

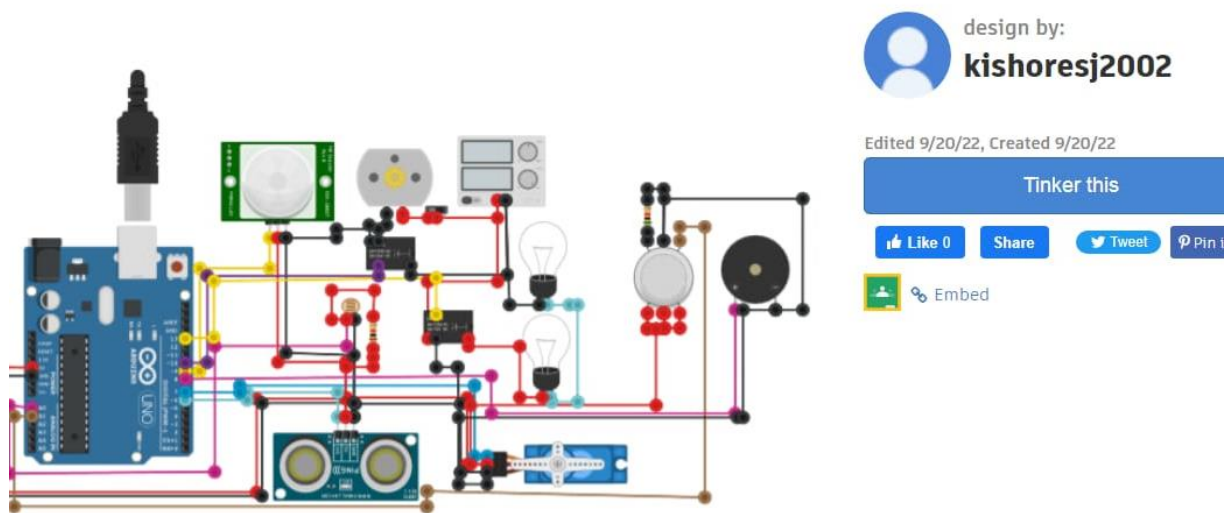
Assignment 1

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Make a home automation with tinkercad, add 2-3 sensors, LED, buzzer and make a common code and alarms should be given.

Ticker Cad link: [Click Here](#)

If does not works use this link: <https://www.tinkercad.com/things/3aSLcv7BBYR>



CODE:

```
#include <Servo.h>
```

```
int output1 Value = 0;
```

```
int sen1Value = 0;
```

```
int sen2Value = 0;
```

```
int const gas_sensor = A1;
```

```
int const LDR = A0;
```

```
int limit = 40
```

```
long readUltrasonicDistance(int triggerPin, int echoPin)
```

```

{
    pinMode(triggerPin, OUTPUT); // Clear the trigger
    digitalWrite(triggerPin, LOW);
    delayMicroseconds(2);
    // Sets the trigger pin to HIGH state for 10 microseconds
    digitalWrite(triggerPin, HIGH);
    delayMicroseconds(10);
    digitalWrite(triggerPin, LOW);
    pinMode(echoPin, INPUT);
    // Reads the echo pin, and returns the sound wave travel time in microseconds
    return pulseIn(echoPin, HIGH);
}

```

```

Servo servo_7;

```

```

void setup()

```

```

{
    Serial.begin(9600);          //initialize serial communication
    pinMode(A0, INPUT);          //LDR
    pinMode(A1, INPUT);          //gas sensor
    pinMode(13, OUTPUT);         //connected to relay
    servo_7.attach(7, 500, 2500); //servo motor

    pinMode(8, OUTPUT);          //signal to piezo buzzer
    pinMode(9, INPUT);           //signal to PIR
    pinMode(10, OUTPUT);         //signal to npn as switch
    pinMode(4, OUTPUT);          //Red LED
    pinMode(3, OUTPUT);          //Green LED

}

```

```

void loop()
{

    //-----light intensity control    //
    //_____
    int val1 = analogRead(LDR);
    if (val1 > 500)
    {
        digitalWrite(13, LOW);
        Serial.print("Bulb ON = ");
        Serial.print(val1);
    }
    else
    {
        digitalWrite(13, HIGH);
        Serial.print("Bulb OFF = ");
        Serial.print(val1);
    }

    //_____

    //----- light & fan control    //
    //_____
    sen2Value = digitalRead(9);
    if (sen2Value == 0)
    {
        digitalWrite(10, LOW); //npn as switch OFF
        digitalWrite(4, HIGH); // Red LED ON, indicating no motion
        digitalWrite(3, LOW); //Green LED OFF, since no Motion detected

        Serial.print("    || NOMotionDetected    ");
    }
}

```

```

    }

    if (sen2Value == 1)
    {
        digitalWrite(10, HIGH); //npn as switch ON
        delay(5000);
        digitalWrite(4, LOW); // RED LED OFF
        digitalWrite(3, HIGH); //GREEN LED ON , indicating motion detected
        Serial.print("      || Motion Detected!    ");
    }

// _____
// ----- Gas Sensor      //
// _____

int val = analogRead(gas_sensor); //read sensor value
Serial.print("|| Gas Sensor Value = ");

Serial.print(val); //Printing in serial monitor

//val = map(val, 300, 750, 0, 100);
if (val > limit)
{
    tone(8, 650);
}
    delay(300);
    noTone(8);

// _____
// ----- servo motor      //
// _____

sen1Value = 0.01723 * readUltrasonicDistance(6, 6);

```

```
if (sen1Value < 100)
{
    servo_7.write(90);
    Serial.print("      || Door Open! ; Distance = ");
    Serial.print(sen1Value);
    Serial.print("\n");

}

else

{
    servo_7.write(0);

    Serial.print("      || Door Closed! ; Distance = ");
    Serial.print(sen1Value);
    Serial.print("\n");
}

delay(10); // Delay a little bit to improve simulation performance
}
```