

## Sprint 2

# Signs with Smart Connectivity for Better Road Safety

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### Sprint Goals:

Push data from local code to cloud

### Program Code:

> weather.py

This file is a utility function that fetches the weather from OpenWeatherAPI. It returns only certain required parameters of the API response.

# Python code

import requests as reqs

def get(myLocation,APIKEY):

    apiURL =

    f"https://api.openweathermap.org/data/2.5/weather?q={ myLocation }&appid={ API KEY }"

    responseJSON = (reqs.get(apiURL)).json()

    returnObject = {

        "temperature" : responseJSON['main']['temp'] - 273.15,

        "weather" : [responseJSON['weather'][\_]['main'].lower() for \_ in

range(len(responseJSON['weather']))],

        "visibility" : responseJSON['visibility']/100, # visibility in percentage where 10km is 100% and 0km is 0%

    }

    if("rain" in responseJSON):

        returnObject["rain"] = [responseJSON["rain"][key] for key in

responseJSON["rain"]]

    return(returnObject)

> publishData.py

This code pushes data to the cloud and logs data. IBM Cloud is configured such that the data is displayed in the following website: [CLICK TO OPEN NODE RED DASHBOARD](#)

# Python code

```
# IMPORT SECTION STARTS
```

```
import wiotp.sdk.device # python -m pip install wiotp
import time
```

```
# IMPORT SECTION ENDS
```

```
# _____
```

```
# API CONFIG SECTION STARTS
```

```
myConfig = {
    "identity" : {
        "orgId" : "epmoec",
        "typeId" : "testDevice",
        "deviceId" : "device0"
    },
    "auth" : {
        "token" : "?-KDXUPMvDo_TK2&b1"
    }
}
```

```
# API CONFIG SECTION ENDS
```

```
# _____
```

```
# FUNCTIONS SECTION STARTS
```

```
def myCommandCallback(cmd):
    print("recieved cmd : ",cmd)
```

```
def logData2Cloud(location,temperature,visibility):
    client = wiotp.sdk.device.DeviceClient(config=myConfig,logHandlers=None)
    client.connect()
    client.publishEvent(eventId="status",msgFormat="json",data={
        "temperature" : temperature,
        "visibility" : visibility,
        "location" : location
    },qos=0,onPublish=None)
    client.commandCallback = myCommandCallback
    client.disconnect()
    time.sleep(1)
```

```
# FUNCTIONS SECTION ENDS
```

```
> brain.py
```

This file is a utility function that returns only essential information to be displayed at the hardware side and abstracts all the unnecessary details. This is where the code

flow logic is implemented.

```
from datetime import datetime as dt
from publishData import logData2Cloud as log2cloud
```

```
# IMPORT SECTION ENDS
```

```
# _____
```

```
# UTILITY LOGIC SECTION STARTS
```

```
def processConditions(myLocation,APIKEY,localityInfo):
```

```
    weatherData = weather.get(myLocation,APIKEY)
```

```
    log2cloud(myLocation,weatherData["temperature"],weatherData["visibility"])
```

```
    finalSpeed = localityInfo["usualSpeedLimit"] if "rain" not in weatherData else
localityInfo["usualSpeedLimit"]/2
```

```
    finalSpeed = finalSpeed if weatherData["visibility"]>35 else finalSpeed/2
```

```
    if(localityInfo["hospitalsNearby"]):
```

```
        # hospital zone
```

```
        doNotHonk = True
```

```
    else:
```

```
        if(localityInfo["schools"]["schoolZone"]==False):
```

```
            # neither school nor hospital zone
```

```
            doNotHonk = False
```

```
        else:
```

```
            # school zone
```

```
            now = [dt.now().hour,dt.now().minute]
```

```
            activeTime = [list(map(int,_.split(":"))) for _ in
```

```
localityInfo["schools"]["activeTime"]]
```

```
            doNotHonk = activeTime[0][0]<=now[0]<=activeTime[1][0] and
activeTime[0][1]<=now[1]<=activeTime[1][1]
```

```
    return({
```

```
        "speed" : finalSpeed,
```

```
        "doNotHonk" : doNotHonk
```

```
    })
```

```
# UTILITY LOGIC SECTION ENDS
```

```
> main.py
```

