## **ASSIGNMENT-4**

## **WOKWI PROGRAM**

ASSIGNMENT DATE	26 OCT
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MAXIMUM MARK	2 MARK

## **CODE**

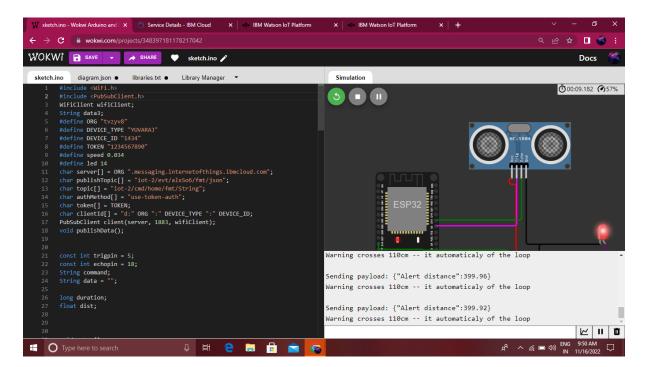
```
#include <WiFi.h>
#include <PubSubClient.h>
WiFiClient wifiClient;
String data3;
#define ORG "tvzyv8"
#define DEVICE TYPE "YUVARAJ"
#define DEVICE ID "1434"
#define TOKEN "1234567890"
#define speed 0.034
#define led 14
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/SAKTHIVEL/fmt/json";
char topic[] = "iot-2/cmd/home/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE TYPE ":" DEVICE ID;
PubSubClient client(server, 1883, wifiClient);
void publishData();
const int trigpin = 5;
const int echopin = 18;
String command;
String data = "";
long duration;
float dist;
```

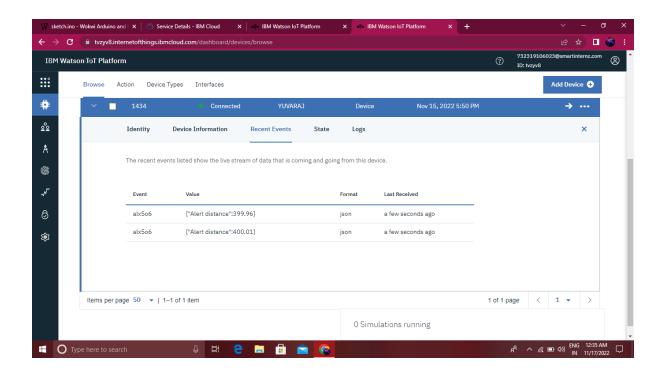
```
void setup()
  Serial.begin(115200);
  pinMode(led, OUTPUT);
  pinMode(trigpin, OUTPUT);
  pinMode(echopin, INPUT);
 wifiConnect();
  mqttConnect();
void loop() {
  bool isNearby = dist < 100;</pre>
  digitalWrite(led, isNearby);
  publishData();
  delay(500);
  if (!client.loop()) {
    mqttConnect();
void wifiConnect() {
  Serial.print("Connecting to "); Serial.print("Wifi");
 WiFi.begin("Wokwi-GUEST", "", 6);
  while (WiFi.status() != WL_CONNECTED) {
    delay(500);
    Serial.print(".");
 Serial.print("WiFi connected, IP address: ");
Serial.println(WiFi.localIP());
void mqttConnect() {
 if (!client.connected()) {
    Serial.print("Reconnecting MQTT client to "); Serial.println(server);
    while (!client.connect(clientId, authMethod, token)) {
      Serial.print(".");
      delay(500);
    initManagedDevice();
    Serial.println();
  }
void initManagedDevice() {
```

```
if (client.subscribe(topic)) {
    // Serial.println(client.subscribe(topic));
    Serial.println("IBM subscribe to cmd OK");
 } else {
    Serial.println("subscribe to cmd FAILED");
void publishData()
 digitalWrite(trigpin, LOW);
 digitalWrite(trigpin, HIGH);
 delayMicroseconds(10);
 digitalWrite(trigpin, LOW);
 duration = pulseIn(echopin, HIGH);
 dist = duration * speed / 2;
 if (dist < 100) {</pre>
    String payload = "{\"Normal Distance\":";
   payload += dist;
    payload += "}";
   Serial.print("\n");
   Serial.print("Sending payload: ");
   Serial.println(payload);
    if (client.publish(publishTopic, (char*) payload.c_str())) {
     Serial.println("Publish OK");
 if (dist > 101 ) {
    String payload = "{\"Alert distance\":";
    payload += dist;
    payload += "}";
   Serial.print("\n");
    Serial.print("Sending payload: ");
   Serial.println(payload);
    if (client.publish(publishTopic, (char*) payload.c_str())) {
     Serial.println("Warning crosses 110cm -- it automaticaly of the loop");
     digitalWrite(led, HIGH);
   } else {
      Serial.println("Publish FAILED");
 }
void callback(char* subscribeTopic, byte* payload, unsigned int payloadLength)
```

```
Serial.print("callback invoked for topic:");
Serial.println(subscribeTopic);
for (int i = 0; i < payloadLength; i++) {
    dist += (char)payload[i];
}
Serial.println("data:" + data3);
if (data3 == "lighton") {
    Serial.println(data3);
    digitalWrite(led, HIGH);
}
data3 = "";
}</pre>
```

## **OUTPUT**





**1.LESS THAN 100** 

