## **Assignment-4**

Question-1: Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to IBM cloud and display in device recent events.

```
Solution:
#define ECHO_PIN 2
#define TRIG_PIN 3
#define organization ="46x7xk"
#define deviceType=" arduino"
#define deviceId ="0504"
#define authMethod ="use-token-auth"
#define authToken ="dv*uK8y__X4O5m!V(K"
void setup() {
// put your setup code here, to run once:
 Serial.begin(9600);
 pinMode(TRIG_PIN,OUTPUT);
 pinMode(ECHO_PIN, INPUT);
}
float readDistanceCM() {
digitalWrite(TRIG_PIN, LOW);
delayMicroseconds(2);
digitalWrite(TRIG_PIN, HIGH);
delayMicroseconds(10);
digitalWrite(TRIG_PIN, LOW);
```

```
int duration = pulseIn(ECHO_PIN, HIGH);
return duration * 0.034 / 2;
}
void loop() {
 // put your main code here, to run repeatedly:
 float distance = readDistanceCM();
 if(distance <= 100)
 {
  Serial.println("person detected ");
 }
 else{
  Serial.print("Measured distance: ");
  Serial.println(readDistanceCM());
 }
 delay(1000);
}
```

```
WOKWI - SAVE - SHARE V
  sketch.ino ● diagram.json Library Manager ▼
                                                                                                                                                        Simulation
                                                                                                                                                    000
       1 #define ECHO_PIN 2
           #define TRIG PIN 3
          #define organization ="46%7xk"
#define deviceType=" anduino"
#define deviceId ="0594"
#define authWethod = use-token-auth"
       7 #define authToken -"dv*uK8y__X405m1V(K"
          void setup() {
           // put your setup code here, to run once:
Serial.begin(9600);
pinhode(TRIG_PIN,OUTPUT);
                                                                                                                                                                                OO) UNO
             pinMode(ECHO_PIN, INPUT);
           float readDistanceCM() {
  digitalNrite(TRIG_PIN, LOW);
           delayMicroseconds(2);
digitalWrite(TRIG_PIN, HIGH);
          delayMicroseconds(18);
digitalWrite(TRIG_PIN, LOW);
    21 int duration = pulseIn(ECHO PIN, HIGH);
22 return duration * 0.034 / 2;
                                                                                                                                                                                                    in in in in
    25 }
    27 void loop() {
28 // put your main code here, to run repeatedly:
           float distance = readDistanceCM();
if(distance <= 100)</pre>
                 Serial.println("person detected ");
           Serial.print("Measured distance: ");
Serial.println(readDistanceOM());
}
             delay(1000);
```

## **Output:**

Wokwi Link: https://wokwi.com/projects/347484942224065107

## **IBM CLOUD**

**Device Recent Events** 

