

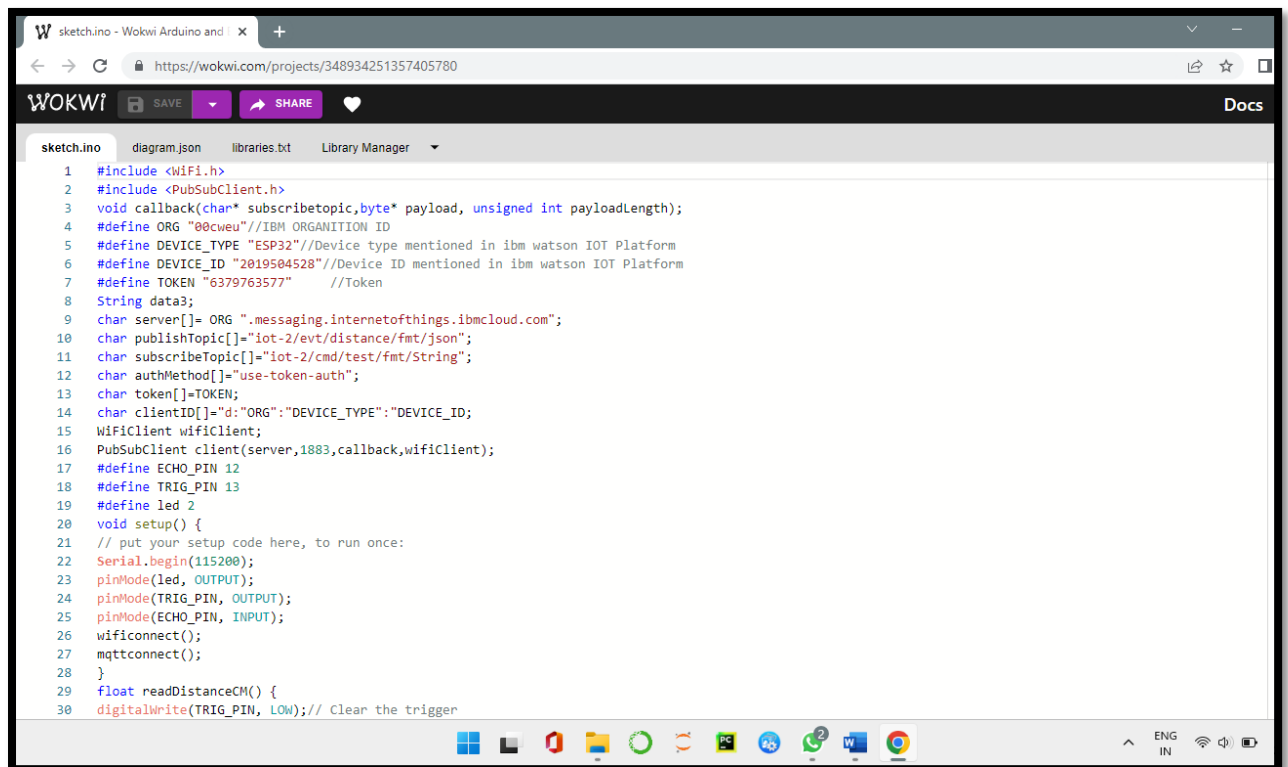
Assignment-4

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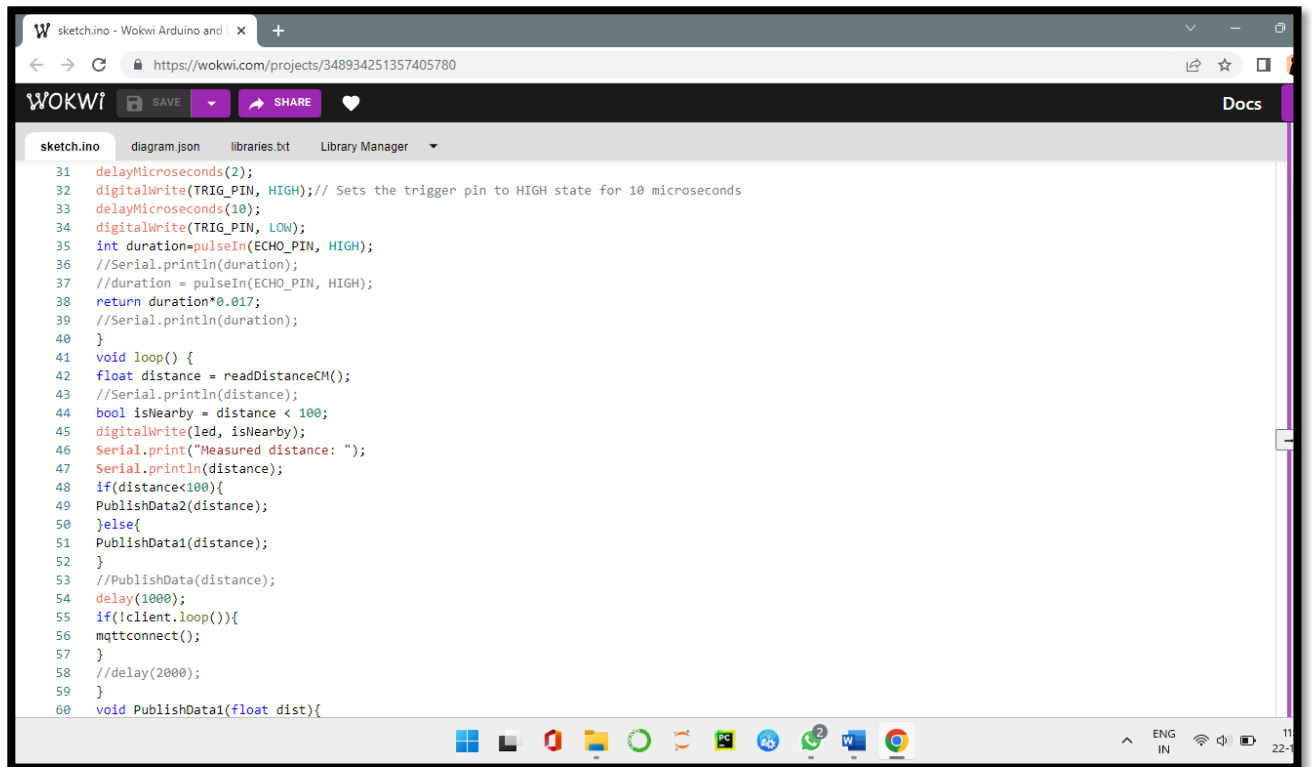
Problem Statement:

Write code and connections in Wokwi for ultrasonic sensor. Whenever distance is less than 100 cm send "alert" to IBM cloud and display in device recent events.

