

```
import RPi.GPIO as GPIO
import time

#GPIO Modus (BOARD / BCM)
GPIO.setmode(GPIO.BOARD)

#Richtung der GPIO-Pins festlegen (IN / OUT)
GPIO.setup(26, GPIO.OUT)

#unendliche Schleife
while True:
    #Pin 26 HIGH Pegel
    GPIO.output(26, True)
    #eine halbe Sekunde warten
    time.sleep(0.5)
    #Pin 26 LOW Pegel
    GPIO.output(26, False)
    #eine halbe Sekunde warten
    time.sleep(0.5)
```