The code that runs in a forever loop in the micro-controller. This calls all the util functions from other python files and based on the return value transduces changes in the output hardware display.

```
# Python code
```

```
# IMPORT SECTION STARTS
```

```
import brain
```

```
# IMPORT SECTION ENDS
```

```
# _____
```

```
# USER INPUT SECTION STARTS
```

```
myLocation = "Chennai,IN"
```

```
APIKEY = "bf4a8d480ee05c00952bf65b78ae826b"
```

```
localityInfo = {
```

```
    "schools" : {
```

```
        "schoolZone" : True,
```

```
        "activeTime" : ["7:00","17:30"] # schools active from 7 AM till 5:30 PM
```

```
    },
```

```
    "hospitalsNearby" : False,
```

```
    "usualSpeedLimit" : 40 # in km/hr
```

```
}
```

```
# USER INPUT SECTION ENDS
```

```
# _____
```

```
# MICRO-CONTROLLER CODE STARTS
```

```
while True :
```

```
    print(brain.processConditions(myLocation,APIKEY,localityInfo))
```

```
'''
```

```
MICRO CONTROLLER CODE WILL BE ADDED IN SPRINT 3 AS PER OUR  
PLANNED SPRINT SCHEDULE
```

```
'''
```

```
# MICRO-CONTROLLER CODE ENDS
```

```
Output :
```

```
LINK TO NODE RED DASHBOARD
```

```
# Code Output
```

```
2022-11-06 21:38:33,452 wiotp.sdk.device.client.DeviceClient INFO
```

```
Connected successfully: d:epmoec:testDevice:device0
```

```
2022-11-06 21:38:33,452 wiotp.sdk.device.client.DeviceClient INFO
```

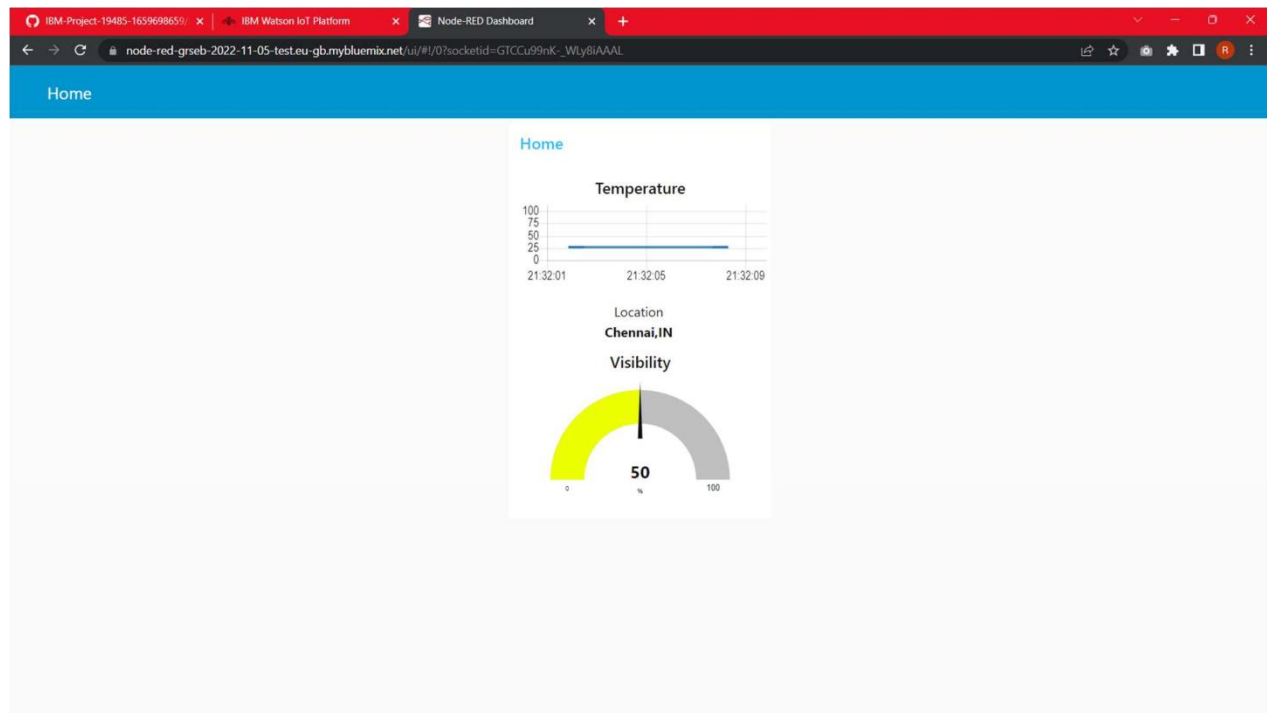
```
Disconnected from the IBM Watson IoT Platform
```

```
2022-11-06 21:38:33,452 wiotp.sdk.device.client.DeviceClient INFO Closed  
connection to the IBM Watson IoT Platform
```

```
{'speed': 40, 'doNotHonk': False}
```

```
2022-11-06 21:38:35,631 wiotp.sdk.device.client.DeviceClient INFO
Connected successfully: d:epmoec:testDevice:device0
2022-11-06 21:38:35,631 wiotp.sdk.device.client.DeviceClient INFO
Disconnected from the IBM Watson IoT Platform
2022-11-06 21:38:35,631 wiotp.sdk.device.client.DeviceClient INFO    Closed
connection to the IBM Watson IoT Platform
{'speed': 40, 'doNotHonk': False}
.
.
.
... repeats every 1 sec
```