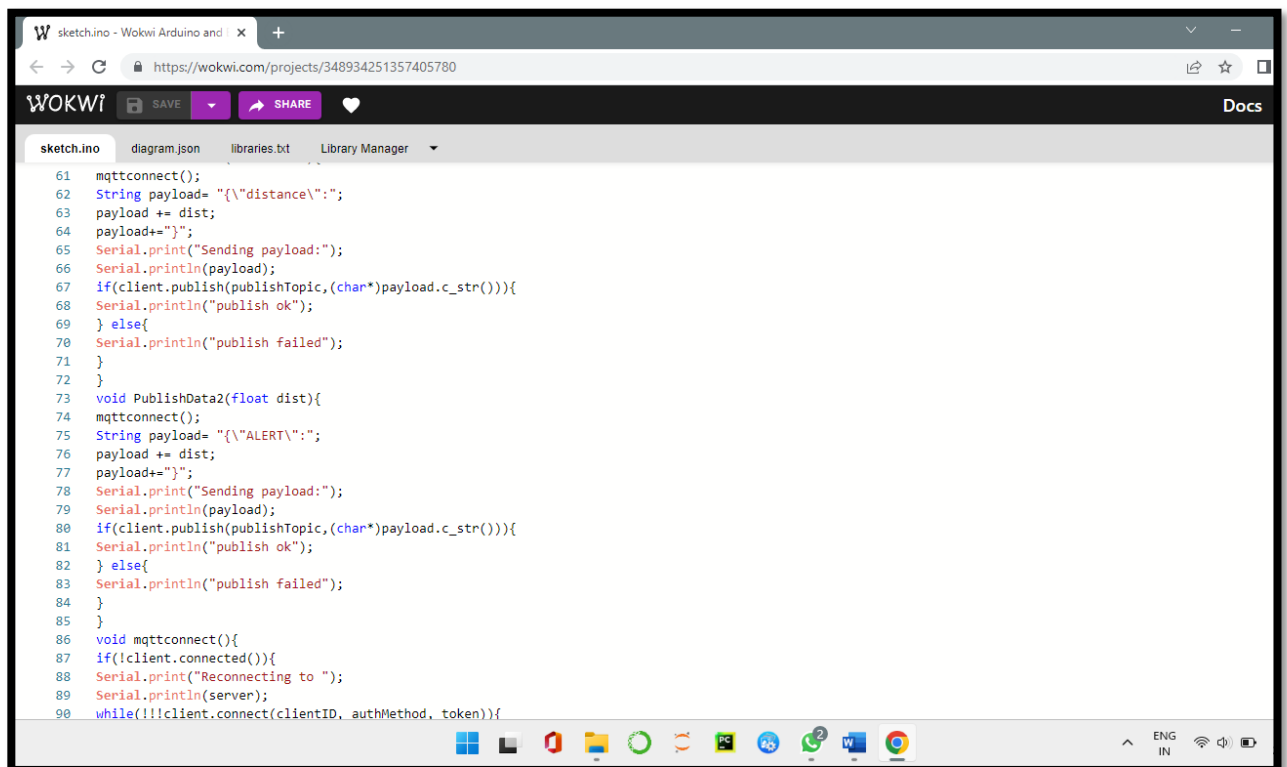
Source Code:



```
1 #include <WiFi.h>
2 #include <PubSubClient.h>
3 void callback(char* topic, byte* payload, unsigned int payloadLength);
4 #define ORG "00cweu"//IBM ORGANITION ID
5 #define DEVICE_TYPE "ESP32"//Device type mentioned in ibm watson IOT Platform
6 #define DEVICE_ID "2019504528"//Device ID mentioned in ibm watson IOT Platform
7 #define TOKEN "6379763577" //Token
8 String data3;
9 char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
10 char publishTopic[] = "iot-2/evt/distance/fmt/json";
11 char subscribeTopic[] = "iot-2/cmd/test/fmt/String";
12 char authMethod[] = "use-token-auth";
13 char token[] = TOKEN;
14 char clientId[] = "d:" + ORG + ":" + DEVICE_TYPE + ":" + DEVICE_ID;
15 WiFiClient wifiClient;
16 PubSubClient client(server, 1883, callback, wifiClient);
17 #define ECHO_PIN 12
18 #define TRIG_PIN 13
19 #define led 2
20 void setup() {
21   // put your setup code here, to run once:
22   Serial.begin(115200);
23   pinMode(led, OUTPUT);
24   pinMode(TRIG_PIN, OUTPUT);
25   pinMode(ECHO_PIN, INPUT);
26   wifiConnect();
27   mqttConnect();
28 }
29 float readDistanceCM() {
30   digitalWrite(TRIG_PIN, LOW); // Clear the trigger
```



```
31 delayMicroseconds(2);
32 digitalWrite(TRIG_PIN, HIGH); // Sets the trigger pin to HIGH state for 10 microseconds
33 delayMicroseconds(10);
34 digitalWrite(TRIG_PIN, LOW);
35 int duration=pulseIn(ECHO_PIN, HIGH);
36 //Serial.println(duration);
37 //duration = pulseIn(ECHO_PIN, HIGH);
38 return duration*0.017;
39 //Serial.println(duration);
40 }
41 void loop() {
42 float distance = readDistanceCM();
43 //Serial.println(distance);
44 bool isNearby = distance < 100;
45 digitalWrite(led, isNearby);
46 Serial.print("Measured distance: ");
47 Serial.println(distance);
48 if(distance<100){
49 PublishData2(distance);
50 }else{
51 PublishData1(distance);
52 }
53 //PublishData(distance);
54 delay(1000);
55 if(!client.loop()){
56 mqttconnect();
57 }
58 //delay(2000);
59 }
60 void PublishData1(float dist){
