Question1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

WOKWI LINK:

https://wokwi.com/projects/305566932847821378

CODE:

```
# disclars ordered list. Dec. () the most property of the most personal list ordered list. Dec. () the most personal list. Dec
```

```
pinMode(trig,OUTPUT);
pinMode(echo,IMPUT);
pinMode(LED, OUTPUT);
delay(10);
37
10
19
     wificonnect();
44
     mqttconnect();
47
    void loop()// Recursive Function
45
      digitalwrite(trig,LOW);
46
      digitalWrite(trig, HIGH);
47
      delayMicroseconds(18);
43
      digitalWrite(trig,tow);
49
       float dur = pulseIn(echo,HIGH);
50
      float dist = (dur * 0.0343)/2;
31
      Serial print ("Distancein cm");
.
      Serial.println(dist);
33
7
55
56
      PublishData(dist);
       delay(1000);
57
       if (iclient.loop()) {
mqttconnect();
3
68
61
62
63
/*.....*/
65
66
     void PublishData(float dist) (
17
      mqttconnect();//function call for connecting to ibm
68
69
70
      creating the String in in form 15on to undate the data to the clo
```

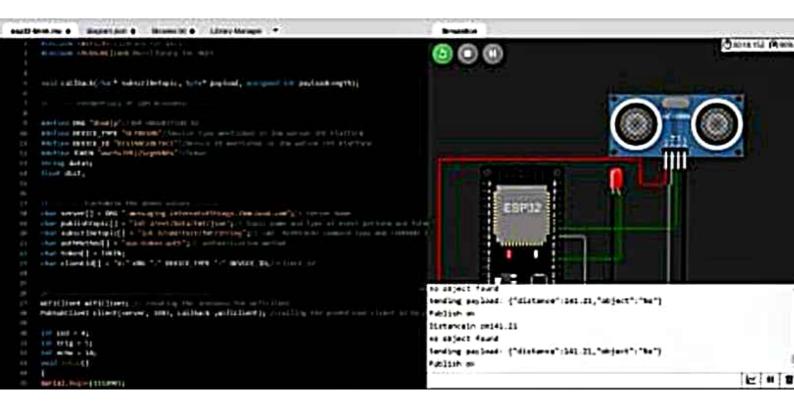
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creating the Afring in in fore 25on to applate the data to its cloud
    1
                          String objects
                            If (dist <100)
    \overline{a}
    И
                                   digitalirite(LED,HIGH);
    4
                                   Serial.printle("object is near");
    76
                                  object " "New"
    17
    79
                            2 72
    digitalistite(LED,(CM);
    П
                                  seriel.println("no object found");
abject = "No";
    .
    ۲
    . .
                           string payload = "{\"distance\":";
payload == ";" "\"abject\":\"";
payload == abject;
    TF.
    77
    \overline{\phantom{a}}
    1
                              popland on "\")";
    3
    97
                          Serial.print("Sending payload: ");
    .
    3
                            Serial.println(payload);
    .
    97
                                           147 #1 1 - 0
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ngli ore re .
                    [* [cliset.philub@milichTopic, [char*) psyload.r_atr())] [
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 test
                         Sectal ar notice "publish failed"
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 10
                mild melteswort()
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                     if [liliest_measted()) (
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                         sectal script ("ecomecting client to "li
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                          bertal printle(server);
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                         wite (Iliciant.comet[clientic, authoritat, tubes]) (
                              serial print["-"li
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 14
 .
 .
 110
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                   torial.printle(");
torial.printle(");
torial.printle(")* automat ");
 10
```

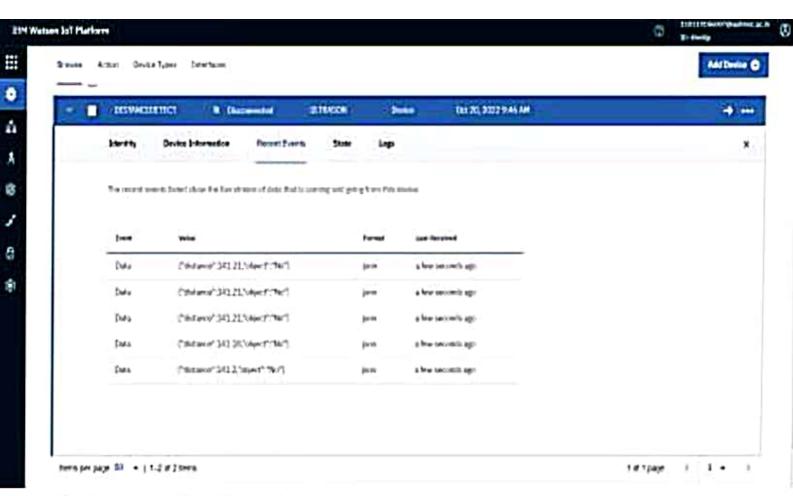
TY

