ASSIGNMENT-4 DISTANCE DETECTION USING ULTRASONIC SENSOR

Date	30 October 2022
Team ID	PNT2022TMID508060
Name	ARUMUGA PRIYA.K
Student Roll Number	953419104013
Maximum Marks	2 Marks

Question1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

WOKWI LINK:

https://wokwi.com/projects/305566932847821378

CODE:

```
### stack or described and the state of the
```

```
libraries.bd ●
esp32-blink.ino • diagram.json •
                                                  Library Manager *
       pinMode(trig,OUTPUT);
       pinMode(echo,IMPUT);
       pinMode(LED, OUTPUT);
       delay(10);
       wificonnect();
       mqttconnect();
       void loop()// Recursive Function
        digitalWrite(trig,LOW);
         digitalWrite(trig,HIGH);
         delayMicroseconds(10);
         digitalWrite(trig,LOW);
         float dur = pulseIn(echo,HIGH);
         float dist = (dur * 0.0343)/2;
         Serial.print ("Distancein cm");
         Serial.println(dist);
         PublishData(dist);
         delay(1000);
         if (!client.loop()) {
           mqttconnect();
       void PublishData(float dist) {
         mqttconnect();//function call for connecting to ibm
```

```
creating the String in in form JSon to update the data to ibm cloud

"/"

String object;

if (dist <100)

{

digitalharite(LED,HIGH);

Serial.println("object is near");

object = "Near";

}

else

{

digitalharite(LED,LOW);

Serial.println("no object found");

object = "No";

}

String payload = "\"distance\";

payload += dist;

payload += "," "\"object\":\"";

payload += object;

payload += "\");

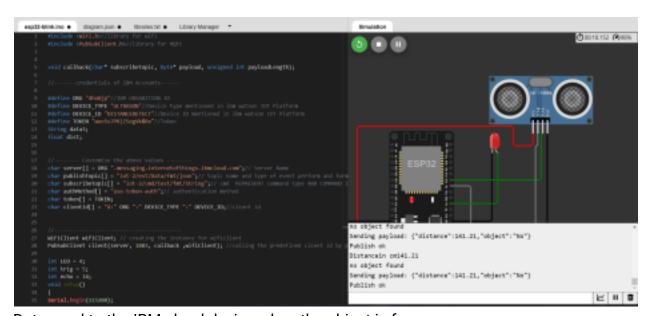
Serial.print("Sending payload: ");

Serial.println(payload);
```

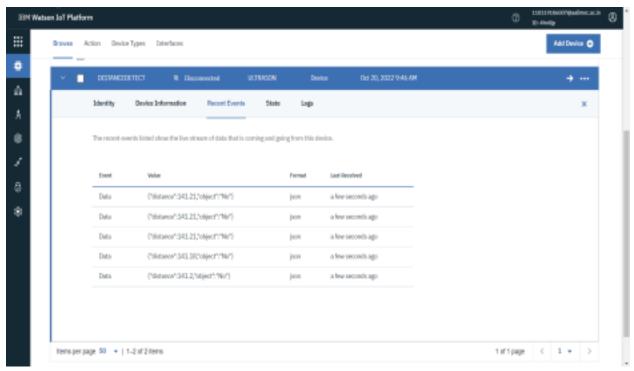
```
esp32-blink.ino •
                   diagram.json •
                                     libraries.bt •
                                                    Library Manager
          WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
while (WiFi.status() != WL_CONNECTED) {
            delay(500);
          Serial.println("");
          Serial.println("WiFi connected");
          Serial.println("IP address: ");
          Serial.println(WiFi.localIP());
        void initManagedDevice() {
          if (client.subscribe(subscribetopic)) {
            Serial.println((subscribetopic));
            Serial.println("subscribe to cmd OK");
            Serial.println("subscribe to cmd FAILED");
        void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
          Serial.println(subscribetopic);
 148
          for (int i = 0; i < payloadLength; i++) {
            data3 += (char)payload[i];
```

```
degramjson • libraries.bt • Library Manager • libraries.bt • libraries.bt • library Manager • libraries.bt • li
```

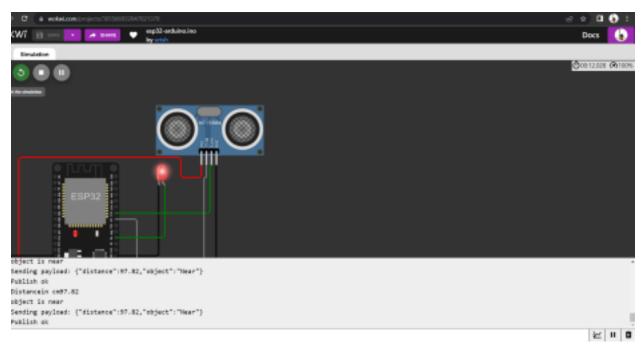
OUTPUT:



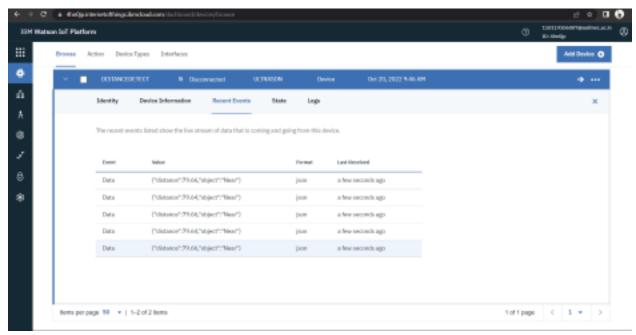
Data send to the IBM cloud device when the object is far



when object is near to the ultrasonic sensor



Data sent to the IBM Cloud Device when the object is near



https://wokwi.com/projects/305566932847821378