ASSIGNMENT 4

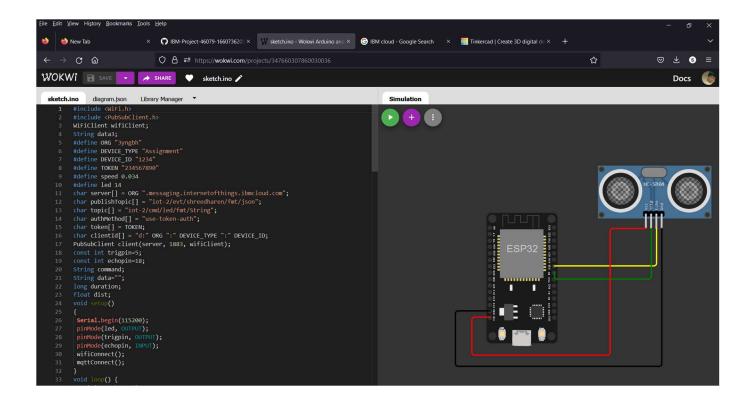
Date	07 November 2022
Team ID	PNT2022TMID47383
Project Name	Real-Time River Water Quality Monitoring and Control System

1.Write Code and connections in wokwi for ultrasonic sensor. whatever distance is less than cms send "Alert" to ibm cloud and display in device recent events.

```
#include <WiFi.h>
#include < PubSubClient.h >
WiFiClient wifiClient;
String data3;
#define ORG "3yngbh"
#define DEVICE TYPE "Assignment"
#define DEVICE ID "1234"
#define TOKEN "234567890"
#define speed 0.034
#define led 14
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/shreedharen/fmt/json";
char topic[] = "iot-2/cmd/led/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE TYPE ":" DEVICE ID;
PubSubClient client(server, 1883, wifiClient);
const int trigpin=5;
const int echopin=18;
String command;
String data="";
long duration;
float dist;
void setup()
Serial.begin(115200);
pinMode(led, OUTPUT);
pinMode(trigpin, OUTPUT);
pinMode(echopin, INPUT);
wifiConnect();
```

```
mqttConnect();
void loop() {
bool isNearby = dist < 100;
digitalWrite(led, isNearby);
publishData();
delay(500);
if (!client.loop()) {
mqttConnect();
void wifiConnect() {
Serial.print("Connecting to "); Serial.print("Wifi");
WiFi.begin("Wokwi-GUEST", "", 6);
while (WiFi.status() != WL CONNECTED) {
delay(500);
Serial.print(".");
Serial.print("WiFi connected, IP address: ");
Serial.println(WiFi.localIP());
void mqttConnect() {
if (!client.connected()) {
Serial.print("Reconnecting MQTT client to "); Serial.println(server);
while (!client.connect(clientId, authMethod, token)) {
Serial.print(".");
delay(500);
initManagedDevice();
Serial.println();
void initManagedDevice() {
if (client.subscribe(topic)) {
// Serial.println(client.subscribe(topic));
Serial.println("IBM subscribe to cmd OK");
} else {
Serial.println("subscribe to cmd FAILED");
```

```
void publishData()
digitalWrite(trigpin,LOW);
digitalWrite(trigpin,HIGH);
delayMicroseconds(10);
digitalWrite(trigpin,LOW);
duration=pulseIn(echopin,HIGH);
dist=duration*speed/2;
if(dist<100){
String payload = "{\"Alert Distance\":";
payload += dist;
payload += "}";
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c_str())) {
Serial.println("Publish OK");
if(dist>100){
String payload = "{\"Distance\":";
payload += dist;
payload += "}";
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if(client.publish(publishTopic, (char*) payload.c_str())) {
Serial.println("Publish OK");
}else {
Serial.println("Publish FAILED");
}
```



Wokwi link: https://wokwi.com/projects/347660307860030036

