# **Assignment-4**

Assignment Date	29 October 2022
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Maximum Marks	2 Marks

### **Question:**

Write code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100 cms send an "alert" to the IBM cloud and display in the device recent events. Upload document with wokwi share link and images of IBM cloud.

## Wokwi Link:

https://wokwi.com/projects/347777130081288786

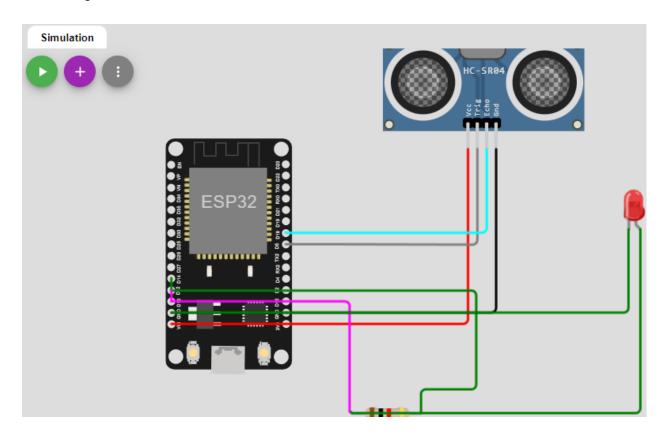
## Code:

```
#include <WiFi.h>
 1
   #include <PubSubClient.h>
 2
     WiFiClient wifiClient;
     String data3;
4
     #define ORG "05wk10"
 5
     #define DEVICE_TYPE "Assignment_4"
     #define DEVICE ID "1234"
7
     #define TOKEN "123456789"
8
     #define speed 0.034
10
     #define led 14
     char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
11
     char publishTopic[] = "iot-2/evt/data/fmt/json";
12
     char topic[] = "iot-2/cmd/home/fmt/String";
13
14
     char authMethod[] = "use-token-auth";
     char token[] = TOKEN;
15
     char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
16
     PubSubClient client(server, 1883, wifiClient);
17
     void publishData();
18
     const int trigpin = 5;
19
     const int echopin = 18;
20
21
     String command;
     String data = "";
22
```

```
23
     long duration;
24
     float dist;
25
     void setup()
26
27
     Serial.begin(115200);
28
     pinMode(led, OUTPUT);
29
     pinMode(trigpin, OUTPUT);
     pinMode(echopin, INPUT);
30
31
     wifiConnect();
32
     mqttConnect();
33
     }
34
     void loop() {
     bool isNearby = dist < 100;</pre>
35
     digitalWrite(led, isNearby);
36
     publishData();
37
     delay(500);
38
     if (!client.loop()) {
39
     mqttConnect();
40
     }
41
42
43
     void wifiConnect() {
     Serial.print("Connecting to "); Serial.print("Wifi");
44
     WiFi.begin("Wokwi-GUEST", "", 6);
45
46
     while (WiFi.status() != WL_CONNECTED) {
     delay(500);
47
     Serial.print(".");
48
49
     }
     Serial.print("WiFi connected, IP address: ");
50
     Serial.println(WiFi.localIP());
51
52
     }
     void mqttConnect() {
53
     if (!client.connected()) {
54
     Serial.print("Reconnecting MQTT client to "); Serial.println(server);
55
     while (!client.connect(clientId, authMethod, token)) {
56
     Serial.print(".");
57
58
     delay(500);
59
     }
60
     initManagedDevice();
61
     Serial.println();
62
     }
63
     void initManagedDevice() {
64
65
     if (client.subscribe(topic)) {
66
     // Serial.println(client.subscribe(topic));
```

```
67
       Serial.println("IBM subscribe to cmd OK");
 68
       } else {
       Serial.println("subscribe to cmd FAILED");
 69
 70
 71
       }
 72
      void publishData()
 73
 74
      digitalWrite(trigpin, LOW);
      digitalWrite(trigpin, HIGH);
 75
 76
       delayMicroseconds(10);
       digitalWrite(trigpin, LOW);
 77
 78
       duration = pulseIn(echopin, HIGH);
 79
       dist = duration * speed / 2;
       if (dist < 100) {
 80
       String payload = "{\"Normal Distance\":";
 81
 82
       payload += dist;
       payload += "}";
 83
       Serial.print("\n");
 84
       Serial.print("Sending payload: ");
 85
       Serial.println(payload);
 86
       if (client.publish(publishTopic, (char*) payload.c str())) {
 87
 88
       Serial.println("Publish OK");
 89
 90
91
      if (dist > 101 ) {
      String payload = "{\"Alert distance\":";
92
93
      payload += dist;
      payload += "}";
94
95
      Serial.print("\n");
96
      Serial.print("Sending payload: ");
      Serial.println(payload);
97
      if (client.publish(publishTopic, (char*) payload.c str())) {
98
99
      Serial.println("Warning crosses 110cm -- it automaticaly of the loop");
      digitalWrite(led, HIGH);
100
      } else {
101
      Serial.println("Publish FAILED");
102
103
      }
104
      }
105
      void callback(char* subscribeTopic, byte* payload, unsigned int payloadLengt
106
107
108
      Serial.print("callback invoked for topic:");
      Serial.println(subscribeTopic);
109
      for (int i = 0; i < payloadLength; i++) {</pre>
110
```

# **Circuit Diagram:**



# **Output:**

