Import and unzip the dataset

```
Team ID: PNT2022TMID09950
```

```
from google.colab import drive
drive.mount('/content/drive')
     Mounted at /content/drive
#unzip the downloaded dataset
!unzip '/content/drive/MyDrive/damage vehicle.zip'
     Archive: /content/drive/MyDrive/damage vehicle.zip
        creating: damage vehicle/
        creating: damage vehicle/body/
        creating: damage vehicle/body/training/
        creating: damage vehicle/body/training/00-front/
       inflating: damage vehicle/body/training/00-front/0001.jpeg
       inflating: damage vehicle/body/training/00-front/0002.JPEG
       inflating: damage vehicle/body/training/00-front/0003.JPEG
       inflating: damage vehicle/body/training/00-front/0004.JPEG
       inflating: damage vehicle/body/training/00-front/0005.JPEG
       inflating: damage vehicle/body/training/00-front/0006.JPEG
       inflating: damage vehicle/body/training/00-front/0007.JPEG
       inflating: damage vehicle/body/training/00-front/0008.jpeg
       inflating: damage vehicle/body/training/00-front/0009.JPEG
       inflating: damage vehicle/body/training/00-front/0010.JPEG
       inflating: damage vehicle/body/training/00-front/0011.JPEG
       inflating: damage vehicle/body/training/00-front/0012.jpeg
       inflating: damage vehicle/body/training/00-front/0013.JPEG
       inflating: damage vehicle/body/training/00-front/0014.JPEG
       inflating: damage vehicle/body/training/00-front/0015.JPEG
       inflating: damage vehicle/body/training/00-front/0016.JPEG
       inflating: damage vehicle/body/training/00-front/0017.JPEG
       inflating: damage vehicle/body/training/00-front/0018.JPEG
       inflating: damage vehicle/body/training/00-front/0019.JPEG
       inflating: damage vehicle/body/training/00-front/0020.jpeg
       inflating: damage vehicle/body/training/00-front/0021.JPEG
       inflating: damage vehicle/body/training/00-front/0022.JPEG
       inflating: damage vehicle/body/training/00-front/0023.JPEG
       inflating: damage vehicle/body/training/00-front/0024.JPEG
       inflating: damage vehicle/body/training/00-front/0025.jpeg
       inflating: damage vehicle/body/training/00-front/0026.JPEG
       inflating: damage vehicle/body/training/00-front/0027.JPEG
       inflating: damage vehicle/body/training/00-front/0028.JPEG
       inflating: damage vehicle/body/training/00-front/0029.JPEG
       inflating: damage vehicle/body/training/00-front/0030.JPEG
       inflating: damage vehicle/body/training/00-front/0031.JPEG
       inflating: damage vehicle/body/training/00-front/0032.JPEG
       inflating: damage vehicle/body/training/00-front/0033.JPEG
       inflating: damage vehicle/body/training/00-front/0034.JPEG
       inflating: damage vehicle/body/training/00-front/0035.jpeg
       inflating: damage vehicle/body/training/00-front/0036.JPEG
       inflating: damage vehicle/body/training/00-front/0037.JPEG
       inflating: damage vehicle/body/training/00-front/0038.JPEG
       inflating: damage vehicle/body/training/00-front/0039.JPEG
       inflating: damage vehicle/body/training/00-front/0040.JPEG
       inflating: damage vehicle/body/training/00-front/0041.JPEG
       inflating: damage vehicle/body/training/00-front/0042.JPEG
       inflating: damage vehicle/body/training/00-front/0043.JPEG
       inflating: damage vehicle/body/training/00-front/0044.JPEG
       inflating: damage vehicle/body/training/00-front/0045.JPEG
       inflating: damage vehicle/body/training/00-front/0046.jpeg
       inflating: damage vehicle/body/training/00-front/0047.JPEG
       inflating: damage vehicle/body/training/00-front/0048.JPEG
       inflating: damage vehicle/body/training/00-front/0049.JPEG
       inflating: damage vehicle/body/training/00-front/0050.JPEG
       inflating: damage vehicle/body/training/00-front/0051.JPEG
       inflating: damage vehicle/body/training/00-front/0052.JPEG
       inflating: damage vehicle/body/training/00-front/0053.JPEG
```

Image Preprocessing

1. Import The ImageDataGenerator Library

```
# Import required lib
```

from tensorflow.keras.preprocessing.image import ImageDataGenerator

2. Configure ImageDataGenerator Class

3. Apply ImageDataGenerator Functionality To Trainset And Testset

Found 979 images belonging to 3 classes.

test_datagen = ImageDataGenerator(rescale=1./255)

Found 171 images belonging to 3 classes.

Found 979 images belonging to 3 classes.

Found 171 images belonging to 3 classes.

Model Building

For Body

1. Importing The Model Building Libraries

```
#Import the library
from tensorflow.keras.layers import Dense, Flatten, Input
from tensorflow.keras.models import Model
from tensorflow.keras.preprocessing import image
from tensorflow.keras.preprocessing.image import ImageDataGenerator, load_img
from tensorflow.keras.applications.vgg16 import VGG16, preprocess_input
from glob import glob
```

```
import numpy as np
import tensorflow as tf
from tensorflow.keras.layers import Input, Lambda, Dense, Flatten
from tensorflow.keras.models import Model
from tensorflow.keras.applications.vgg16 import VGG16
from tensorflow.keras.applications.vgg19 import VGG19
from tensorflow.keras.preprocessing import image
from tensorflow.keras.preprocessing.image import ImageDataGenerator,load_img
from tensorflow.keras.models import Sequential
import numpy as np
from glob import glob
```

2. Loading The Model

3. Adding Flatten Layer

```
for layer in vgg16.layers:
    layer.trainable = False

folders = glob('/content/damage vehicle/body/training/*')

folders

['/content/damage vehicle/body/training/00-front',
    '/content/damage vehicle/body/training/01-rear',
    '/content/damage vehicle/body/training/02-side']

x = Flatten()(vgg16.output)

len(folders)
3
```

4. Adding Output Layer

```
prediction = Dense(len(folders), activation='softmax')(x)
```

5. Creating A Model Object

```
model = Model(inputs=vgg16.input, outputs=prediction)
```

Model: "model"

model.summary()

| Layer (type) | Output Shape | Param # |
|---------------------------------------|-----------------------|---------|
| input_1 (InputLayer) | [(None, 224, 224, 3)] | 0 |
| block1_conv1 (Conv2D) | (None, 224, 224, 64) | 1792 |
| block1_conv2 (Conv2D) | (None, 224, 224, 64) | 36928 |
| <pre>block1_pool (MaxPooling2D)</pre> | (None, 112, 112, 64) | 0 |
| block2_conv1 (Conv2D) | (None, 112, 112, 128) | 73856 |
| block2_conv2 (Conv2D) | (None, 112, 112, 128) | 147584 |

```
block2_pool (MaxPooling2D) (None, 56, 56, 128)
                           (None, 56, 56, 256)
 block3_conv1 (Conv2D)
                                                    295168
 block3_conv2 (Conv2D)
                           (None, 56, 56, 256)
                                                    590080
 block3_conv3 (Conv2D)
                           (None, 56, 56, 256)
                                                    590080
 block3_pool (MaxPooling2D) (None, 28, 28, 256)
 block4_conv1 (Conv2D)
                           (None, 28, 28, 512)
                                                   1180160
 block4 conv2 (Conv2D)
                           (None, 28, 28, 512)
                                                    2359808
                                                   2359808
 block4 conv3 (Conv2D)
                           (None, 28, 28, 512)
 block4_pool (MaxPooling2D) (None, 14, 14, 512)
 block5_conv1 (Conv2D)
                           (None, 14, 14, 512)
                                                   2359808
 block5_conv2 (Conv2D)
                           (None, 14, 14, 512)
                                                    2359808
 block5_conv3 (Conv2D)
                           (None, 14, 14, 512)
                                                    2359808
 block5_pool (MaxPooling2D) (None, 7, 7, 512)
 flatten (Flatten)
                           (None, 25088)
                                                    0
 dense (Dense)
                                                    75267
                           (None, 3)
______
Total params: 14,789,955
Non-trainable params: 14,714,688
```

Trainable params: 75,267

6. Configure The Learning Process

```
model.compile(
 loss='categorical_crossentropy',
 optimizer='adam',
  metrics=['accuracy']
```

7. Train The Model

```
r = model.fit_generator(
 xtrain,
 validation_data=xtest,
 epochs=25,
 steps_per_epoch=len(xtrain),
 validation steps=len(xtest)
)
```

