

## Problem Statement

# REAL - TIME RIVER WATER QUALITY MONITORING AND CONTROL SYSTEM

Domain :

## Internet of Things

### Assignment 1:

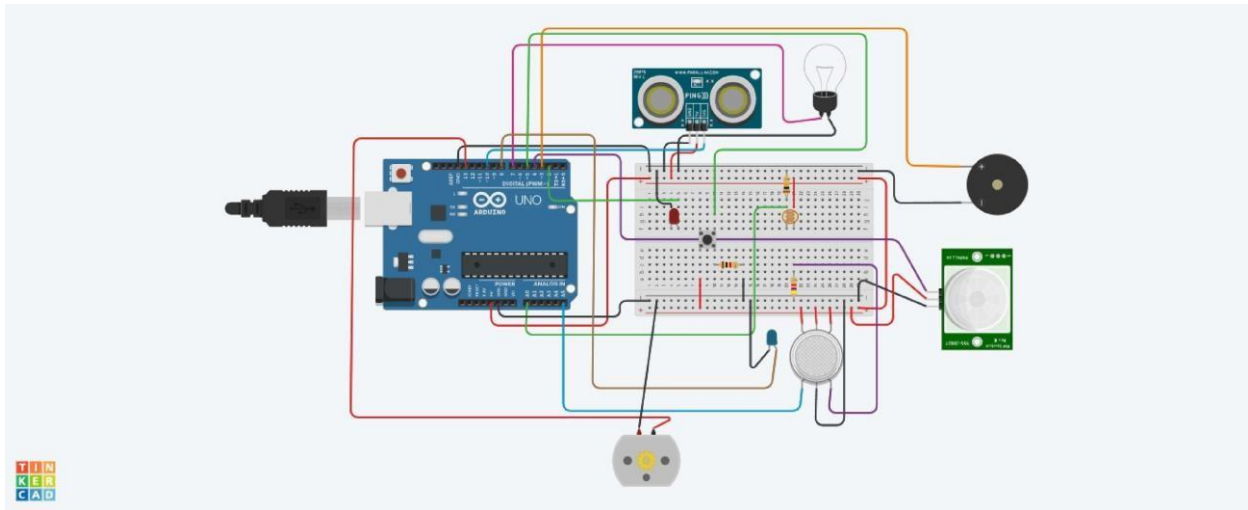
A Smart home in tinkercad with two sensors , an led and  
buzzer

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Link: [https://www.tinkercad.com/things/39SEf7Fqr4h-terrific-luulia-amur/editel?sharecode=FKQR\\_ZuHMPvx0HiLnrJ0Iagb3g2hb1sZ9oTxZPFFAo](https://www.tinkercad.com/things/39SEf7Fqr4h-terrific-luulia-amur/editel?sharecode=FKQR_ZuHMPvx0HiLnrJ0Iagb3g2hb1sZ9oTxZPFFAo)

## Circuit diagram



## Arduino Uno Code:

```
const int pingPin = 10;
const int ledUS = 2;
const int light = 7;
const int pir = 4;
#define photosensor
A0 #define buzzer 3 int
const PINO SGAS =
A5; int const ledGas =
8; int const button = 5;
int const motor = 13;
void setup()

pinMode(ledUS,
  OUTPUT); pinMode(light,
  OUTPUT);
pinMode(buzzer,
  OUTPUT);
pinMode(ledGas,
  OUTPUT);
```

```
pinMode(motor,
OUTPUT); pinMode(pir,
INPUT); pinMode(button,
INPUT);
pinMode(photoSensor,
INPUT);
Serial.begin(9600);
```

```
void loop()
```

```
long duration, cm; int valLight =
analogRead(photoSensor); int valPIR=
digitalRead(pir); int valGAS =
analogRead(PIN0 SGAS); valGAS =
map(valGAS, 300, 750, 0, 100); int valBt =
digitalRead(button); pinMode(pingPin,
OUTPUT); digitalWrite(pingPin, LOW);
delayMicroseconds(2); digitalWrite(pingPin,
HIGH); delayMicroseconds(5);
digitalWrite(pingPin, LOW); pinMode(pingPin,
INPUT); duration = pulseIn(pingPin, HIGH);
cm = microsecondsToCentimeters(duration);
if(cm < 336)(
digitalWrite(ledUS, HIGH);
}else( digitalWrite(ledUS,
LOW);
if(valLight < 890)(
digitalWrite(light, HIGH);
}else(
digitalWrite(light, LOW);
if(valPIR == 1)(
digitalWrite(buzzer, HIGH);
```

```
}else(  
    digitalWrite(buzzer, LOW);  
if(valBt == 1)(  
    digitalWrite(motor, HIGH);  
}else(  
    digitalWrite(motor, LOW);  
if(valGAS > 20)(  
    digitalWrite(ledGas, HIGH);  
}else(  
    digitalWrite(ledGas, LOW);
```

```
Serial.print(valPIR);
```

```
Serial.println();
```

```
long microsecondsToCentimeters(long microseconds) {
```

```
    return microseconds / 29 / 2;
```