

Assignment - 4

Assignment Date	02 November 2022
Student Name	Ms.Y.Safreen Banu
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Maximum Marks	2 marks

Question -1:

Write code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100cms send an "alert" to the IBM cloud and display in the device recent events. Upload document with wokwi share link and images of IBM cloud.

Wowki Link:

<https://wokwi.com/projects/347392537590235730>

Code:

```
1  #include <WiFi.h>
2  #include <PubSubClient.h>
3  WiFiClient wifiClient;
4  String data3;
5  #define ORG "yet4pm"
6  #define DEVICE_TYPE "Assignment4"
7  #define DEVICE_ID "12345"
8  #define TOKEN "12345678"
9  #define speed 0.034
10 #define led 14
11 char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
12 char publishTopic[] = "iot-2/evt/data/fmt/json";
13 char topic[] = "iot-2/cmd/home/fmt/String";
14 char authMethod[] = "use-token-auth";
15 char token[] = TOKEN;
16 char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
17 PubSubClient client(server, 1883, wifiClient);
18 void publishData();
19 const int trigpin = 5;
20 const int echopin = 18;
21 String command;
22 String data = "";
23 long duration;
24 float dist;
25 void setup()
```

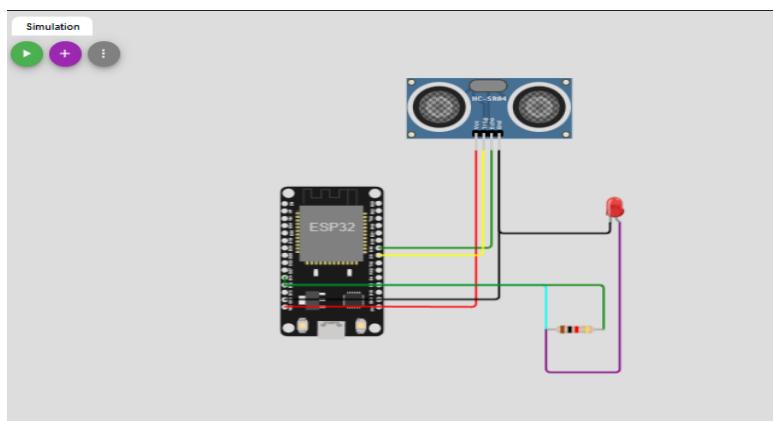
```
26 {
27   Serial.begin(115200);
28   pinMode(led, OUTPUT);
29   pinMode(trigpin, OUTPUT);
30   pinMode(echopin, INPUT);
31   wifiConnect();
32   mqttConnect();
33 }
34 void loop() {
35   bool isNearby = dist < 100;
36   digitalWrite(led, isNearby);
37   publishData();
38   delay(500);
39   if (!client.loop()) {
40     mqttConnect();
41   }
42   void wifiConnect() {
43     Serial.print("Connecting to "); Serial.print("Wifi");
44     WiFi.begin("Wokwi-GUEST", "", 6);
45     while (WiFi.status() != WL_CONNECTED) {
46       delay(500);
47       Serial.print(".");
48     }
49     Serial.print("WiFi connected, IP address: ");
50     Serial.println(WiFi.localIP());
51   }
52   void mqttConnect() {
53     if (!client.connected()) {
54       Serial.print("Reconnecting MQTT client to "); Serial.println(server);
55       while (!client.connect(clientId, authMethod, token)) {
56         Serial.print(".");
57         delay(500);
58       }
59       initManagedDevice();
60       Serial.println();
61     }
62     void initManagedDevice() {
63       if (client.subscribe(topic)) {
64         // Serial.println(client.subscribe(topic));
65         Serial.println("IBM subscribe to cmd OK");
66       } else {
67         Serial.println("subscribe to cmd FAILED");
68       }
69     }
70     void publishData() {
71       digitalWrite(trigpin, LOW);
72       digitalWrite(trigpin, HIGH);
73       delayMicroseconds(10);
74       digitalWrite(trigpin, LOW);
75       duration = pulseIn(echopin, HIGH);
```

```

76  dist = duration * speed / 2;
77  if (dist < 100) {
78      String payload = "{\"Normal Distance\":\"";
79      payload += dist;
80      payload += "\"";
81      Serial.print("\n");
82      Serial.print("Sending payload: ");
83      Serial.println(payload);
84      if (client.publish(publishTopic, (char*) payload.c_str())) {
85          Serial.println("Publish OK");
86      }
87      if (dist > 101 ) {
88          String payload = "{\"Alert distance\":\"";
89          payload += dist;
90          payload += "\"";
91          Serial.print("\n");
92          Serial.print("Sending payload: ");
93          Serial.println(payload);
94          if (client.publish(publishTopic, (char*) payload.c_str())) {
95              Serial.println("Warning crosses 110cm -- it automatically of the loop");
96              digitalWrite(led, HIGH);
97          } else {
98              Serial.println("Publish FAILED");
99          }
100     }
101 }
102 void callback(char* subscribeTopic, byte* payload, unsigned int payloadLength)
103 {
104     Serial.print("callback invoked for topic:");
105     Serial.println(subscribeTopic);
106     for (int i = 0; i < payloadLength; i++) {
107         dist += (char)payload[i];
108     }
109     Serial.println("data:" + data3);
110     if (data3 == "lighton") {
111         Serial.println(data3);
112         digitalWrite(led, HIGH);
113     }
114     data3 = "";
115 }

```

Circuit Diagram:



Output:

```
1 #include <WiFi.h>
2 #include <PubSubClient.h>
3 WiFiClient wifiClient;
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5 #define ORG "yet4pm"
6 #define DEVICE_TYPE "Assignment4"
7 #define DEVICE_ID "12345"
8 #define TOKEN "12345678"
9 #define speed 0.034
10 #define led 14
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17 PubSubClient client(server, 1883, wifiClient);
18 void publishData();
19 const int trigpin = 5;
20 const int echopin = 18;
21 String command;
22 String data = "";
23 long duration;
24 float dist;
25 void setup()
26 {
27   Serial.begin(115200);
28   pinMode(led, OUTPUT);

```

Simulation

Editing Ultrasonic Distance Sensor
Distance: 73cm

Sending payload: {"Normal Distance":93.96}
Publish OK

Sending payload: {"Normal Distance":72.96}
Publish OK

Sending payload: {"Normal Distance":72.96}

IBM Watson IoT Platform

821919104023@smartinternz.com
ID: yet4pm

Browse Action Device Types Interfaces

12345 Connected Assignment4 Device Nov 7, 2022 9:00 PM

Identity Device Information Recent Events State Logs

The recent events listed show the live stream of data that is coming and going from this device.

Event	Value	Format	Last Received
data	{"Normal Distance":72.96}	json	a few seconds ago
data	{"Normal Distance":72.96}	json	a few seconds ago
data	{"Normal Distance":93.96}	json	a few seconds ago
data	{"Normal Distance":44.97}	json	a few seconds ago