## Output Image



## Output Image

The screenshot displays the Visual Studio Code interface with a project named "IBM". The Explorer sidebar on the left shows the project structure, including a "Project Development Phase" folder with subfolders for "Sprint 1", "Sprint 2", "Sprint 3", and "Sprint 4". The "main.py" file is selected in the "Sprint 2" folder.

The main editor window shows the following Python code in "main.py":

```
19     "hospitalsNearby" : False,
20     "usualSpeedLimit" : 40 # in km/hr
21 }
22
23 # USER INPUT SECTION ENDS
24 # -----
25 # MICRO-CONTROLLER CODE STARTS
26 while True :
27     print(brain.processConditions(myLocation,APIKEY,localityInfo))
28
29
30 MICRO CONTROLLER CODE WILL BE ADDED IN SPRINT 2 AS PER OUR PLANNED
31
32
```

The bottom panel shows the "TERMINAL" output, which contains the following logs:

```
P:\temp\IBM\Project Development Phase\Sprint 2>python main.py
2022-11-06 21:32:02,167 wiotp.sdk.device.client.DeviceClient INFO Connected successfully: d:epmoec:testDevice:device0
2022-11-06 21:32:02,182 wiotp.sdk.device.client.DeviceClient INFO Disconnected from the IBM Watson IoT Platform
2022-11-06 21:32:02,182 wiotp.sdk.device.client.DeviceClient INFO Closed connection to the IBM Watson IoT Platform
{'speed': 40, 'dototkank': False}
2022-11-06 21:32:04,330 wiotp.sdk.device.client.DeviceClient INFO Connected successfully: d:epmoec:testDevice:device0
2022-11-06 21:32:04,330 wiotp.sdk.device.client.DeviceClient INFO Disconnected from the IBM Watson IoT Platform
2022-11-06 21:32:04,330 wiotp.sdk.device.client.DeviceClient INFO Closed connection to the IBM Watson IoT Platform
{'speed': 40, 'dototkank': False}
```

The status bar at the bottom indicates the current file is "main.py" at line 29, column 4, using UTF-8 encoding and CRLF line endings. The Python version is 3.8.5 64-bit.