

PROBLEM STATEMENT :

IoT Based Smart Solution for Railways

DOMAIN :

Internet of Things

ASSIGNMENT 4:

Write code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100 cms send an "alert" to the IBM cloud and display in the device recent events. Upload document with wokwi share link and images of IBM cloud

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Question-1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to IBM cloud and display in device recent events.

WOKWI LINK:

<https://wokwi.com/projects/347922986871816786>

CODE:

```
#include <WiFi.h>
#include <PubSubClient.h>
WiFiClient wifiClient;
String data3;
#define ORG "6w5ymb"
#define DEVICE_TYPE "esp32_ultrasonic"
#define DEVICE_ID "arun"
#define TOKEN "6363636363"
#define speed 0.034
#define led 14
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/manimd/fmt/json";
char topic[] = "iot-2/cmd/led/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);
```

```
const int trigpin=5;
const int echopin=18;
String command;
String data="";
```

```
long duration;
float dist;
```

```
void setup()
{
  Serial.begin(115200);
  pinMode(led, OUTPUT);
  pinMode(trigpin, OUTPUT);
  pinMode(echopin, INPUT);
```

```

    wifiConnect();
    mqttConnect();
}

void loop() {
    bool isNearby = dist < 100;
    digitalWrite(led, isNearby);

    publishData();
    delay(500);

    if (!client.loop()) {
        mqttConnect();
    }
}

void wifiConnect() {
    Serial.print("Connecting to "); Serial.print("Wifi");
    WiFi.begin("Wokwi-GUEST", "", 6);
    while (WiFi.status() != WL_CONNECTED) {
        delay(500);
        Serial.print(".");
    }
    Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
}

void mqttConnect() {
    if (!client.connected()) {
        Serial.print("Reconnecting MQTT client to "); Serial.println(server);
        while (!client.connect(clientId, authMethod, token)) {
            Serial.print(".");
            delay(500);
        }
        initManagedDevice();
        Serial.println();
    }
}

void initManagedDevice() {
    if (client.subscribe(topic)) {
        // Serial.println(client.subscribe(topic));
        Serial.println("IBM subscribe to cmd OK");
    } else {
        Serial.println("subscribe to cmd FAILED");
    }
}

void publishData()
{
    digitalWrite(trigpin, LOW);
    digitalWrite(trigpin, HIGH);
    delayMicroseconds(10);
    digitalWrite(trigpin, LOW);
    duration=pulseIn(echopin, HIGH);
    dist=duration*speed/2;
    if(dist<100){
        String payload = "{\"Alert Distance\":\"";
        payload += dist;
        payload += "\"}";
    }
}

```

```

Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c_str())) {
    Serial.println("Publish OK");
}
}

if(dist>100){
String payload = "{\"Distance\":\"";
payload += dist;
payload += "}";

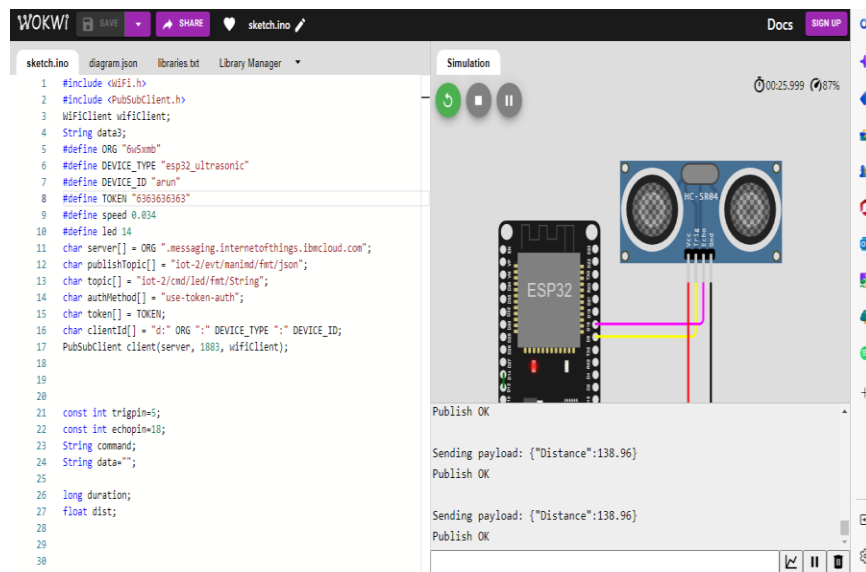
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if(client.publish(publishTopic, (char*) payload.c_str())) {
    Serial.println("Publish OK");
}else {
    Serial.println("Publish FAILED");
}
}

}

}

```

OUTPUT:



Watson iot connected:

The screenshot displays the IBM Watson IoT Platform interface. At the top, the header shows the platform name and a user profile. The main navigation bar includes 'Browse', 'Action', 'Device Types', and 'Interfaces'. A sidebar on the left contains various icons for navigation. The central area shows a list of devices, with 'arun' selected and its status 'Connected'. Below the device list, a detailed view for 'arun' is shown, including tabs for 'Identity', 'Device Information', 'Recent Events', 'State', and 'Logs'. The 'Recent Events' tab is active, displaying a table of events.

Event	Value	Format	Last Received
manimd	["Distance":138.96]	json	a few seconds ago
manimd	["Distance":138.96]	json	a few seconds ago
manimd	["Distance":138.96]	json	a few seconds ago
manimd	["Distance":138.96]	json	a few seconds ago
manimd	["Distance":138.96]	json	a few seconds ago