

SMART WASTE MANAGEMENT

USING INTERNET OF THINGS

CODE :

```
include <WiFi.h> // library for wifi
#include <PubSubClient.h> // library for MQTT
#include <LiquidCrystal_I2C.h>
LiquidCrystal_I2C lcd(0x27, 20, 4);
//----- credentials of IBM Accounts -----
-----
#define ORG "wsl5rn" // IBM organisation id
#define DEVICE_TYPE "GARBAGE" // Device type mentioned in ibm watson iot
platform
#define DEVICE_ID "113366" // Device ID mentioned in ibm watson iot platform
#define TOKEN "11223344556678" // Token
//----- customise above values -----
-----
char server[] = ORG ".messaging.internetofthings.ibmcloud.com"; // server name
char publishTopic[] = "iot-2/evt/data/fmt/json";
char topic[] = "iot-2/cmd/led/fmt/String"; // cmd Represent type and command
is test format of strings
char authMethod[] = "use-token-auth"; // authentication method
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID; //Client id
//-----
-----
WiFiClient wifiClient; // creating instance for wificlient
PubSubClient client(server, 1883, wifiClient);
#define ECHO_PIN 12
#define TRIG_PIN 13
float dist;
void setup()
{
  Serial.begin(115200);
  pinMode(LED_BUILTIN, OUTPUT);
  pinMode(TRIG_PIN, OUTPUT);
  pinMode(ECHO_PIN, INPUT);
  //pir pin
  pinMode(4, INPUT);
  //ledpins
  pinMode(23, OUTPUT);
  pinMode(2, OUTPUT);
  pinMode(4, OUTPUT);
```

```

pinMode(15, OUTPUT);
lcd.init();
lcd.backlight();
lcd.setCursor(1, 0);
lcd.print("");
wifiConnect();
mqttConnect();
}
float readcmCM()
{
digitalWrite(TRIG_PIN, LOW);
delayMicroseconds(2);
digitalWrite(TRIG_PIN, HIGH);
delayMicroseconds(10);
digitalWrite(TRIG_PIN, LOW);
int duration = pulseIn(ECHO_PIN, HIGH);
return duration * 0.034 / 2;
}
void loop()
{
lcd.clear();
publishData();
delay(500);
if (!client.loop())
{
mqttConnect(); // function call to connect to IBM
}
}
/* -----retrieving to
cloud-----*/
void wifiConnect()
{
Serial.print("Connecting to ");
Serial.print("Wifi");
WiFi.begin("Wokwi-GUEST", "", 6);
while (WiFi.status() != WL_CONNECTED)
{
delay(500);
Serial.print(".");
}
Serial.print("WiFi connected, IP address: ");
Serial.println(WiFi.localIP());
}
void mqttConnect()
{
if (!client.connected())
{
Serial.print("Reconnecting MQTT client to ");

```

```

Serial.println(server);
while (!client.connect(clientId, authMethod, token))
{
    Serial.print(".");
    delay(500);
}
initManagedDevice();
Serial.println();
}
}
void initManagedDevice()
{
    if (client.subscribe(topic))
    {
        Serial.println("IBM subscribe to cmd OK");
    }
    else
    {
        Serial.println("subscribe to cmd FAILED");
    }
}
void publishData()
{
    float cm = readcmCM();
    if(digitalRead(34)) //PIR motion detection
    {
        Serial.println("Motion Detected");
        Serial.println("Lid Opened");
        digitalWrite(15, HIGH);
    }
    else
    {
        digitalWrite(15, LOW);
    }
    if(digitalRead(34)== true)
    {
        if(cm <= 100) //Bin level detection
        {
            digitalWrite(2, HIGH);
            Serial.println("High Alert!!!,Trash bin is about to be full");
            Serial.println("Lid Closed");
            lcd.print("Full! Don't use");
            delay(2000);
            lcd.clear();
            digitalWrite(4, LOW);
            digitalWrite(23, LOW);
        }
        else if(cm > 150 && cm < 250)

