

EMERGING METHODS FOR EARLY DETECTION OF FOREST FIRES

VIDEO ANALYSIS

OPENCV FOR VIDEO PROCESSING

Date	04 November 2022
Team ID	PNT2022TMID30386
Project Name	Emerging Methods for Early Detection of Forest Fires

Importing The ImageDataGenerator Library

```
import keras
from keras.preprocessing.image import ImageDataGenerator
```

Define the parameters/arguments for ImageDataGenerator class

```
train_datagen = ImageDataGenerator(rescale=1./255, shear_range=0.2, rotation_range=180, zoom_range=0.2,
horizontal_flip=True) test_datagen = ImageDataGenerator(rescale=1./255)
```

Applying ImageDataGenerator functionality to train set

```
x_train = train_datagen.flow_from_directory(r'/content/drive/MyDrive/Dataset/train_set', target_size=(128, 128), batch_size=32, class_mode='binary')
```

Found 436 images belonging to 2 classes.

Applying ImageDataGenerator functionality to test set

```
x_test=test_datagen.flow_from_directory(r'/content/drive/MyDrive  
/  
Dataset/test_set',target_size=(128,128),batch_size=32,c  
lass_mode='binary')
```

Found 121 images belonging to 2 classes.

Import model building libraries

```
#To define Linear initialisation import Sequential  
from keras.models import Sequential  
#To add layers import Dense  
from keras.layers import Dense  
#To create Convolution kernel import Convolution2D  
from keras.layers import Convolution2D  
#import Max pooling layer  
from keras.layers import MaxPooling2D  
#import flatten layer  
from keras.layers import  
Flatten  
import  
warnings.filterwarnings('igno  
re')
```

Initializing the model

```
model=Sequential()
```

Add CNN Layer

```
model.add(Convolution2D(32,(3,3),input_shape=(12  
8,128,3),activation='relu'))#add max pooling layer
```

```
model.add(MaxPooling2D(pool_size=(2,2)))  
#add flatten layer  
model.add(Flatten())
```

AddHiddenLayer

```
#add hidden  
layermodel.add(Dense(150,activation='relu')  
)#add output  
layermodel.add(Dense(1,activation='sigmoid')  
)
```

Configurethelearningprocess

```
model.compile(loss='binary_crossentropy',optimizer="adam",metrics=["  
accuracy"])
```

Trainthemodel

```
model.fit_generator(x_train,steps_per_epoch=14,epochs=10,validation_  
data=x_test,validation_steps=4)
```

Epoch1/10

14/14[=====]-97s7s/step -loss:

1.3060 -

accuracy: 0.7775 - val_loss: 0.5513 - val_accuracy:

0.8512Epoch2/10

14/14[=====]-26s2s/step -loss:

0.3178 -

accuracy: 0.8807 - val_loss: 0.1299 - val_accuracy:

0.9421Epoch3/10

14/14[=====]-26s2s/step -loss:

0.2226 -

accuracy: 0.9106 - val_loss: 0.1311 - val_accuracy:

0.9421Epoch4/10

14/14[=====]-31s2s/step -loss:

0.1836 -

accuracy: 0.9174 - val_loss: 0.1129 - val_accuracy:

0.9339Epoch5/10

14/14[=====]-30s 2s/step-loss:

0.1675 -

```

accuracy: 0.9243 - val_loss: 0.0925 - val_accuracy:
0.9669Epoch6/10
14/14[=====]-26s2s/step -loss:
0.1884 -
accuracy: 0.9289 - val_loss: 0.1287 - val_accuracy:
0.9339Epoch7/10
14/14[=====] -28s 2s/step -loss:
0.1724 -
accuracy: 0.9335 - val_loss: 0.0926 - val_accuracy:
0.9752Epoch8/10
14/14[=====]-26s2s/step -loss:
0.1510 -
accuracy: 0.9404 - val_loss: 0.0757 - val_accuracy:
0.9752Epoch 9/10
14/14[=====]-26s
2s/step-loss:
accuracy:0.9174-val_loss:0.0537 -val_accuracy:0.9835
Epoch10/10
14/14[=====]-26s
2s/step-loss:
accuracy:0.9312-val_loss:0.0573 -val_accuracy:0.9835
<keras.callbacks.Historyat0x7f05d66a9c90>

```

```

#importcv2
importcv2

```

SaveTheModel

```
model.save("forest1.h5")
```

Predictions

```

#import
load_modelfrom
keras.model
fromkeras.models
importload_model
#importimageclassfromk
eras
from tensorflow.keras.preprocessing import image
#importnumpy
importnumpyasnp

```

0.173-2

0.154-6

#loadthesavedmodel

```
model=load_model("forest1.h5")
```

```
img=image.load_img(r'/content/drive/MyDrive/Dataset/test_set/fore  
st/
```

```
0.48007200_1530881924_final_forest.jpg')x=image.img_to_arra  
y(img)
```

```
res = cv2.resize(x, dsize=(128,  
128),interpolation=cv2.INTER_CU
```

```
BIC)#expand the image
```

```
shapex=np.expand_di
```

```
ms(res,axis=0)p
```

```
red=model.predi
```

```
ct(x)
```

```
1/1[=====]-0s
```

```
126ms/step
```

```
pred
```

```
array([[0.]],dtype=float32)
```

OpenCVForVideoProcessing

pipinstalltwilio

Looking in indexes: <https://pypi.org/simple>, <https://us-python.pkg.dev/colab-wheels/public/simple>Requirement already satisfied:twilio in /usr/local/lib/python3.7/dist-packages(7.15.1)
Requirement already satisfied: pytz in /usr/local/lib/python3.7/dist-packages(fromtwilio)(2022.5)
Requirement already satisfied:requests>=2.0.0in /usr/local/lib/python3.7/dist-packages(fromtwilio)(2.23.0)Requirement already satisfied: PyJWT<3.0.0,>=2.0.0in /usr/local/lib/python3.7/dist-packages(fromtwilio)(2.6.0)Requirement already satisfied:urllib3!=1.25.0,!=1.25.1,<1.26,>=1.21.1in /usr/local/lib/python3.7/dist-packages(fromrequests>=2.0.0->twilio)(1.24.3)
Requirement already satisfied:certifi>=2017.4.17in /usr/local/lib/python3.7/dist-packages (from requests>=2.0.0->twilio)(2022.9.24)
Requirement already satisfied:idna<3,>=2.5in /usr/local/lib/python3.7/dist-packages (from requests>=2.0.0->twilio)(2.10)
Requirement already satisfied:chardet<4,>=3.0.2in /usr/local/lib/python3.7/dist-packages (from requests>=2.0.0->twilio)(3.0.4)

pipinstallplaysound

Looking in indexes: <https://pypi.org/simple>, <https://us-python.pkg.dev/colab-wheels/public/simple>Requirement already satisfied:playsound in /usr/local/lib/python3.7/dist-packages(1.3.0)

#importopencvlibrary

importcv2

```
#importnumpy  
importnumpyasnp  
#importimagefunctionfromkeras  
fromkeras.preprocessingimport
```



```

image#importload_modelfromk
eras
fromkeras.modelsimportload_model
#import client from twilio
APIfrom twilio.rest import
Client#importplaysoundpacka
ge
fromplaysoundimportplaysound

```

WARNING:playsound:playsoundisrelyingonanotherpythonsubproces
s.Pleaseuse`pipinstallpygobject`ifyouwantplaysoundtorun more
efficiently.

```

#load the saved
modelmodel=load_model("fores
t1.h5") #define
videovideo=cv2.VideoCapture(
0)#define the
featuresname=['forest','withfire'
]

```