PROJECT DEVELOPMENT PHASE DELIVERY OF SPRINT-1

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Team ID	PNT2022TMID51665
Project Name	Project - Industry Specific Intelligent Fire Management System

```
#include <WiFi.h>
#include <Wire.h>
#include <SPI.h>
#include "ThingSpeak.h"
#include <WiFiClient.h>
unsigned long myChannelNumber = 2;
const char * myWriteAPIKey = "25V40ZAPI6KIZFGY";
int LED_PIN = 32; // the current reading from the input pin
int BUZZER_PIN= 12;
const int mq2 = 4;
int value = 0;
//Flame
int flame sensor pin = 10;// initializing pin 10 as the sensor digital output
pin int flame_pin = HIGH; // current state of sensor
char ssid[] = "Jenito";
char pass[] = "Jose Jenito";
WiFiClient client;
#define PIN_LM35 39
#define ADC_VREF_mV 3300.0
#define ADC_RESOLUTION 4096.0
void setup()
  Serial.begin(115200);
  Serial.print("Connecting to ");
 Serial.println(ssid);
WiFi.begin(ssid, pass);
 int wifi ctr = 0;
 while (WiFi.status() != WL_CONNECTED)
 {
 delay(1000);
 Serial.print(".");
```

```
Serial.println("WiFi connected");
 ThingSpeak.begin(client);
pinMode(LED_PIN, OUTPUT);
pinMode(mq2, INPUT); pinMode (
flame_sensor_pin , INPUT ); // declaring
sensor pin as input pin for Arduino
pinMode(BUZZER_PIN, OUTPUT);
}
void temperature()
 int adcVal = analogRead(PIN_LM35);
 float milliVolt = adcVal * (ADC_VREF_mV /
ADC_RESOLUTION); float tempC = milliVolt / 10;
Serial.print("Temperature: ");
 Serial.print(tempC);
Serial.print("°C");
 if(tempC > 60)
  Serial.println("Alert");
  digitalWrite(BUZZER_PIN, HIGH); // turn on
else
 {
   digitalWrite(BUZZER PIN, LOW); // turn on
 int x = ThingSpeak.writeField(myChannelNumber,1, tempC, myWriteAPlKey);
}
void GasSensors()
 //mq2
 int gassensorAnalogmq2 = analogRead(mq2);
 Serial.print("mq2 Gas Sensor: ");
 Serial.print(gassensorAnalogmq2);
 Serial.print("\t");
 Serial.print("\t");
 Serial.print("\t");
 if (gassensorAnalogmq2 > 1500)
  Serial.println("mg2Gas");
  Serial.println("Alert");
else
```

```
Serial.println("No mq2Gas");
 int a = ThingSpeak.writeField(myChannelNumber,4, gassensorAnalogmq2,
myWriteAPIKey); }
void flamesensor()
flame_pin = digitalRead (flame_sensor_pin); // reading from the
sensor if (flame_pin == LOW ) // applying condition
Serial.println ( " ALERT: FLAME DETECTED" );
digitalWrite (buz_pin, HIGH);//if state is high, then turn high the
BUZZER }
else
Serial.println ( " NO FLAME DETECTED " );
digitalWrite (buz_pin, LOW); // otherwise turn it low
}
void loop() {
temperature()
GasSensors()
flamesensor()
}
```