```

```

{
digitalWrite(4, HIGH);
Serial.println("Warning!!,Trash is about to cross 50% of bin level");
digitalWrite(2, LOW);
digitalWrite(23, LOW);
}
else if(cm > 250 && cm <=400)
{
digitalWrite(23, HIGH);
Serial.println("Bin is available");
digitalWrite(2,LOW);
digitalWrite(4, LOW);
}
delay(10000);
Serial.println("Lid Closed");
}
else
{
Serial.println("No motion detected");
}
if(cm <= 100)
{
digitalWrite(21,HIGH);
String payload = "{\"High Alert!!\":";
payload += cm;
payload += "left\" }";
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c_str())) // if data is
uploaded to cloud successfully,prints publish ok or prints publish failed
{
Serial.println("Publish OK");
}
}
if(cm <= 250)
{
digitalWrite(22,HIGH);
String payload = "{\"Warning!!\":";
payload += dist;
payload += "left\" }";
Serial.print("\n");
Serial.print("Sending distance: ");
Serial.println(cm);
if(client.publish(publishTopic, (char*) payload.c_str()))
{
Serial.println("Publish OK");
}
}

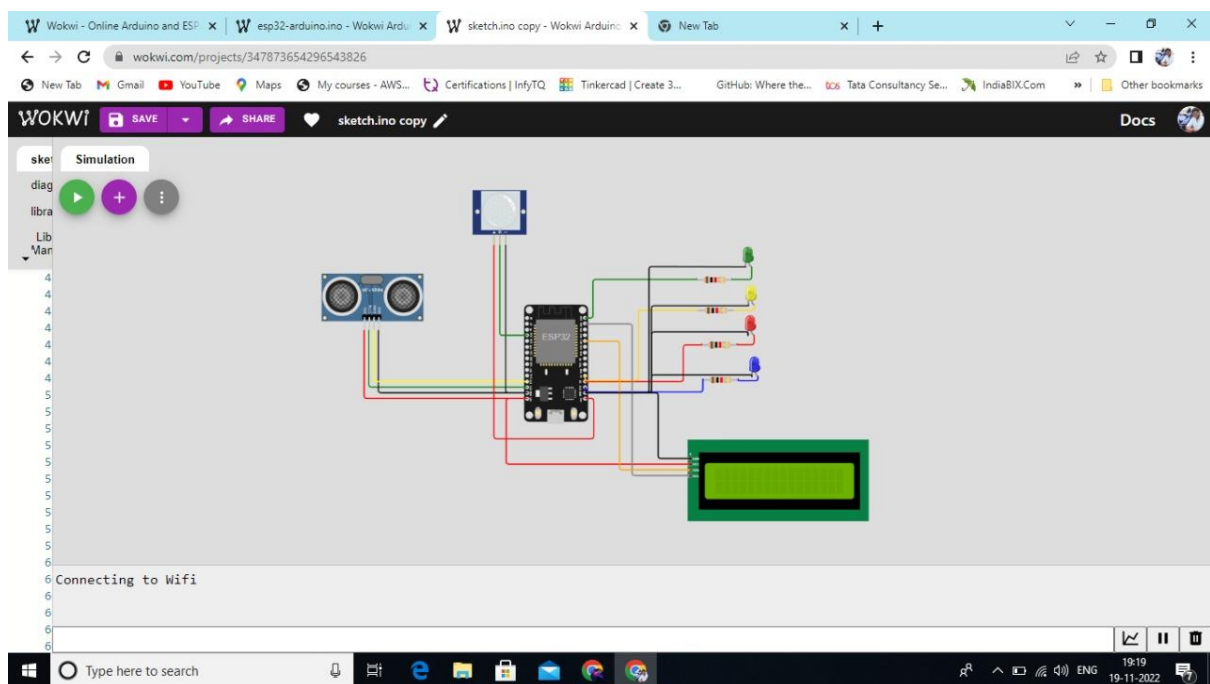
```

```

else
{
  Serial.println("Publish FAILED");
}
}

float inches = (cm / 2.54); //print on LCD
lcd.setCursor(0,0);
lcd.print("Inches");
lcd.setCursor(4,0);
lcd.setCursor(12,0);
lcd.print("cm");
lcd.setCursor(1,1);
lcd.print(inches, 1);
lcd.setCursor(11,1);
lcd.print(cm, 1);
lcd.setCursor(14,1);
delay(1000);
lcd.clear();
}

