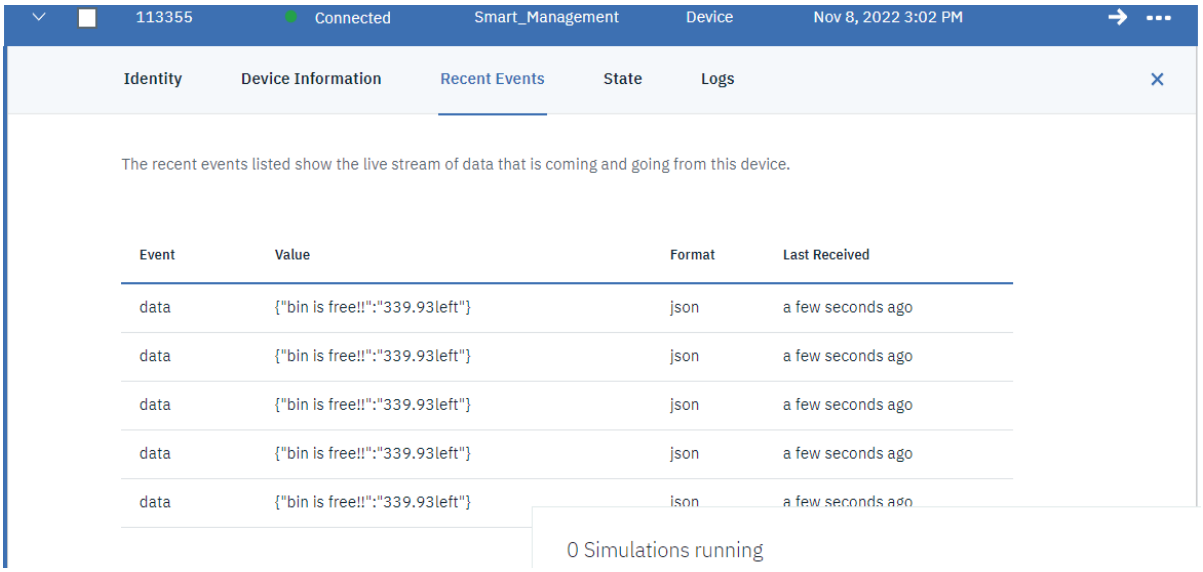


- When The Trash Bin Is below 10% It Indicates Red Light.(That Warns User Not To Use The Bin).

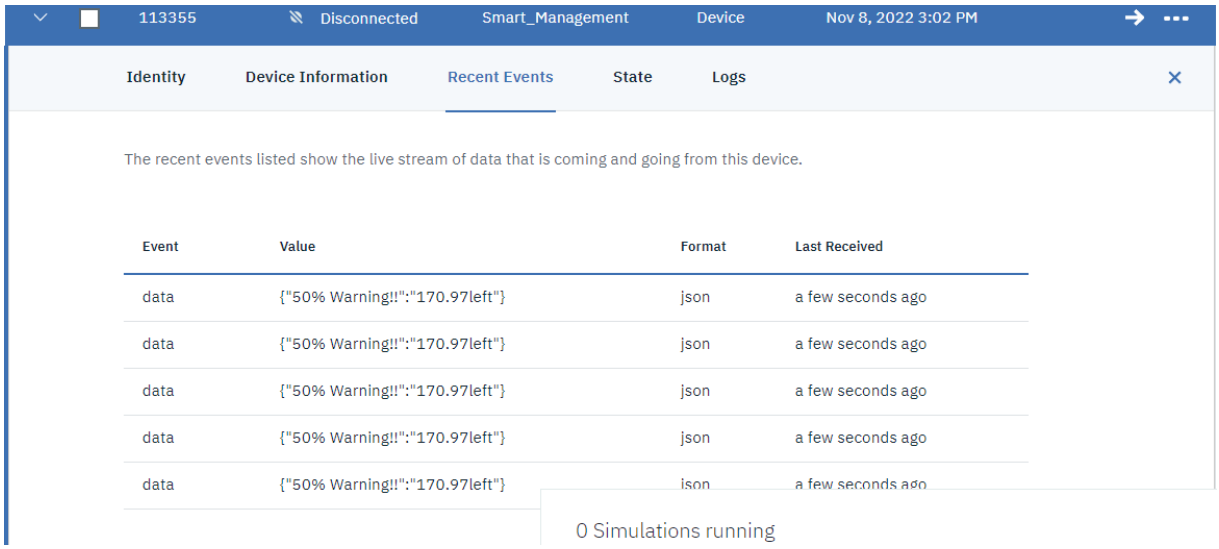


Output Displayed in IoT Platform:

- If the bin is free ,it indicates a message as "bin is free!!".



- If the bin is 50% filled ,it indicates the Message as”50%WARNING”.



- If the bin is filled or about to fill ,it indicates the message as ”HIGH ALERT”.