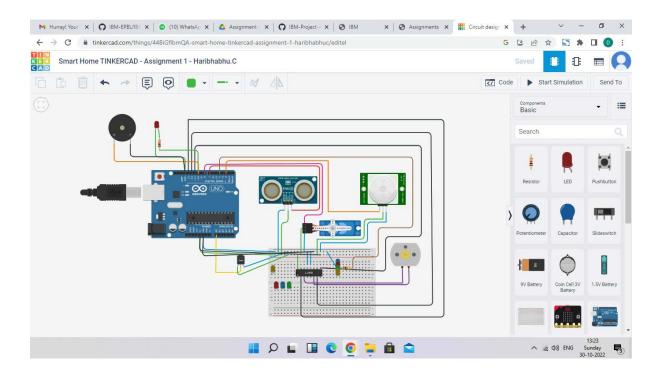
## Assignment -1

Assignment Date	21 September 2022
Student Name	Haribhabhu.C
Student Roll Number	713319CS034
Maximum Marks	2 Marks

## Question-1:

Build a smart home in Tinkercad with 2 sensors, an Led, buzzer and submit it

## **Solution:**



```
#include<Servo.h>
const int pingPin = 7;
int servoPin = 8;

Servo servo1;

void setup() {
    Serial.begin(9600);
```

```
servo1.attach(servoPin);
 pinMode(2,INPUT);
 pinMode(4,OUTPUT);
 pinMode(11,OUTPUT);
 pinMode(12,OUTPUT);
 pinMode(13,OUTPUT);
 pinMode(A0,INPUT);
 digitalWrite(2,LOW);
 digitalWrite(11,HIGH);
 pinMode(2, INPUT);
 pinMode(10,OUTPUT);
}
void loop() {
 long duration, inches, cm;
 pinMode(pingPin, OUTPUT);
 digitalWrite(pingPin, LOW);
 delayMicroseconds(2);
 digitalWrite(pingPin, HIGH);
 delayMicroseconds(5);
 digitalWrite(pingPin, LOW);
 pinMode(pingPin, INPUT);
 duration = pulseIn(pingPin, HIGH);
inches = microsecondsToInches(duration);
 cm = microsecondsToCentimeters(duration);
 servo1.write(0);
```

```
if(cm < 40)
 servo1.write(90);
 delay(2000);
}
else
{
 servo1.write(0);
}
int pir = digitalRead(2);
if(pir == HIGH)
 digitalWrite(4,HIGH);
 delay(1000);
}
else if(pir == LOW)
 digitalWrite(4,LOW);
}
Serial.println(digitalRead(2));
if (digitalRead(2) == 1) {
 digitalWrite(10, HIGH);
} else {
 digitalWrite(10, LOW);
}
delay(10);
float value=analogRead(A0);
```

```
float temperature=value*0.48;
Serial.println("temperature");
Serial.println(temperature);
if(temperature > 20)
  digitalWrite(12,HIGH);
  digitalWrite(13,LOW);
}
else
{
  digitalWrite(12,LOW);
  digitalWrite(13,LOW);
}
}
long microsecondsToInches(long microseconds) {
return microseconds / 74 / 2;
}
long microsecondsToCentimeters(long microseconds) {
return microseconds / 29 / 2;
}
```