PROBLEM STATEMENT:

IoT Based Smart Solution for Railways

DOMAIN:

Internet of Things

ASSIGNMENT 1:

Smart home with at least two sensors and led, buzzer in TinkerCad

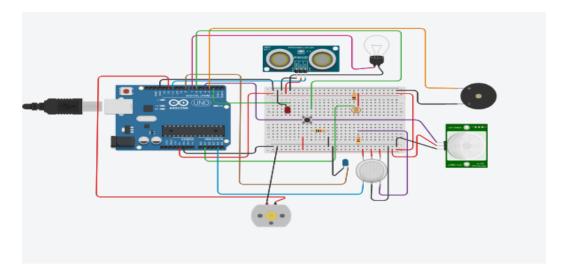
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Link:

 $https://www.tinkercad.com/things/39SEf7Fqr4h-terrific-luulia\%20\%20\%20\%20\%20\%20\%20mur/editel?sharecode=FKQR_ZuHMpvx0HiLrnrJ0Iagb3g2hb1sZ9oTxZPFFAo$

CIRCUIT DIAGRAM:



ARDUINO UNO CODE:

```
const int pingPin = 11;
const int ledUS = 2;
const int led = 7;
const int pirsensor = 4;
#define photoSensor A1
#define sound 3
int const PINO\_SGAS = A4;
int const ledGas = 8;
int const button = 6;
int const motor = 12;
void setup()
 pinMode(ledUS, OUTPUT);
 pinMode(led, OUTPUT);
 pinMode(sound, OUTPUT);
 pinMode(ledGas, OUTPUT);
 pinMode(motor, OUTPUT);
 pinMode(pirsensor, INPUT);
```

```
pinMode(button, INPUT);
 pinMode(photoSensor, INPUT);
 Serial.begin(9600);
void loop()
 long duration, cm;
 int valLight = analogRead(photoSensor);
 int valPIR= digitalRead(pirsensor);
 int valGAS = analogRead(PINO_SGAS);
 valGAS = map(valGAS, 350, 800, 0, 150);
 int valBt = digitalRead(button);
 pinMode(pingPin, OUTPUT);
 digitalWrite(pingPin, LOW);
 delayMicroseconds(4);
 digitalWrite(pingPin, HIGH);
 delayMicroseconds(8);
 digitalWrite(pingPin, LOW);
 pinMode(pingPin, INPUT);
 duration = pulseIn(pingPin, HIGH);
 cm = microsecondsToCentimeters(duration);
 if(cm < 600){
  digitalWrite(ledUS, HIGH);
 }else{
  digitalWrite(ledUS, LOW);
 if(valLight < 700){
```

```
digitalWrite(led, HIGH);
 }else{
  digitalWrite(led, LOW);
 }
 if(valPIR == 1){
  digitalWrite(sound, HIGH);
 }else{
  digitalWrite(sound, LOW);
 }
 if(valBt == 1){
  digitalWrite(motor, HIGH);
 }else{
  digitalWrite(motor, LOW);
 }
 if(valGAS > 20){
  digitalWrite(ledGas, HIGH);
 }else{
  digitalWrite(ledGas, LOW);
 }
 Serial.print(valPIR);
 Serial.println();
}
long microsecondsToCentimeters(long microseconds) {
 return microseconds / 29 / 2;
}
```

OUTPUT:

