PROBLEM STATEMENT:

IoT BASED SMART CROP PROTECTION SYSTEM FOR AGRICULTURE

DOMAIN:

INTERNET OF THINGS

ASSIGNMENT 4:

DISTANCE DETECTION USING ULTRASONIC SENSOR

BY

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QUESTION-1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cmssend "alert" to IBM cloud and display in device recent events.

WOKWI LINK:

https://wokwi.com/projects/348098230227042899

CODE:

```
#include <WiFi.h>
#include <WiFiClient.h>
#include <PubSubClient.h>
const int trigPin = 5;
const int echoPin = 18;
//define sound speed in cm/uS
#define SOUND_SPEED 0.034
#define CM_TO_INCH 0.393701
long duration;
float distanceCm;
float distanceInch;
```

```
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength);
//----credentials of IBM Accounts-----
#define ORG "5aa4nx"//IBM ORGANITION ID
#define DEVICE_TYPE "esp-32device"//Device type mentioned in ibm watson IOT
Platform
#define DEVICE ID "saraswathi"//Device ID mentioned in ibm watson IOT Platform
#define TOKEN "9095077880"
                            //Token
String data3;
//----- Customise the above values ------
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";// Server Name
char publishTopic[] = "iot-2/evt/Data/fmt/json";// topic name and type of event
perform and format in which data to be send
char subscribetopic[] = "iot-2/cmd/test/fmt/String";// cmd REPRESENT command
type AND COMMAND IS TEST OF FORMAT STRING
char authMethod[] = "use-token-auth";// authentication method
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;//client id
WiFiClient wifiClient; // creating the instance for wificlient
PubSubClient client(server, 1883, callback ,wifiClient);
void setup() {
  Serial.begin(115200); // Starts the serial communication
  pinMode(trigPin, OUTPUT); // Sets the trigPin as an Output
  pinMode(echoPin, INPUT); // Sets the echoPin as an Input
  Serial.println();
 wificonnect();
 mqttconnect();
}
void loop() {
 // Clears the trigPin
 digitalWrite(trigPin, LOW);
 delayMicroseconds(2);
 // Sets the trigPin on HIGH state for 10 micro seconds
 digitalWrite(trigPin, HIGH);
  delayMicroseconds(10);
 digitalWrite(trigPin, LOW);
 // Reads the echoPin, returns the sound wave travel time in microseconds
```

```
duration = pulseIn(echoPin, HIGH);
 // Calculate the distance
  distanceCm = duration * SOUND SPEED/2;
 // Convert to inches
  distanceInch = distanceCm * CM TO INCH;
 // Prints the distance in the Serial Monitor
 Serial.print("Distance (cm): ");
 Serial.println(distanceCm);
 Serial.print("Distance (inch): ");
 Serial.println(distanceInch);
 PublishData(distanceCm);
 delay(1000);
  if (!client.loop()) {
   mqttconnect();
  }
}
 void PublishData(float Cm) {
  mqttconnect();//function call for connecting to ibm
  /*
     creating the String in in form JSon to update the data to ibm cloud
  */
  String payload = "{\"Distance (cm)\":";
  payload += Cm;
  payload += "}";
 Serial.print("Sending payload: ");
 Serial.println(payload);
 if (client.publish(publishTopic, (char*) payload.c_str())) {
   Serial.println("Publish ok");// if it sucessfully upload data on the cloud
then it will print publish ok in Serial monitor or else it will print publish
failed
  } else {
   Serial.println("Publish failed");
  }
void mqttconnect() {
```

```
if (!client.connected()) {
    Serial.print("Reconnecting client to ");
    Serial.println(server);
    while (!!!client.connect(clientId, authMethod, token)) {
      Serial.print(".");
      delay(500);
    }
     initManagedDevice();
     Serial.println();
  }
}
void wificonnect() //function defination for wificonnect
  Serial.println();
 Serial.print("Connecting to ");
 WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish
the connection
  while (WiFi.status() != WL_CONNECTED) {
    delay(500);
    Serial.print(".");
  }
  Serial.println("");
  Serial.println("WiFi connected");
 Serial.println("IP address: ");
  Serial.println(WiFi.localIP());
}
void initManagedDevice() {
  if (client.subscribe(subscribetopic)) {
    Serial.println((subscribetopic));
    Serial.println("subscribe to cmd OK");
  } else
    Serial.println("subscribe to cmd FAILED");
  }
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
{
  Serial.print("callback invoked for topic: ");
  Serial.println(subscribetopic);
  for (int i = 0; i < payloadLength; i++) {</pre>
    //Serial.print((char)payload[i]);
```

```
data3 += (char)payload[i];
}
```



