

## SPRINT – 2

DATE	12 November 2022
TEAM ID	PNT2022TMID0
PROJECT NAME	Smart Farmer - IoT Enabled Smart Farming Application

### FINAL SENSOR CONNECTION WITH ARDUINO PROGRAM FOR OUR PROJECT

#### **Description:**

This Smart Irrigation System is used to help farmers in the irrigation process. The System provides data on the parameters which can be used to monitor the condition of the field to maintain and protect the crops. The parameters like temperature, soil moisture, the water level in the field, etc., can be accessed through the system. The sensors in the system monitor the parameters and provide them to the farmer to take the necessary measures.

#### **Program:**

```
#include <Adafruit_LiquidCrystal.h> //Includes the library for LCD Display
```

```
#include <Wire.h> //Includes the library for connections
```

```
#include <Servo.h> //Includes the library for Servo Motor
```

```
Servo s;
```

```
int e = 4;
```

```
int t = 5;
```

```
int r = 12;
```

```
int b = 11;
```

```
int g = 10;
```

```
int sec = 0;
```

```
int Sensor = 0;  
int soil = 0;  
int motorPin = 9;  
Adafruit_LiquidCrystal lcd(0);
```

```
void setup()  
{  
  Wire.begin();  
  pinMode(A0, INPUT);           // Temperature Sensor  
  pinMode(A1, INPUT);           // Soil Moisture Sensor  
  pinMode(t, OUTPUT);           // Ultra sonic Trigger  
  pinMode(e, INPUT);           // Ultra sonic Echo  
  pinMode(b, OUTPUT);           // GREEN light for LED  
  pinMode(g, OUTPUT);           // BLUE light for LED  
  pinMode(r, OUTPUT);           // RED light for LED  
  pinMode(motorPin, OUTPUT);    // DC motor  
  s.attach(3);                  // Servo Motor  
  lcd.begin(16, 2);             // LCD 16x2 Display  
  lcd.setBacklight(0);  
  Serial.begin(9600);  
}
```

```
float readDistanceCM()  
{  
  digitalWrite(t, LOW);  
  delayMicroseconds(2);  
  digitalWrite(t, HIGH);
```

```

    delayMicroseconds(10);
    digitalWrite(t, LOW);
    int duration = pulseIn(e, HIGH);
    return duration * 0.034 / 2;
}

void loop()
{
    // Soil Moisture:
    Sensor = analogRead(A1);
    // Reads data from Soil Moisture sensor
    soil = map(Sensor, 0, 1023, 0, 117);
    // Low analog value indicates HIGH moisture level and High analog value
    indicates LOW moisture level
    // data = map(analogValue,fromLOW,fromHIGH,toLOW,toHIGH)
    Serial.print("Soil Moisture value:");
    Serial.println(soil);
    //'data = 0' indicates total wetness and 'data = 100' indicates total dryness

    // Temperature:
    double a = analogRead(A0); // Reads data from Temperature sensor
    double t = (((a / 1024) * 5) - 0.5) * 100;
    Serial.print("Temperature value:"); //Temperature value in Celsius
    Serial.println(t);

    // Ultrasonic sensor:
    float distance = readDistanceCM(); //Reads data from Ultrasonic sensor
    Serial.print("Measured distance: ");

```

```
Serial.println(readDistanceCM());
```

```
// LCD Display:
```

```
lcd.setBacklight(1);           //ON the background light in LCD
```

```
lcd.clear();
```

```
// Conditions:
```

```
/*If the temperature is Greater than 20 and less than 35 and also the moisture  
of soil is less than 60 then the GREEN light will be turned ON indicating the  
Normal condition */
```

```
if (t >= 20 && t < 35 && soil >= 40 && soil < 50)
```

```
{
```

```
    digitalWrite(b, 0);
```

```
    digitalWrite(g, 1);
```

```
    digitalWrite(r, 0);
```

```
    s.write(90);
```

```
    digitalWrite(motorPin, HIGH);
```

```
    lcd.setCursor(3, 0);
```

```
    lcd.print("ON MOTOR");
```

```
    delay(1000);
```

```
    lcd.clear();
```

```
    Serial.println("Water Partially Flows");
```

```
}
```

```
/*If the temperature is Greater than 35 and less than 45, then the BLUE light  
will be turned ON indicating the Intermediate risk condition due to slightly  
warm weather */
```

```

else if (t >= 35 && t < 45)
{
    digitalWrite(b, 1);
    digitalWrite(g, 0);
    digitalWrite(r, 0);
    s.write(90);
    digitalWrite(motorPin, HIGH);
    lcd.setCursor(3, 0);
    lcd.print("ON MOTOR");
    delay(1000);
    lcd.clear();
    Serial.println("Water Partially Flows");
}

```

/\*If the temperature is Greater than 45 or the moisture of soil is less than 30, then the RED light will be turned ON indicating the Critical condition due to highly warm weather or the low moisture content in soil \*/

```

else if (t >= 45 || soil < 30)
{
    digitalWrite(b, 0);
    digitalWrite(g, 0);
    digitalWrite(r, 1);
    s.write(180);
    digitalWrite(motorPin, HIGH);
    Serial.println("Water Fully Flows");
    lcd.setCursor(2, 0);
    lcd.print("ON MOTOR!!!");
    lcd.setCursor(3, 1);
}

