Assignment -4

Distance Detection Using Ultrasonic Sensor

Assignment Date	25 October 2022
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Maximum Marks	2 Marks

Question-1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to IBM cloud and display in device recent events.

CODE:

```
#include <WiFi.h>//library for wifi #include
<PubSubClient.h>//library for MQtt
void callback(char* subscribetopic, byte* payload, unsigned intpayloadLength);
//----credentials of IBM Accounts-----
#define ORG "f59trs"//IBM ORGANITION ID
#define DEVICE TYPE "ultrasonicsensor"//Device type mentioned inibm watson IOT
Platform
#define DEVICE_ID "distancedetection"//Device ID mentioned in ibmwatson IOT
#define TOKEN "AlGMGaaF01nawa1QA3"
String data3;
float dist;
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";//Server Name
char publishTopic[] = "iot-2/evt/Data/fmt/json";// topic name andtype of event perform
and format in which data to be send
char subscribetopic[] = "iot-2/cmd/test/fmt/String";//
emd REPRESENT command type AND COMMAND IS TEST OF FORMAT STRING
char authMethod[] = "use-token-auth";// authentication methodchar token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;//clientid
WiFiClient wifiClient; // creating the instance for wificlient
```

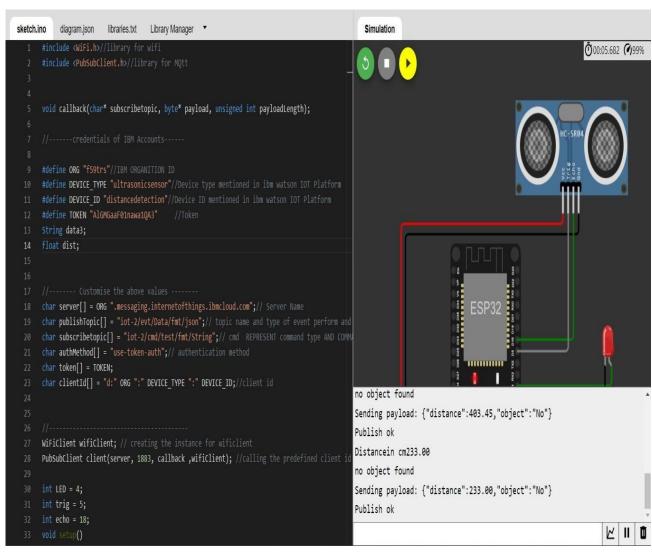
```
if (dist <100)
  { digitalWrite(LED, HIGH);
     Serial.println("object is near"); object =
     "Near";
  { digitalWrite(LED,LOW); Serial.println("no
     object found");object
  String payload = "{\"distance\":"; payload +=
  dist;
  payload += "," "\"object\":\""; payload +=
  object; payload += "\"}";
  Serial.print("Sending payload: ");
  Serial.println(payload);
  if (client.publish(publishTopic, (char*) payload.c_str())) {
     Serial.println("Publish ok");// if it sucessfully upload data on the cloud then it
  } else {
     Serial.println("Publish failed");
void mqttconnect() { if (!client.connected()) {
  Serial.print("Reconnecting client to ");
  Serial.println(server);
     while (!!!client.connect(clientId, authMethod, token)) {
        Serial.print("."); delay(500);
       initManagedDevice();
      Serial.println();
  String object;
```

```
// digitalWrite(LED,LOW);

// }
data3="";
}
```

```
void wificonnect() //function defination for wificonnect
  Serial.print(n); Serial.print("Connecting to
  WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the
connection while (WiFi.status() != WL_CONNECTED) { delay(500);
     Serial.print(".");
  Serial.println(""); Serial.println("WiFi
  connected");Serial .println("IP address: ");
  Serial.println(WiFi.localIP());
void initManagedDevice() { if (client.subscribe(subscribetopic)) {
  Serial.println((subscribetopic)); Serial.println("subscribe to cmd
  OK");
  } else {
     Serial.println("subscribe to cmd FAILED");
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
  Serial.print("callback invoked for topic: ");
  Serial.println(subscribetopic);
  for (int i = 0; i < payloadLength; i++) {
     //Serial.print((char)payload[i]); data3 +=
     (char)payload[i];
 digitalWrite(LED,HIGH);
```

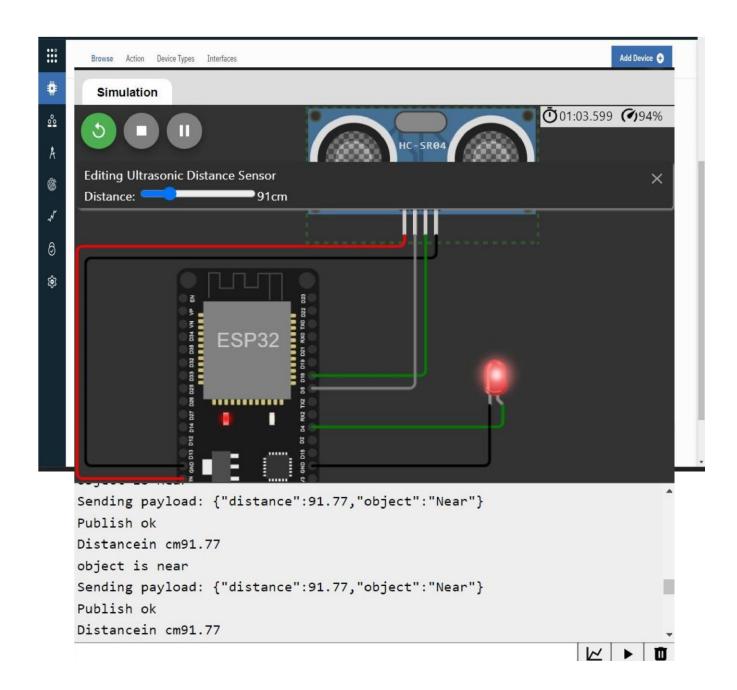
OUTPUT: When object is not near to the ultrasonic



sensor

Data sent to the IBM cloud device when the object is far

When object is nearer to the ultrasonic sensor Data sent



to the IBM cloud device when the object is near