```



Wokwi - Online Arduino and ESP8266 IDE

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```

46 delayMicroseconds(2);
47 digitalWrite(TRIG_PIN, HIGH);
48 delayMicroseconds(10);
49 digitalWrite(TRIG_PIN, LOW);
50 int duration = pulseIn(ECHO_PIN, HIGH);
51 return duration * 0.034 / 2;
52 }
53 void loop()
54 {
55   lcd.clear();
56   publishData();
57   delay(500);
58   if (!client.loop())
59   {
60     mqttConnect(); // function call to connect to IBM
61   }
62 }
63 /* -----retrieving to cloud----- */
64 void wifiConnect()
65 {
66   Serial.print("Connecting to ");
67   Serial.print("Wifi");
68   WiFi.begin("Wokwi-GUEST", "", 6);
69   while (WiFi.status() != WL_CONNECTED)
70   {
71     delay(500);
72     Serial.print(".");
73   }

```

Simulation

01:31.718 89%

No motion detected

Sending distance: 132.99
Publish OK
Reconnecting MQTT client to
ws15rn.messaging.internetofthings.ibmcloud.com

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17 //-----
18 WiFiClient wifiClient; // creating instance for wifiClient
19 PubSubClient client(server, 1883, wifiClient);
20 #define ECHO_PIN 12
21 #define TRIG_PIN 13
22 float dist;
23 void setup()
24 {
25   Serial.begin(115200);
26   pinMode(LED_BUILTIN, OUTPUT);
27   pinMode(TRIG_PIN, OUTPUT);
28   pinMode(ECHO_PIN, INPUT);
29   //pin_nin

```

Simulation

01:08.523 62%

No motion detected

Sending distance: 132.99
Publish OK
No motion detected

Sending distance: 132.99

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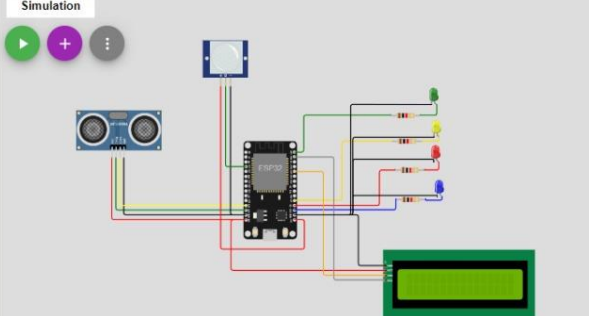
Wokwi

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sketch.ino diagram.json libraries.txt Library Manager

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43 float readcmCH()
44 {
45   digitalWrite(TRIG_PIN, LOW);
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49   digitalWrite(TRIG_PIN, LOW);
50   int duration = pulseIn(ECHO_PIN, HIGH);
51   return duration * 0.034 / 2;
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53 void loop()
54 {
55   lcd.clear();
56   publishData();
57   delay(500);
58   if (!client.loop())
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60     mqttConnect(); // function call to connect to IBM
61   }
62 }
63 /* -----retrieving to cloud----- */
64 void wifiConnect()
65 {
66   Serial.print("Connecting to ");
67   Serial.print("Wifi");
68   Wifi.begin("Wokwi-GUEST", "", 6);
69   while (Wifi.status() != WL_CONNECTED)
70   {
71     delay(500);
```

Simulation



Connecting to Wifi

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19:18 19-11-2022