```



```
61 mqttconnect();
62 String payload= "{\"distance\":";
63 payload += dist;
64 payload+="\"";
65 Serial.print("Sending payload:");
66 Serial.println(payload);
67 if(client.publish(publishTopic,(char*)payload.c_str())){
68 Serial.println("publish ok");
69 } else{
70 Serial.println("publish failed");
71 }
72 }
73 void PublishData2(float dist){
74 mqttconnect();
75 String payload= "{\"ALERT\":";
76 payload += dist;
77 payload+="\"";
78 Serial.print("Sending payload:");
79 Serial.println(payload);
80 if(client.publish(publishTopic,(char*)payload.c_str())){
81 Serial.println("publish ok");
82 } else{
83 Serial.println("publish failed");
84 }
85 }
86 void mqttconnect(){
87 if(!client.connected()){
88 Serial.print("Reconnecting to ");
89 Serial.println(server);
90 while(!client.connect(clientID, authMethod, token)){
```

```
sketch.ino diagram.json libraries.txt Library Manager
91 Serial.print(".");
92 delay(500);
93 }
94 initManagedDevice();
95 Serial.println();
96 }
97 }
98 void wificonnect(){
99 Serial.println();
100 Serial.print("Connecting to");
101 WiFi.begin("Wokwi-GUEST","",6);
102 while(WiFi.status() != WL_CONNECTED){
103 delay(500);
104 Serial.print(".");
105 }
106 Serial.println("");
107 Serial.println("WIFI CONNECTED");
108 Serial.println("IP address:");
109 Serial.println(WiFi.localIP());
110 }
111 void initManagedDevice(){
112 if(client.subscribe(subscribeTopic)){
113 Serial.println(subscribeTopic);
114 Serial.println("subscribe to cmd ok");
115 }else{
116 Serial.println("subscribe to cmd failed");
117 }
118 }
119 void callback(char* subscribeTopic, byte* payload, unsigned int
120 payloadLength){
```

```
121 Serial.print("callback invoked for topic:");
122 Serial.println(subscribeTopic);
123 for(int i=0; i<payloadLength; i++){
124 data3 += (char)payload[i];
125 }
126 Serial.println("data:"+ data3);
127 if(data3=="lighton"){
128 Serial.println(data3);
129 digitalWrite(led,HIGH);
130 }else{
131 Serial.println(data3);
132 digitalWrite(led,LOW);
133 }
134 data3="";
135 }
```

