PROBLEM STATEMENT:

IOT BASED - REAL TIME RIVER WATER QUALITY MONITORING AND CONTROL SYSTEM

DOMAIN:

INTERNET OF THINGS

ASSIGNMENT 4:

DISTANCE DETECTION USING ULTRASONIC SENSOR

 \mathbf{BY}

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QUESTION-1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cmssend "alert" to IBM cloud and display in device recent events.

WOKWI LINK:

https://wokwi.com/projects/347923162518782547

```
WiFiClient wifiClient;
String data3;
#define ORG "ttkiqy"
#define DEVICE TYPE "Esp-32"
#define DEVICE_ID "keerthi"
#define TOKEN "8870489279"
#define speed 0.034
#define led 14
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/manimd/fmt/json";
char topic[] = "iot-2/cmd/led/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE TYPE ":" DEVICE ID;
PubSubClient client(server, 1883, wifiClient);
const int trigpin=5;
const int echopin=18;
String command;
String data="";
long duration;
float dist;
void setup()
{
  Serial.begin(115200);
  pinMode(led, OUTPUT);
  pinMode(trigpin, OUTPUT);
  pinMode(echopin, INPUT);
  wifiConnect();
  mqttConnect();
}
void loop() {
  bool isNearby = dist < 100;</pre>
  digitalWrite(led, isNearby);
  publishData();
  delay(500);
```

```
if (!client.loop()) {
    mqttConnect();
  }
}
void wifiConnect() {
  Serial.print("Connecting to "); Serial.print("Wifi");
 WiFi.begin("Wokwi-GUEST", "", 6);
 while (WiFi.status() != WL CONNECTED) {
    delay(500);
   Serial.print(".");
  }
 Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
}
void mqttConnect() {
  if (!client.connected()) {
    Serial.print("Reconnecting MQTT client to "); Serial.println(server);
    while (!client.connect(clientId, authMethod, token)) {
      Serial.print(".");
      delay(500);
    initManagedDevice();
    Serial.println();
  }
}
void initManagedDevice() {
  if (client.subscribe(topic)) {
   // Serial.println(client.subscribe(topic));
    Serial.println("IBM subscribe to cmd OK");
  } else {
    Serial.println("subscribe to cmd FAILED");
  }
void publishData()
{
  digitalWrite(trigpin,LOW);
  digitalWrite(trigpin, HIGH);
  delayMicroseconds(10);
  digitalWrite(trigpin,LOW);
  duration=pulseIn(echopin,HIGH);
  dist=duration*speed/2;
  if(dist<100){</pre>
    String payload = "{\"Alert Distance\":";
```

```
payload += dist;
 payload += "}";
 Serial.print("\n");
 Serial.print("Sending payload: ");
 Serial.println(payload);
 if (client.publish(publishTopic, (char*) payload.c_str())) {
   Serial.println("Publish OK");
 }
}
 if(dist>100){
 String payload = "{\"Distance\":";
 payload += dist;
 payload += "}";
 Serial.print("\n");
 Serial.print("Sending payload: ");
 Serial.println(payload);
  if(client.publish(publishTopic, (char*) payload.c_str())) {
   Serial.println("Publish OK");
 }else {
   Serial.println("Publish FAILED");
 }
}
}
```



