## **Assignment -4**

Question-1: Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to IBM cloud and display in device recent events.

```
Solution:
#define ECHO_PIN 2
#define TRIG_PIN 3
#define organization ="46x7xk"
#define deviceType=" arduino"
#define deviceId ="0504"
#define authMethod ="use-token-auth"
#define authToken ="dv*uK8y__X4O5m!V(K"
void setup() {
 // put your setup code here, to run once:
 Serial.begin(9600);
 pinMode(TRIG_PIN,OUTPUT);
 pinMode(ECHO_PIN, INPUT);
float readDistanceCM() {
digitalWrite(TRIG_PIN, LOW);
delayMicroseconds(2);
digitalWrite(TRIG_PIN, HIGH);
delayMicroseconds(10);
digitalWrite(TRIG_PIN, LOW);
```

```
int duration = pulseIn(ECHO_PIN, HIGH);
return duration * 0.034 / 2;
void loop() {
 // put your main code here, to run repeatedly:
 float distance = readDistanceCM();
 if(distance <= 100)
  Serial.println("person detected ");
 else{
  Serial.print("Measured distance: ");
  Serial.println(readDistanceCM());
 delay(1000);
```

```
WOKWI - SAVE -
                         SHARE
 sketch.ino • diagram.json Library Manager *
    1 #define ECHO_PIN 2
    2 #define TRIG PIN 3
    #define organization ="46x7xk"
    4 #define deviceType=" arduino"
    5 #define deviceId ="0504"
    6 #define authMethod ="use-token-auth"
       #define authToken ="dv*uK8y__X405m!V(K"
    9 void setup() {
   10 // put your setup code here, to run once:
   11 Serial.begin(9588);
   12 pinMode(TRIG_PIN,OUTPUT);
   13 pinMode(ECHO_PIN, INPUT);
   14 }
   15 float readDistanceCM() {
   16 digitalWrite(TRIG_PIN, LOW);
   17 delayMicroseconds(2);
   18 digitalWrite(TRIG_PIN, HIGH);
                                                                                                                                        ***********
   19 delayMicroseconds(10);
   20 digitalWrite(TRIG_PIN, LOW);
                                                                                                                                        ************
   21 int duration = pulseIn(ECHO_PIN, HIGH);
   22 return duration * 0.034 / 2;
   23
   24
   25
   26
   27 void loop() {
   28 // put your main code here, to run repeatedly:
        float distance = readDistanceCM();
         if(distance <= 100)
   31
   32
           Serial println("person detected ");
   33
   34
         else
           Serial.print("Measured distance: ");
   36
           Serial.println(readDistanceOf());
   37
   38
         delay(1000);
   39
   48
   41
   42
```

## **Output:**

```
WOKWI - SAVE -
                                                                    - SHARE
                                                                                                                                                                                                                                                                                              Simulation
    sketch.ino ● diagram json Library Manager ▼
          1 #define ECHO_PIN 2
          2 #define TRIG PIN 3
                     #define organization ="46x7xk"
          4 #define deviceType*" arduino"
                    #define deviceId ="0504"
                     #define authMethod ="use-token-auth"
                     #define authToken ="dv*uKBy__X405m!V(K"
                     void setup() {
        10 // put your setup code here, to run once:
        11 Serial.begin(9600);
                        pinMode(TRIG_PIN,OUTPUT);
                         pinMode(ECHO_PIN, INPUT);
        14
        15 float readDistanceCM() {
        16 digitalWrite(TRIG_PIN, LOW);
        17 delayMicroseconds(2);
        18 digitalwrite(TRIG_PIN, HIGH);
        19 delayMicroseconds(10);
                                                                                                                                                                                                                                                                                                                                                                               SALAR 
        20 digitalWrite(TRIG_PIN, LOW);
                                                                                                                                                                                                                                                                                                                                                                                .....
        21 int duration = pulseIn(ECHO_PIN, HIGH);
                                                                                                                                                                                                                                                                                                                                                                                 22 return duration * 0.034 / 2;
        23
        24
        25
        26
        27
                     void loop() {
        28
                     // put your main code here, to run repeatedly:
                         float distance = readDistanceCM();
        29
        38
                        if(distance <= 100)
        31
        32
                            Serial.println("person detected ");
        33
                                                                                                                                                                                                                                                                                       Measured distance: 395.27
        34
                                                                                                                                                                                                                                                                                       Measured distance: 395.25
                           Serial.print("Measured distance: ");
        35
                                                                                                                                                                                                                                                                                       Measured distance: 395.27
                             Serial.println(readDistanceOM());
        36
        37
                                                                                                                                                                                                                                                                                       Measured distance: 395.25
        38
                        delay(1800);
                                                                                                                                                                                                                                                                                       Measured distance: 395.25
        39
                                                                                                                                                                                                                                                                                       Measured distance: 395.25
        48
        41
                                                                                                                                                                                                                                                                                       Measured distance: 395.25
        42
```

Wokwi Link: https://wokwi.com/projects/347484942224065107

## **IBM CLOUD**

**Device Recent Events** 

