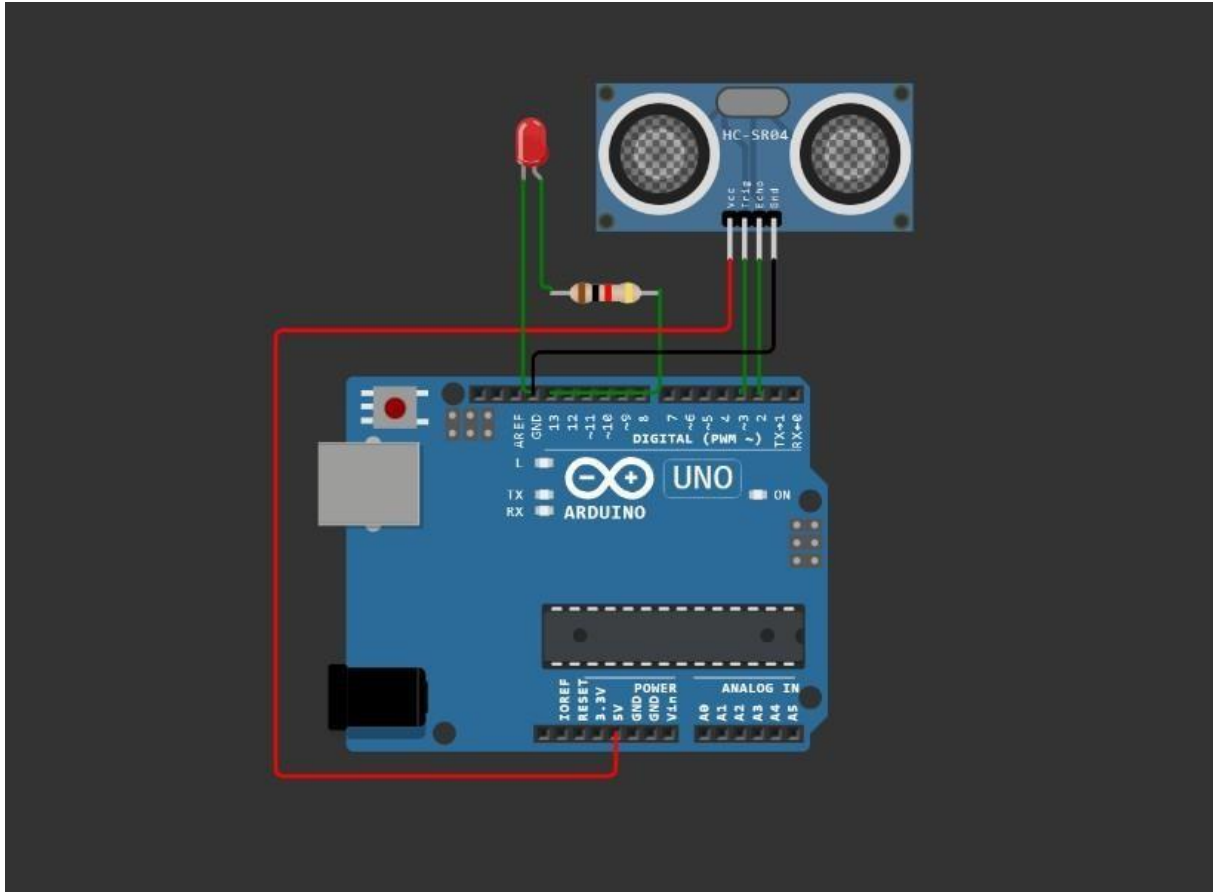


# ULTRASONIC SENSORS



```
#define ECHO_PIN 2

#define TRIG_PIN 3

void setup() {
  Serial.begin(115200);

  pinMode(LED_BUILTIN, OUTPUT);
  pinMode(TRIG_PIN, OUTPUT);
  pinMode(ECHO_PIN, INPUT);
}

float readDistanceCM() {
  digitalWrite(TRIG_PIN, LOW);
```

```
delayMicroseconds(2);
digitalWrite(TRIG_PIN, HIGH);
delayMicroseconds(10);
digitalWrite(TRIG_PIN, LOW);
int duration = pulseIn(ECHO_PIN, HIGH);
return duration * 0.034/2;
}

void loop() {
    float distance = readDistanceCM();

    bool isNearby = distance < 100 ;
    digitalWrite(LED_BUILTIN, isNearby);
    Serial.print("Measured distance: ");
    Serial.println(readDistanceCM());

    delay(100);
```

<https://wokwi.com/projects/346497866532913748>