/usr/local/lib/python3.7/dist-packages/ipykernel_launcher.py:6: UserWarning: `Model.fit_generator` is deprecated and will be Epoch 1/25 98/98 [==============] - 23s 146ms/step - loss: 1.2077 - accuracy: 0.5465 - val_loss: 1.2900 - val_accuracy: Enoch 2/25 98/98 [===============] - 13s 128ms/step - loss: 0.8364 - accuracy: 0.7028 - val_loss: 0.8665 - val_accuracy: Epoch 3/25 98/98 [==============] - 13s 128ms/step - loss: 0.5293 - accuracy: 0.7998 - val_loss: 1.3260 - val_accuracy: Epoch 4/25 Epoch 5/25 98/98 [==============] - 12s 127ms/step - loss: 0.2783 - accuracy: 0.9030 - val_loss: 0.9397 - val_accuracy: Epoch 6/25 Epoch 7/25 98/98 [==============] - 12s 127ms/step - loss: 0.1788 - accuracy: 0.9448 - val_loss: 1.0052 - val_accuracy: Epoch 8/25 98/98 [===============] - 13s 129ms/step - loss: 0.1671 - accuracy: 0.9469 - val_loss: 1.1693 - val_accuracy: Epoch 9/25 98/98 [========: 0.9561 - val_loss: 1.0058 - val_accuracy: 0.9561 - val_loss: 1.0058 - val_accuracy: Epoch 10/25 98/98 [===============] - 13s 128ms/step - loss: 0.1184 - accuracy: 0.9591 - val_loss: 1.0620 - val_accuracy: Epoch 11/25 98/98 [==============] - 13s 130ms/step - loss: 0.0963 - accuracy: 0.9745 - val_loss: 1.1219 - val_accuracy: Epoch 12/25

```
98/98 [==============] - 13s 129ms/step - loss: 0.0857 - accuracy: 0.9765 - val_loss: 1.0284 - val_accuracy:
Epoch 13/25
98/98 [========: 0.9837 - val_loss: 1.1153 - val_accuracy: 0.9837 - val_loss: 1.1153 - val_accuracy:
Epoch 14/25
98/98 [===============] - 13s 129ms/step - loss: 0.0688 - accuracy: 0.9877 - val_loss: 1.1033 - val_accuracy:
Epoch 15/25
98/98 [==============] - 13s 131ms/step - loss: 0.0709 - accuracy: 0.9867 - val_loss: 1.0730 - val_accuracy:
Epoch 16/25
98/98 [==============] - 13s 128ms/step - loss: 0.0895 - accuracy: 0.9775 - val_loss: 1.1225 - val_accuracy:
Epoch 17/25
Epoch 18/25
98/98 [========: 0.9714 - val_loss: 1.1754 - val_accuracy: 0.9714 - val_loss: 1.1754 - val_accuracy:
Epoch 19/25
98/98 [===============] - 13s 128ms/step - loss: 0.0728 - accuracy: 0.9847 - val_loss: 1.5074 - val_accuracy:
Epoch 20/25
98/98 [========:: 0.9714 - val_loss: 1.4684 - val_accuracy:
Epoch 21/25
98/98 [=============] - 13s 131ms/step - loss: 0.0404 - accuracy: 0.9908 - val_loss: 1.4215 - val_accuracy:
Epoch 22/25
98/98 [===============] - 13s 131ms/step - loss: 0.0854 - accuracy: 0.9867 - val_loss: 1.4772 - val_accuracy:
Epoch 23/25
98/98 [===============] - 13s 128ms/step - loss: 0.0399 - accuracy: 0.9918 - val_loss: 1.4306 - val_accuracy:
Fnoch 24/25
98/98 [=============] - 13s 129ms/step - loss: 0.0400 - accuracy: 0.9908 - val_loss: 1.4562 - val_accuracy:
Epoch 25/25
98/98 [==============] - 13s 129ms/step - loss: 0.1692 - accuracy: 0.9387 - val_loss: 1.6805 - val_accuracy:
```