Wokwi Link:

<https://wokwi.com/projects/348934251357405780>

Output:

Normal Case:

WOKWI SAVE SHARE sketch.ino Docs SIGN IN

sketch.ino diagram.json libraries.txt Library Manager

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28 }
29 float readDistanceCM() {
30   digitalWrite(TRIG_PIN, LOW); // Clear the trigger
31   delayMicroseconds(2);
32   digitalWrite(TRIG_PIN, HIGH); // Sets the trigger pin to HIGH state for 10 microseconds
33   delayMicroseconds(10);
34   digitalWrite(TRIG_PIN, LOW);
35   int duration = pulseIn(ECHO_PIN, HIGH);
```

Simulation

publish ok
Measured distance: 399.92
Sending payload:{"distance":399.92}
publish ok
Measured distance: 399.92
Sending payload:{"distance":399.92}
publish ok

Alert Case:

WOKWI SAVE SHARE sketch.ino Docs SIGN UP

sketch.ino diagram.json libraries.txt Library Manager

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35   int duration = pulseIn(ECHO_PIN, HIGH);
```

Simulation

Editing Ultrasonic Distance Sensor
Distance: 17cm

publish ok
Measured distance: 16.98
Sending payload:{"ALERT":16.98}
publish ok
Measured distance: 16.98
Sending payload:{"ALERT":16.98}
publish ok

IBM Cloud Storage:

IBM Watson IoT Platform

2019504528@student.annauniv.edu
ID: 000WBU

Browse Action Device Types Interfaces

Add Device +

Identity Device Information Recent Events State Logs

The recent events listed show the live stream of data that is coming and going from this device.

Event	Value	Format	Last Received
distance	{"ALERT":16.98}	json	a few seconds ago
distance	{"ALERT":16.97}	json	a few seconds ago
distance	{"ALERT":16.98}	json	a few seconds ago
distance	{"ALERT":16.98}	json	a few seconds ago

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