```
MiF1.begin("Wobwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
124
        while (MIFI.status() I- ML_COMMECTED) (
125
176
          delay(500);
          Serial.print(",");
111
1718
        Serial printin("");
129
        Serial.println("NiFi connected");
130
        Serial.println("IP address: ");
111
        Serial.println(MiFi.localIF());
1877
в
\mathbf{I}
      void initPanagedDevice() (
if (client.subscribe(subscribetopic)) (
116
          Serial.println((subscribetopic));
117
          Serial.println("subscribe to cmd OK");
139
        else (
         Serial printin("subscribe to cmd FAILED");
140
141
142
void callback(char* subscribetopic, byte* payload, unsigned int payloadlength)
111
133
144
        Serial print("callback invoked for topic: ");
147
        Serial.println(subscribetopic);
148
140
        for (int i - 0; i < psyloadlongth; i++) {
          //Serial.print((char)payload[i]);
...
          data3 +- (char)payload[i];
123
157
1533
           Serial.println("data: "+ data3);
1
      11
           If(data) == "Near")
155
      11
"
      // Serial.println(data));
157
```

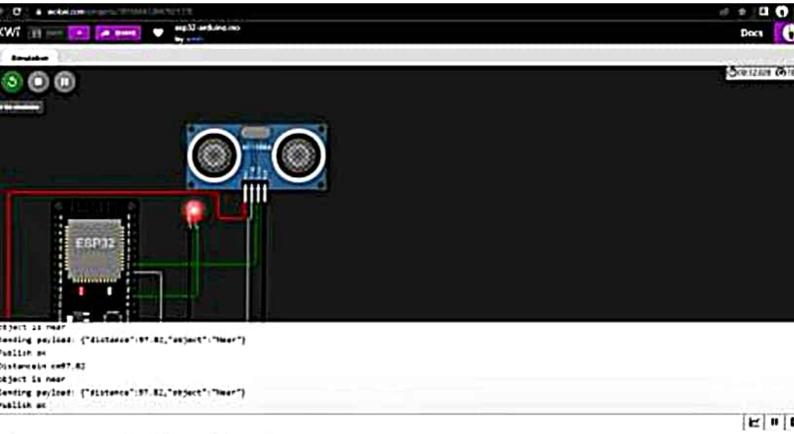
```
142
143
144
      void callback(char* subscribetopic, byte* payload, unsigned int payloadlength)
145
146
        Serial.print("callback invoked for topic: ");
147
        Serial.println(subscribetopic);
148
        for (int i = 0; i < payloadlength; i++) [
149
          //Serlal.print((char)paylmad[[]);
150
151
          data3 += (char)payload[i];
        ١
152
153
           Secial println("data: "* data));
154
155
           If(data3--"Mear")
156
157
158
      // digitalwrite(IED, HIGH);
159
160
161
162
      // mlse
163
164
165
      // digitalwrite(ttD,tOW);
166
157
      data3-"":
168
169
170
      7
171
```

OUTPUT:

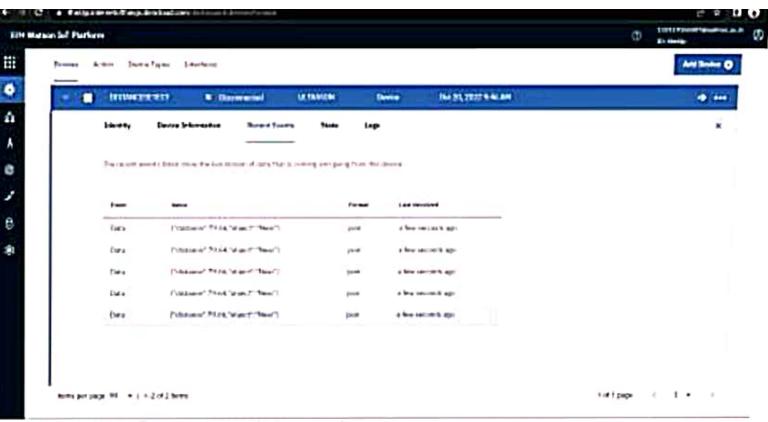




when object is near to the ultrasonic sensor



Data sent to the IBM Cloud Device when the object is near



nttps://wokwi.com/projects/305566932847821378