8. Save The Model

```
from tensorflow.keras.models import load_model
model.save('/content/damage vehicle/Model/body.h5')
```

```
9. Test The Model
from tensorflow.keras.models import load model
import cv2
from skimage.transform import resize
model = load_model('/content/damage vehicle/Model/body.h5')
def detect(frame):
 img = cv2.resize(frame,(224,224))
 img = cv2.cvtColor(img,cv2.COLOR_BGR2RGB)
 if(np.max(img)>1):
   img = img/255.0
 img = np.array([img])
 prediction = model.predict(img)
  label = ["front","rear","side"]
 preds = label[np.argmax(prediction)]
 return preds
import numpy as np
data = "/content/damage vehicle/body/training/00-front/0002.JPEG"
image = cv2.imread(data)
print(detect(image))
    1/1 [======] - 0s 148ms/step
```

Model Building

For Level

1. Importing The Model Building Libraries

```
import tensorflow as tf
from tensorflow.keras.layers import Input, Lambda, Dense, Flatten
from tensorflow.keras.models import Model
from tensorflow.keras.applications.vgg16 import VGG16
from tensorflow.keras.applications.vgg19 import VGG19
from tensorflow.keras.preprocessing import image
from tensorflow.keras.preprocessing.image import ImageDataGenerator,load_img
from tensorflow.keras.models import Sequential
import numpy as np
from glob import glob
```

2. Loading The Model

```
IMAGE_SIZE = [224, 224]

train_path = '/content/damage vehicle/level/training'
valid_path = '/content/damage vehicle/level/validation'

vgg16 = VGG16(input_shape=IMAGE_SIZE + [3], weights='imagenet', include_top=False)
```

3. Adding Flatten Layer

```
for layer in vgg16.layers:
    layer.trainable = False

folders = glob('/content/damage vehicle/level/training/*')

folders

['/content/damage vehicle/level/training/03-severe',
    '/content/damage vehicle/level/training/02-moderate',
    '/content/damage vehicle/level/training/01-minor']

x = Flatten()(vgg16.output)

len(folders)

3
```

4. Adding Output Layer

```
prediction = Dense(len(folders), activation='softmax')(x)
```

5. Creating A Model Object

```
model = Model(inputs=vgg16.input, outputs=prediction)
model.summary()
```

Model: "model_1"

| Layer (type) | Output Shape | Param # |
|---------------------------------------|-----------------------|---------|
| input_2 (InputLayer) | [(None, 224, 224, 3)] | 0 |
| block1_conv1 (Conv2D) | (None, 224, 224, 64) | 1792 |
| block1_conv2 (Conv2D) | (None, 224, 224, 64) | 36928 |
| <pre>block1_pool (MaxPooling2D)</pre> | (None, 112, 112, 64) | 0 |
| block2_conv1 (Conv2D) | (None, 112, 112, 128) | 73856 |
| block2_conv2 (Conv2D) | (None, 112, 112, 128) | 147584 |
| <pre>block2_pool (MaxPooling2D)</pre> | (None, 56, 56, 128) | 0 |
| block3_conv1 (Conv2D) | (None, 56, 56, 256) | 295168 |

```
590080
block3_conv2 (Conv2D)
                           (None, 56, 56, 256)
                                                   590080
block3 conv3 (Conv2D)
                           (None, 56, 56, 256)
block3_pool (MaxPooling2D) (None, 28, 28, 256)
block4_conv1 (Conv2D)
                           (None, 28, 28, 512)
                                                   1180160
block4_conv2 (Conv2D)
                           (None, 28, 28, 512)
                                                   2359808
block4_conv3 (Conv2D)
                           (None, 28, 28, 512)
                                                   2359808
block4 pool (MaxPooling2D)
                           (None, 14, 14, 512)
                                                   2359808
block5 conv1 (Conv2D)
                           (None, 14, 14, 512)
block5_conv2 (Conv2D)
                           (None, 14, 14, 512)
                                                   2359808
block5_conv3 (Conv2D)
                           (None, 14, 14, 512)
                                                   2359808
block5_pool (MaxPooling2D) (None, 7, 7, 512)
flatten_1 (Flatten)
                           (None, 25088)
                                                   a
dense_1 (Dense)
                           (None, 3)
                                                   75267
______
Total params: 14,789,955
Trainable params: 75,267
Non-trainable params: 14,714,688
```

6. Configure The Learning Process

```
model.compile(
  loss='categorical_crossentropy',
  optimizer='adam',
  metrics=['accuracy']
)
```

