

Coding:

```
#include<Wifi.h>//library for wifi
#include<PubSubClient.h>//library for MQTT
void callback(char* subscribetopic, byte* payload,unsigned int payloadlength);
//-----credentials of IBM Account-----
#define ORG "45z3o2"// IBM ORGANIZATION ID
#define DEVICE_TYPE "ESP32_Controller"//DEVICE TYPE MENTIONED IN IOT WATSON PLATFORM#define
DEVICE_ID "bme2"//DEVICE ID MENTIONED IN IOT WATSON PLATFORM
#define TOKEN "OKZ+q@JfPWDOd6wBTj"//Token
String data3;
float dist;
//-----customize the above value-----
char server[]=ORG ".messaging.internetofthings.ibmcloud.com";//server name
char publishtopic[]="ultrasonic/evt/Data/fmt/json";//topic name and type of event performand
/*format in which data to be send*/
char subscribetopic[]="ultrasonic/cmd/test/fmt/String";//cmd REPRESENT Command tupe and
COMMAND IS TEST OF FORMAT STRING*/
```

```
char authMethod[]="use-token-auth";//authentication method char
token[]=TOKEN;

char clientid[]="d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;//CLIENT ID
// .....

WiFiClient wifiClient;// creating an instance for wifi client
PubSubClient client(server, 1883 , callback , wifiClient);/*calling the predefined client id by
passing parameter like server id,portand wificredential*/

int LED =4;
int trig =5;
int echo=18;

void setup(){

  Serial.begin(115200);
  pinMode(trig,OUTPUT);
  pinMode(echo,INPUT);
  pinMode(LED,OUTPUT);
  delay(10);
  Serial.println();
  wificonnect();
  mqttconnect();
}
```

```

void loop() {
    digitalWrite(trig,LOW);
    digitalWrite(trig,HIGH);
    delayMicroseconds(10);
    digitalWrite(trig,LOW);
    float dur=pulseIn(echo,HIGH);
    float dist=(dur * 0.0343)/2;
    Serial.print("distance in cm");
    Serial.println(dist);
    PublishData(dist); delay(1000);
    if (!client.loop()){
        mqttconnect();
    }
}

/*.....retriving          to cloud.....*/
void PublishData(float dist){ mqttconnect();//function
    call for connecting to ibm
    /*creating the string in form of JSON to update the data to ibm cloud*/String
    object;

```

```
if(dist<100)
{
    digitalWrite(LED,HIGH);
    Serial.println("no object is near");
    object="Near";
}
else
{
    digitalWrite(LED,LOW);
    Serial.println("no object found");
    object="No";
}
String payload="{\"distance\": ";
payload +=dist;
payload +=",\" \"object\": \"";
payload += object;
payload += "\"} ";

Serial.print("Sending payload: ");
Serial.println(payload);
```

```

if(client.publish(publishtopic, (char*) payload.c_str())){
    Serial.println("Publish ok");/* if its sucessfully upload data on the cloud then it will print publish ok
    in serial monitor or else it will print publish failed*/
} else{
    Serial.println("Publish failed");
}
}

void mqttconnect(){
    if(!client.connected()){
        Serial.print("Reconnecting client to ");
        Serial.println(server);
        while(!client.connect(clientid,authMethod, token)){
            Serial.print(".");
            delay(500);
        }
        initManagedDevice();
        Serial.println();
    }
}

void wificonnect();//function defenition for wificonnect

```

```

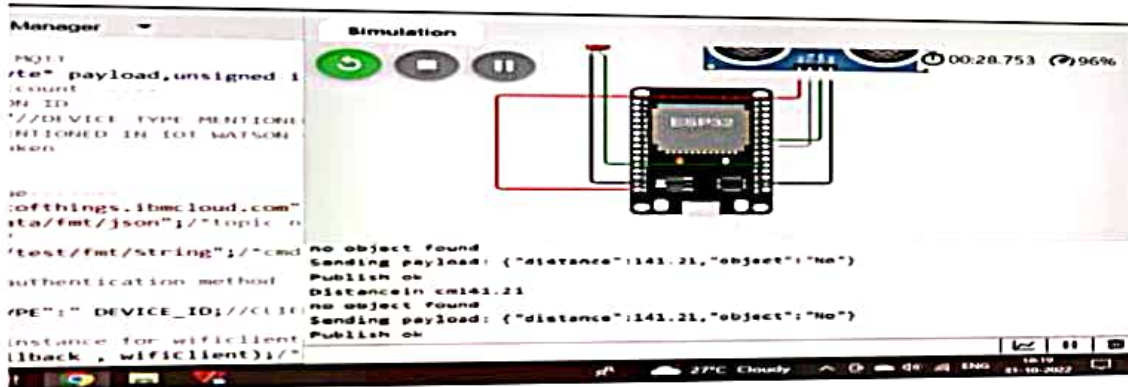
{
    Serial.println();
    Serial.print("Connecting to ");
    WiFi.begin("vivo 1816", "taetae95");//PASSING THE WIFI CREDENTIALS TO ESTABLISH CONNECTION
    while (WiFi.status() != WL_CONNECTED){
        delay(500);
        Serial.print(".");
    }
    Serial.println("");
    Serial.println("WiFi connected");
    Serial.println("IP address");
    Serial.println(WiFi.localIP());
}

void initManagedDevice(){
    if(client.subscribe(subscribetopic)){
        Serial.println((subscribetopic));
        Serial.println("subscribe to cmd OK");
    }else{
        Serial.println("subscribe to cmd failed");
    }
}

```

```
}  
  
void callback(char* subscribetopic,byte*payload,unsigned int payloadLength)  
{  
    Serial.print("callback invoked for topic: ");  
    Serial.println(subscribetopic);  
    for(int i=0; i< payloadLength; i++){  
        //Serial.print((char)payload[i]);  
        data3 +=(char)payload[i];  
    }  
    //Serial.println("dta: "+ data3);  
    //if(data3=="Near")  
    //{  
    //Serial.println(data3);  
    //digitalWrite(LED,HIGH);  
    //}  
    //else //{  
    //Serial.println(data3);  
    //digitalWrite(LED,LOW);//}  
    data3="";  
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