

## **PROBLEM STATEMENT :**

IoT based Smart crop protection system

## **DOMAIN :**

Internet of Things

## **ASSIGNMENT 1:**

Smart home with at least two sensors and led, buzzer in TinkerCad

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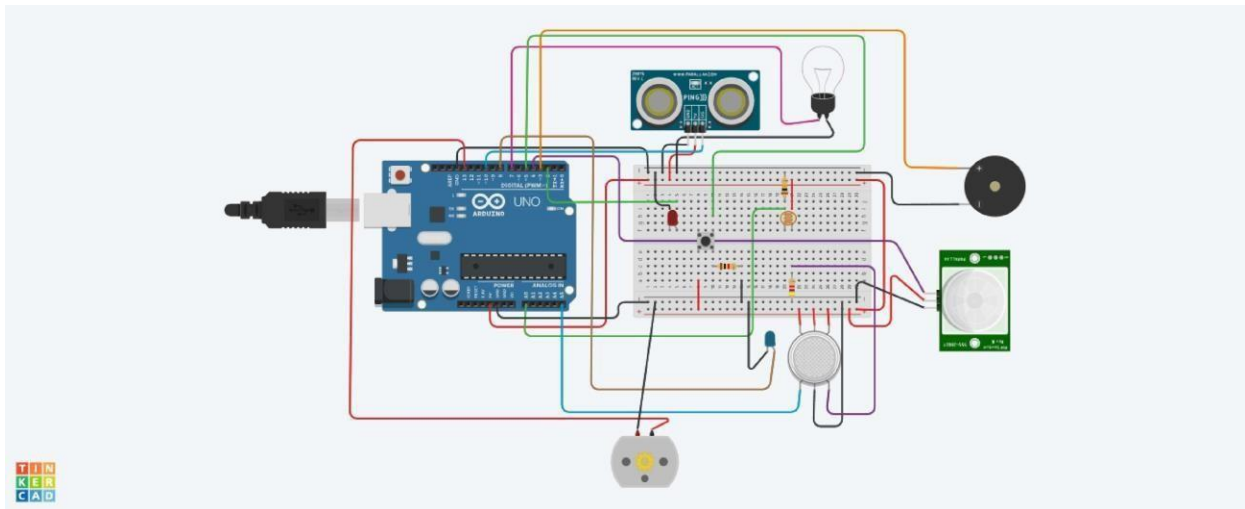
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Link: [https://www.tinkercad.com/things/39SEf7Fqr4h-terrific-luulia-amur/editel?sharecode=FKQR\\_ZuHMPvx0HiLmrJ0Iagb3g2hb1sZ9oTxZPFFAo](https://www.tinkercad.com/things/39SEf7Fqr4h-terrific-luulia-amur/editel?sharecode=FKQR_ZuHMPvx0HiLmrJ0Iagb3g2hb1sZ9oTxZPFFAo)

**CIRCUIT DIAGRAM :**



## ARDUINO UNO CODE:

```
const int pingPin =
```

```
10;    const int IedUS
```

```
= 2; const int light = 7;
```

```
const int pir = 4;
```

```
#define photosensor A0
```

```
#define    buzzer    3
```

```
intconst PINO SGAS =
```

```
A5; int const IedGas =
```

```
8; int const button = 5;
```

```
int const motor =13;
```

```
void setup()
```

```
pinMode(IedUS,
```

```
    OUTPUT);
```

```
pinMode(light,
```

```
    OUTPUT);
```

```
pinMode(buzzer,
```

```
    OUTPUT);
```

```
pinMode(IedGas,
```

```
    OUTPUT);
```

```
pinMode(motor,
OUTPUT); pinMode(pir,
INPUT);
pinMode(button,
INPUT);
pinMode(photoSensor, INPUT);
Serial.begin(9600);
```

```
void loop()
```

```
long duration, cm; int valLight =
analogRead(photoSensor); int valPIR=
digitalRead(pir); intvalIGAS
=analogRead(PIN0 SGAS); valIGAS =
map(valIGAS, 300, 750, 0, 100); int valBt =
digitalRead(button); pinMode(pingPin,
OUTPUT); digitalWrite(pingPin, LOW);
delayMicroseconds(2);
digitalWrite(pingPin, HIGH);
delayMicroseconds(5); digitalWrite(pingPin,
LOW); pinMode(pingPin, INPUT); duration
= pulseIn(pingPin, HIGH); cm =
microsecondsToCentimeters(duration);
if(cm < 336)(
digitalWrite(lcdUS, HIGH);
}else( digitalWrite(lcdUS,
LOW);

if(valLight < 890)(
digitalWrite(light, HIGH);
}else(
```

```
    digitalWrite(light, LOW);  
if(vaIPIR == 1){  
    digitalWrite(buzzer, HIGH);  
}else(  
    digitalWrite(buzzer, LOW);  
if(vaIBt == 1){  
    digitalWrite(motor, HIGH);  
}else(  
    digitalWrite(motor, LOW);  
if(vaIGAS > 20){  
    digitalWrite(IedGas, HIGH);  
}else( digitalWrite(IedGas,  
    LOW);
```

```
Serial.print(vaIPIR);
```

```
Serial.println();
```

```
long microsecondsToCentimeters(long microseconds) (  
    return
```

```
microseconds / 29 / 2;
```