## ASSIGNMENT - 4 DISTANCE DETECTION USING ULTRASONIC SENSOR

Date	10 NOVEMBER 2022
Team ID	PNT2022TMID47589
Name	N.Swetha
Register Number	911019104028
Maximum Marks	2 Marks

## **CODE:**

```
#include apubsubclient.hb//library for NQt

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subscribetopic, byte* payload, unsigned int payloadLength);

adding one of the payload of the pay
```

```
pinMode(trig,OUTPUT);
pinMode(echo,INPUT);
pinMode(LED, OUTPUT);
delay(10);
wificonnect();
mqttconnect();
void loop()// Recursive Function
 digitalWrite(trig,LOW);
  digitalWrite(trig,HIGH);
  delayMicroseconds(10);
  digitalWrite(trig,LOW);
  float dur = pulseIn(echo,HIGH);
  float dist = (dur * 0.0343)/2;
  Serial.print ("Distancein cm");
  Serial.println(dist);
  PublishData(dist);
  delay(1000);
  if (!client.loop()) {
    mqttconnect();
void PublishData(float dist) {
  mqttconnect();//function call for connecting to ibm
```

```
creating the String in in form JSon to update the data to ibm cloud

//
String object;
if (dist <100)
{
    digitalWrite(LED,HJGH);
    Serial.println("object is near");
    object = "Near";
}
else
{
    digitalWrite(LED,LOW);
    Serial.println("no object found");
    object = "No";
}

String payload = "{\"distance\":";
    payload += dist;
    payload += "," "\"object\":\"";
    payload += object;
    payload += "\"";

Serial.print("Sending payload: ");
    Serial.println(payload);
</pre>
```

```
if (client.publish(publishTopic, (char*) payload.c.str())) {
    serial.println("Publish ok");// if it successfully upload data on the cloud then it will print publish ok in Serial monitor or else it will print publish failed");
} else {
    serial.println("Publish failed");
}

void myttconnect() {
    if (!client.connected()) {
        serial.print("Reconnecting client to ");
        serial.print("Reconnecting client to ");
        serial.print(");
    delay(500);
}

initManagedDevice();
    serial.println();
}

void wificonnect() //function defination for wificonnect

serial.println();

serial.println();

serial.println();

serial.println();

serial.println();

serial.println(");

serial.print("");

serial.println("");

serial.
```

## **OUTPUT:**









