

ASSIGNMENT-4

Write code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100 cms send an "alert" to the IBM cloud and display in the device recent events.

CODE:

```
#include <WiFi.h>
#include <WiFiClient.h>
#include <PubSubClient.h>
const int trigPin = 5;
const int echoPin = 18;
//define sound speed in cm/uS
#define Speed 0.034
#define cm_to_inch 0.393701
long duration;
float distance;
float distanceInch;

void callback(char* subscribetopic, byte* payload, unsigned int
payloadLength);
//-----credentials of IBM Accounts-----

#define ORG "tej4h6"//IBM ORGANITION ID
#define DEVICE_TYPE "ultrasonic"//Device type mentioned in ibm watson IOT
Platform
#define DEVICE_ID "ultrasonicsensor"//Device ID mentioned in ibm watson IOT
Platform
#define TOKEN "12345678" //Token
String data3;

//----- Customise the above values -----
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";// Server Name
char publishTopic[] = "iot-2/evt/Data/fmt/json";// topic name and type of
event perform and format in which data to be send
char subscribetopic[] = "iot-2/cmd/test/fmt/String";// cmd REPRESENT command
type AND COMMAND IS TEST OF FORMAT STRING
char authMethod[] = "use-token-auth";// authentication method
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;//client id

WiFiClient wifiClient; // creating the instance for wificlient
PubSubClient client(server, 1883, callback ,wifiClient);

void setup() {
  Serial.begin(115200); // Starts the serial communication
  pinMode(trigPin, OUTPUT); // Sets the trigPin as an Output
  pinMode(echoPin, INPUT); // Sets the echoPin as an Input
```

```

    Serial.println();
    wificonnect();
    mqttconnect();

}

void loop() {
    // Clears the trigPin
    digitalWrite(trigPin, LOW);
    delayMicroseconds(2);
    // Sets the trigPin on HIGH state for 10 micro seconds
    digitalWrite(trigPin, HIGH);
    delayMicroseconds(10);
    digitalWrite(trigPin, LOW);

    // Reads the echoPin, returns the sound wave travel time in microseconds
    duration = pulseIn(echoPin, HIGH);

    // Calculate the distance
    distance = duration * Speed/2;

    // Convert to inches
    distanceInch = distance * cm_to_inch;

    // Prints the distance in the Serial Monitor
    Serial.print("Distance : ");
    Serial.println(distance);

    PublishData(distance);
    delay(1000);
    if (!client.loop()) {
        mqttconnect();
    }
}

void PublishData(float centimeter) {
    mqttconnect();//function call for connecting to ibm
    /*
        creating the String in in form JSON to update the data to ibm cloud
    */
    String payload = "{\"Distance in Centimeter\":\"";
    payload += centimeter;
    payload += "\"}";

    Serial.print("Sending payload: ");
    Serial.println(payload);
}

```

```

    if (client.publish(publishTopic, (char*) payload.c_str())) {
        Serial.println("Publish ok");// if it successfully upload data on the cloud
        then it will print publish ok in Serial monitor or else it will print publish
        failed
    } else {
        Serial.println("Publish failed");
    }
}

void mqttconnect() {
    if (!client.connected()) {
        Serial.print("Reconnecting client to ");
        Serial.println(server);
        while (!client.connect(clientId, authMethod, token)) {
            Serial.print(".");
            delay(500);
        }

        initManagedDevice();
        Serial.println();
    }
}

void wificonnect() //function definition for wificonnect
{
    Serial.println();
    Serial.print("Connecting... ");

    WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish
the connection
    while (WiFi.status() != WL_CONNECTED) {
        delay(500);
        Serial.print(".");
    }
    Serial.println("");
    Serial.println("WiFi connected");
    Serial.println("IP address: ");
    Serial.println(WiFi.localIP());
}

void initManagedDevice() {
    if (client.subscribe(subscribetopic)) {
        Serial.println((subscribetopic));
        Serial.println("subscribe to cmd OK");
    } else
    {
        Serial.println("subscribe to cmd FAILED");
    }
}

```

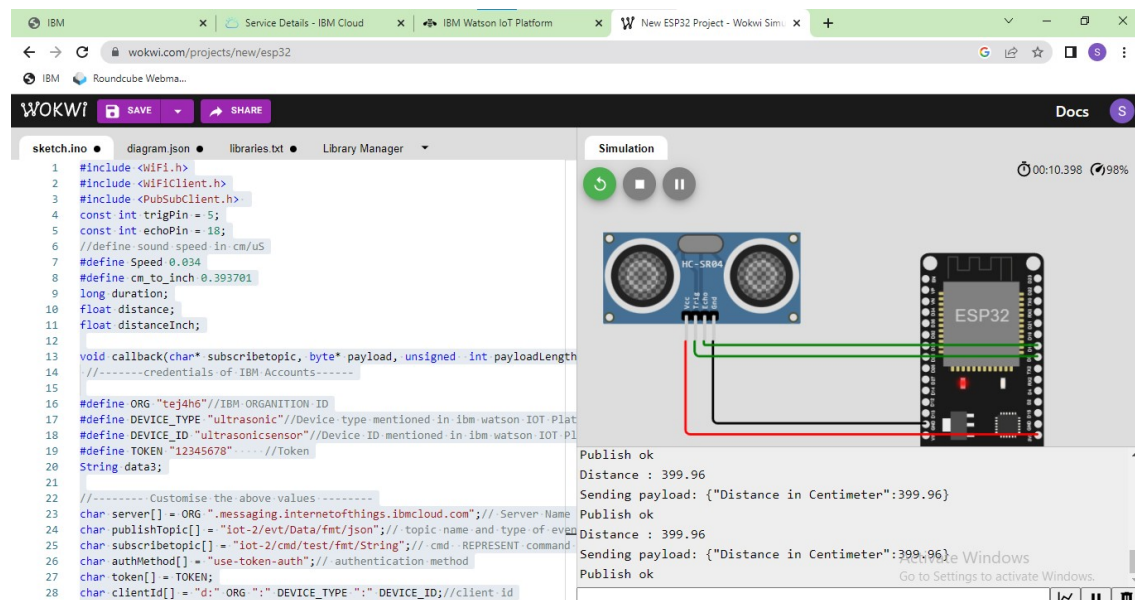
```

}
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
{

    Serial.print("callback invoked for topic: ");
    Serial.println(subscribetopic);
    for (int i = 0; i < payloadLength; i++) {
        //Serial.print((char)payload[i]);
        data3 += (char)payload[i];
    }
}
}

```

OUTPUT:



The screenshot shows the IBM Watson IoT Platform interface. The top navigation bar includes 'Browse', 'Action', 'Device Types', and 'Interfaces'. A sidebar on the left contains icons for various functions. The main content area displays details for a device named 'ultrasonicsensor', which is 'Connected'. Below this, there are tabs for 'Identity', 'Device Information', 'Recent Events', 'State', and 'Logs'. The 'Recent Events' tab is active, showing a table of events.

Event	Value	Format	Last Received
Data	{"Distance in Centimeter":399.96}	json	a few seconds ago
Data	{"Distance in Centimeter":399.96}	json	a few seconds ago
Data	{"Distance in Centimeter":399.98}	json	a few seconds ago
Data	{"Distance in Centimeter":399.96}	json	a few seconds ago
Data	{"Distance in Centimeter":399.96}	json	a few seconds ago

An 'Add Device' button is visible in the top right corner of the device details section. A Windows watermark is present in the bottom right corner of the screenshot.

WOKWI SHARE LINK

<https://wokwi.com/projects/new/esp32>