7. Train The Model

x_train,

r = model.fit_generator(

Epoch 12/25

Epoch 13/25

Epoch 14/25

```
validation_data=x_test,
epochs=25,
steps_per_epoch=len(x_train),
validation_steps=len(x_test)
 /usr/local/lib/python3.7/dist-packages/ipykernel_launcher.py:6: UserWarning: `Model.fit_generator` is deprecated and will be
 Epoch 1/25
 Epoch 2/25
 Epoch 3/25
 98/98 [==============] - 13s 130ms/step - loss: 0.4978 - accuracy: 0.8161 - val_loss: 1.5663 - val_accuracy:
 Epoch 4/25
 98/98 [===============] - 13s 128ms/step - loss: 0.5277 - accuracy: 0.7865 - val_loss: 1.6003 - val_accuracy:
 Epoch 5/25
 98/98 [=============] - 13s 128ms/step - loss: 0.3763 - accuracy: 0.8468 - val_loss: 1.1925 - val_accuracy:
 Epoch 6/25
 Epoch 7/25
 98/98 [==============] - 13s 128ms/step - loss: 0.1902 - accuracy: 0.9346 - val_loss: 1.2155 - val_accuracy:
 Epoch 8/25
 Epoch 9/25
 98/98 [============] - 13s 127ms/step - loss: 0.1206 - accuracy: 0.9540 - val loss: 1.1282 - val accuracy:
 Epoch 10/25
 Epoch 11/25
 98/98 [==============] - 13s 128ms/step - loss: 0.0910 - accuracy: 0.9765 - val_loss: 1.1538 - val_accuracy:
```

98/98 [===============] - 12s 127ms/step - loss: 0.0813 - accuracy: 0.9806 - val_loss: 1.2209 - val_accuracy:

98/98 [==============] - 13s 128ms/step - loss: 0.0603 - accuracy: 0.9857 - val_loss: 1.2545 - val_accuracy:

```
98/98 [==============] - 12s 127ms/step - loss: 0.0474 - accuracy: 0.9949 - val_loss: 1.1609 - val_accuracy:
Epoch 15/25
98/98 [===============] - 13s 129ms/step - loss: 0.0366 - accuracy: 0.9959 - val_loss: 1.1688 - val_accuracy:
Epoch 16/25
98/98 [==============] - 13s 128ms/step - loss: 0.0493 - accuracy: 0.9888 - val_loss: 1.1850 - val_accuracy:
Epoch 17/25
98/98 [========: 0.9939 - val_loss: 1.1884 - val_accuracy: 0.9939 - val_loss: 1.1884 - val_accuracy:
Epoch 18/25
98/98 [==============] - 13s 129ms/step - loss: 0.0363 - accuracy: 0.9939 - val_loss: 1.2897 - val_accuracy:
Epoch 19/25
Epoch 20/25
98/98 [========: 0.9980 - val_loss: 1.2801 - val_accuracy: 0.9980 - val_loss: 1.2801 - val_accuracy:
Epoch 21/25
98/98 [========: 0.9959 - val_loss: 1.2366 - val_accuracy: 0.9959 - val_loss: 1.2366 - val_accuracy:
Epoch 22/25
98/98 [========:: 1.2901 - val_accuracy: 1.0000 - val_loss: 1.2901 - val_accuracy:
Epoch 23/25
98/98 [==============] - 13s 130ms/step - loss: 0.0216 - accuracy: 1.0000 - val_loss: 1.2697 - val_accuracy:
Epoch 24/25
98/98 [========: 0.9908 - val_loss: 1.4214 - val_accuracy:
Epoch 25/25
98/98 [==============] - 13s 129ms/step - loss: 0.0380 - accuracy: 0.9939 - val_loss: 1.4219 - val_accuracy:
```

8. Save The Model

```
from tensorflow.keras.models import load_model
model.save('/content/damage vehicle/Model/level.h5')
```

```
9. Test The Model
from tensorflow.keras.models import load model
import cv2
from skimage.transform import resize
model = load_model('/content/damage vehicle/Model/level.h5')
def detect(frame):
  img = cv2.resize(frame,(224,224))
  img = cv2.cvtColor(img,cv2.COLOR_BGR2RGB)
  if(np.max(img)>1):
   img = img/255.0
  img = np.array([img])
  prediction = model.predict(img)
  label = ["minor","moderate","severe"]
  preds = label[np.argmax(prediction)]
  return preds
import numpy as np
data = "/content/damage vehicle/level/validation/01-minor/0005.JPEG"
image = cv2.imread(data)
print(detect(image))
    1/1 [======== ] - 0s 142ms/step
     minor
```

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