```

```
lcd.print("Low Water");  
delay(1000);  
lcd.clear();  
}
```

/\*If the level of water is MORE in the field it will be indicated by distance sensor for less than 10cm and also the moisture of soil is greater than 80, then the YELLOW light will be turned ON indicating the high water level \*/

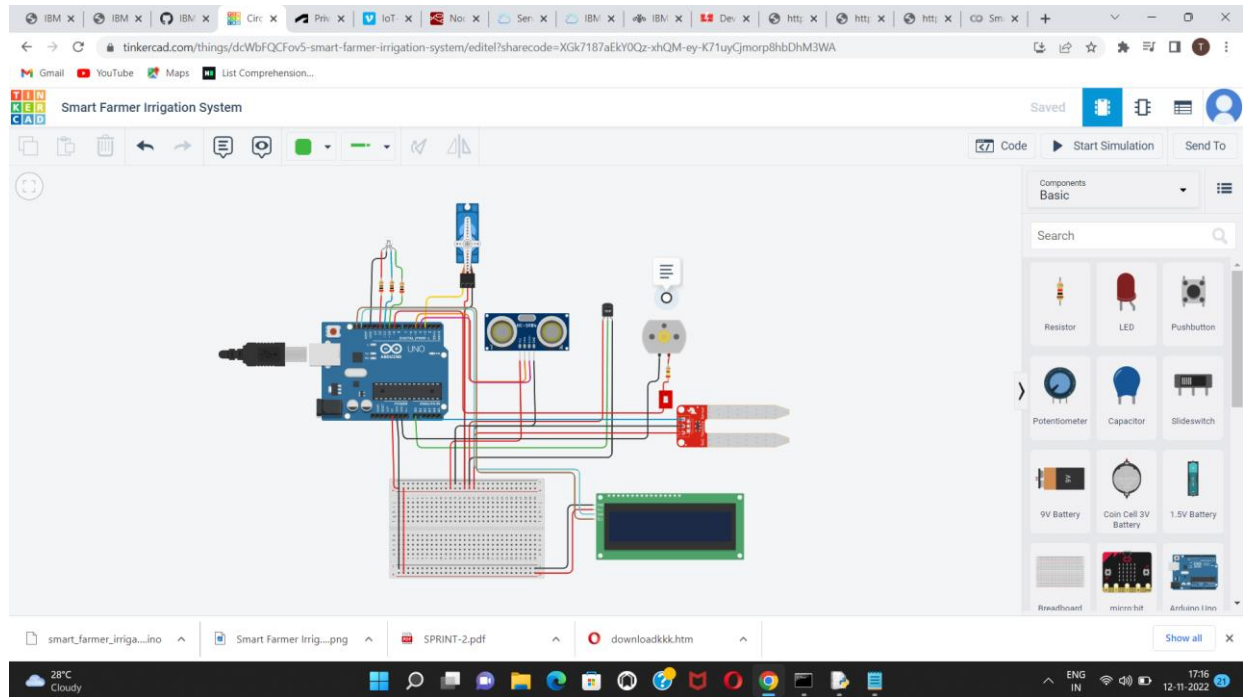
```
else if (distance<10 && soil> 80)  
{  
digitalWrite(b, 0);  
digitalWrite(g, 1);  
digitalWrite(r, 1);  
s.write(0);  
digitalWrite(motorPin, LOW);  
Serial.println("Water Does Not Flow");  
lcd.clear();  
lcd.setCursor(3, 0);  
lcd.print("OFF MOTOR");  
delay(1000);  
lcd.clear();  
lcd.setCursor(1, 0);  
lcd.print("DRAIN WATER!!!");  
delay(1000);  
lcd.clear();  
}
```

```
else
{
    digitalWrite(b, 1);
    digitalWrite(g, 1);
    digitalWrite(r, 0);
    s.write(0);
    digitalWrite(motorPin, LOW);
    lcd.setCursor(3, 0);
    lcd.print("OFF MOTOR");
    delay(1000);
    lcd.clear();
    Serial.println("Water Does Not Flow");
}
```

```
    lcd.setCursor(0, 0);
    lcd.print("Temp:");
    lcd.print(t);
    lcd.print("degree");
    lcd.setCursor(0, 1);
    lcd.print("SoilWetness:");
    lcd.print(soil);
    lcd.print("%");

    Serial.println(" -----");
    delay(1000);
}
```

# Circuit Diagram:





## Component Used:

Name	Quantity	Component
UAU	1	Arduino Uno R3
SERVOMS	1	Positional Micro Servo
DLED	1	LED RGB
RGreen LED Resistor RRed LED Resistor RBlue LED Resistor	3	200 $\Omega$ Resistor
SENSMS	1	Soil Moisture Sensor
MSmall 6V DC Motor	1	DC Motor
RMotor Resistor	1	240 $\Omega$ Resistor
UTS	1	Temperature Sensor [TMP36]
DISTUltrasonic Distance Sensor	1	Ultrasonic Distance Sensor
U3	1	MCP23008-based, 32 LCD 16 x 2 (I2C)
SWDPST Switch	1	DIP Switch DPST