## Assignment -4 Wowki & IBM Cloud

## Ques on-1:

Write code and connections in wowki for ultrasonic sensor. Whenever the distance is less than 100 cms sent "alert" to ibm cloud and display in device recent events.

```
Solu on:
Code:
#include <WiFi.h>
#include < PubSubClient.h>
WiFiClient wifiClient;
String data3;
#define ORG "3yngbh"
#define DEVICE_TYPE "Assignment"
#define DEVICE_ID "1234"
#define TOKEN "234567890"
#define speed 0.034 #define led 14 char server[] = ORG
".messaging.internetofthings.ibmcloud.com"; char publishTopic[] = "iot-
2/evt/shreedharen/fmt/json"; char topic[] = "iot-2/cmd/led/fmt/String"; char
authMethod[] = "use-token-auth"; char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID; PubSubClient client(server, 1883, wifiClient);
const int trigpin=5; const int
echopin=18;
String command; String
data=""; long duration; float
dist;
void setup()
```

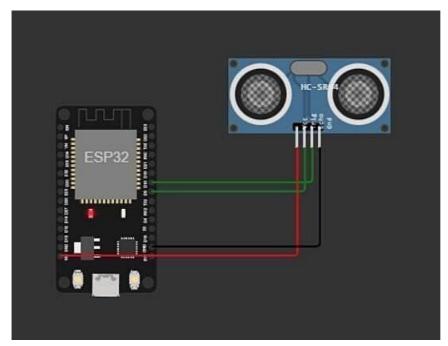
```
{
 Serial.begin(115200); pinMode(led, OUTPUT);
 pinMode(trigpin, OUTPUT);
 pinMode(echopin, INPUT);
 wifiConnect();
 mqttConnect();
}
void loop() {
 bool isNearby = dist < 100;
 digitalWrite(led, isNearby);
 publishData();
 delay(500);
 if (!client.loop()) {
  mqttConnect();
 }
}
void wifiConnect() {
 Serial.print("Connecting to "); Serial.print("Wifi");
 WiFi.begin("Wokwi-GUEST", "", 6);
 while (WiFi.status() != WL_CONNECTED) {
  delay(500);
  Serial.print("."); }
 Serial.print("WiFi connected, IP address: ");
Serial.println(WiFi.localIP());
}
void mqttConnect() {
  if
(!client.connected()) {
  Serial.print("Reconnecting MQTT client to ");
Serial.println(server);
  while (!client.connect(clientId, authMethod, token)) {
```

```
Serial.print(".");
   delay(500);
  }
  initManagedDevice();
  Serial.println();
 }
}
void initManagedDevice() { if
(client.subscribe(topic)) {
  // Serial.println(client.subscribe(topic));
  Serial.println("IBM subscribe to cmd OK"); } else {
  Serial.println("subscribe to cmd FAILED");
 }
}
void publishData()
{
 digitalWrite(trigpin,LOW);
 digitalWrite(trigpin,HIGH);
 delayMicroseconds(10);
 digitalWrite(trigpin,LOW);
 duration=pulseIn(echopin,HIGH);
 dist=duration*speed/2;
 if(dist<100){
  String payload = "{\"Alert Distance\":";
  payload += dist;
  payload += "}";
  Serial.print("\n");
  Serial.print("Sending payload: ");
  Serial.println(payload);
  if (client.publish(publishTopic, (char*) payload.c_str())) {
   Serial.println("Publish OK");
 }
 }
```

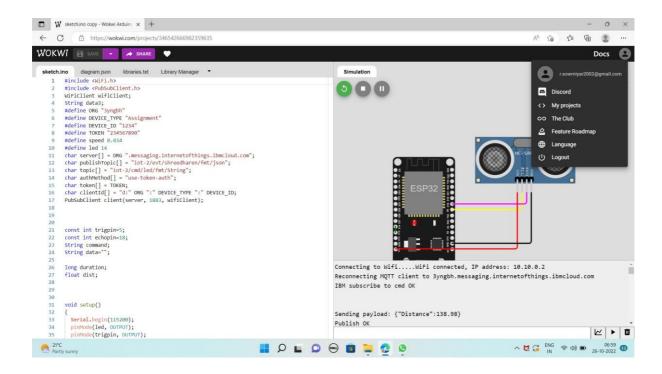
```
if(dist>100){
String payload = "{\"Distance\":";
payload += dist;
payload += "}";

Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if(client.publish(publishTopic, (char*) payload.c_str())) {
    Serial.println("Publish OK");
}else {
    Serial.println("Publish FAILED");
}
```

## Connec ons:



Output:(wowki)



Link: https://wokwi.com/projects/346405970317935188

Output:(IBM Cloud)

