TEAM ID	PNT2022TMID47365
PROJECT	Smart Waste Management System For
	Metropolitan Cities

SPRINT DELIVERY 2:

Python script:

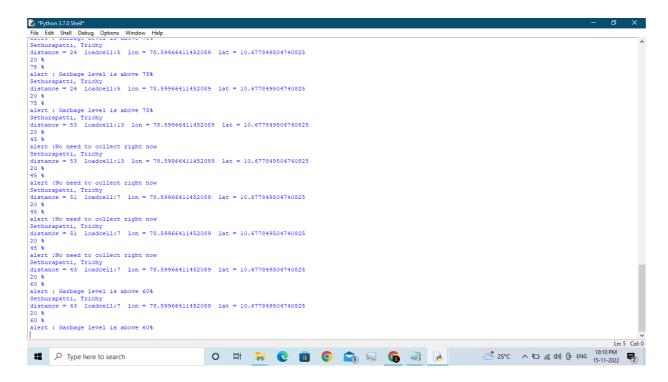
load = "45 %"

```
import random
import ibmiotf.application
import ibmiotf.device
import time
from time import sleep
import sys
#IBM Watson Device Credentials.
organization = "sl1jtd"
deviceType = "abcde"
deviceId = "08"
authMethod = "token"
authToken = "830119106008"
def myCommandCallback(cmd):
  print("Command received: %s" % cmd.data['command'])
  status = cmd.data['command']
try:
  deviceOptions = {"org": organization, "type": deviceType, "id": deviceId, "auth-method":
authMethod, "auth-token": authToken}
  deviceCli = ibmiotf.device.Client(deviceOptions)
except Exception as e:
  print("Caught exception connecting device: %s" % str(e))
  sys.exit()
deviceCli.connect()
while True:
distance= random.randint(10,70)
loadcell= random.randint(5,15)
data= {'dist':distance,'load':loadcell}
#weight of the bin
if loadcell <= 13 and loadcell >= 15:
   load = "90 %"
elif loadcell <= 10 and loadcell >= 12:
   load = "75 %"
elif loadcell <= 8 and loadcell >= 10:
   load = "75 %"
elif loadcell <= 4 and loadcell >= 7:
```

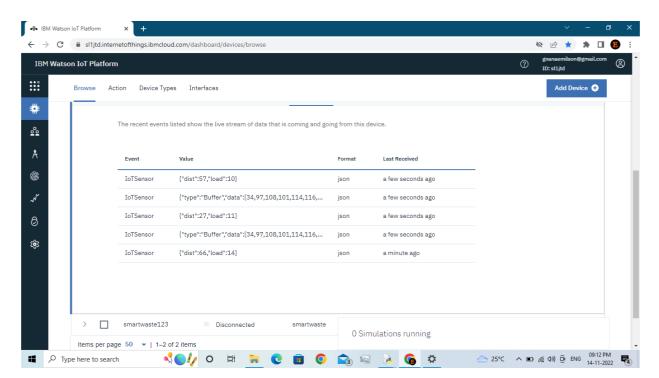
```
else:
  load = "20 %"
#empty distance in the bin
if distance <= 15:
  dist = '90 \%'
elif distance <= 30 and distance >= 16:
  dist = '75 %'
elif distance \leq 45 and distance \geq 31 :
  dist = '60 \%'
elif distance \leq 60 and distance \geq 46:
  dist = '45 \%'
else:
  dist = '25 \%'
#alert and warning for garbage level and weight
if load == "90 %" or dist == "90 %":
  warn = 'alert : Garbage level in the trash can is going to be full, Time to collect '
elif load == "75 %" or dist == "75 %":
  warn = 'alert : Garbage level is above 75%'
elif load == "60 %" or dist == "60 %":
  warn = 'alert : Garbage level is above 60%'
else:
  warn = 'alert :' 'No need to collect right now '
def myOnPublishCallback(lat=10.677849504740825,long=78.59966411452089):
  print("Sethurapatti, Trichy")
  print("distance = %s" %distance,"loadcell:%s" %loadcell,"lon = %s" %long,"lat = %s"
%lat)
  print(load)
  print(dist)
  print(warn)
time.sleep(5)
success=deviceCli.publishEvent ("IoTSensor", "json", warn, qos=0, on_publish=
myOnPublishCallback)
success=deviceCli.publishEvent ("IoTSensor","json",data,qos=0,on_publish=
myOnPublishCallback)
if not success:
  print("not connected to ibmiot")
```

deviceCli.commandCallback=myCommandCallback #disconnect the device deviceCli.disconnect

OUTPUT:



IBM WATSON:



NODE RED

