

Assignment-4

Assignment Date	20 October 2022
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Maximum Marks	2 Marks

Question-1:

Write code and connections in work for the ultrasonic sensor.

Whenever the distance is less than 100 cms send an "alert" to the IBM cloud and display in the device recent events.

Upload document with wokwi share link and images of IBM cloud

Solution :

```
#include <WiFi.h>
#include <PubSubClient.h>
#include <ArduinoJson.h>

WiFiClient wifiClient;

#define ORG "nhpwjc"
#define DEVICE_TYPE "raspberrypi"
#define DEVICE_ID "12345"
#define TOKEN "123456789"
#define speed 0.034

char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Data/fmt/json";
char topic[] = "iot-2/cmd/home/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);
void publishData();

const int trigpin=5;
const int echopin=18;
String command;
String data="";

long duration;
int dist;

void setup()
{
  Serial.begin(115200);
  pinMode(trigpin, OUTPUT);
  pinMode(echopin, INPUT);
  wifiConnect();
  mqttConnect();
}

void loop() {

  publishData();
  delay(500);

  if (!client.loop())
  { mqttConnect();
  }
}
```

```

void wifiConnect() {
    Serial.print("Connecting to "); Serial.print("Wifi");
    WiFi.begin("Wokwi-GUEST", "", 6);
    while (WiFi.status() != WL_CONNECTED)
    { delay(500);
      Serial.print(".");
    }
    Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
}

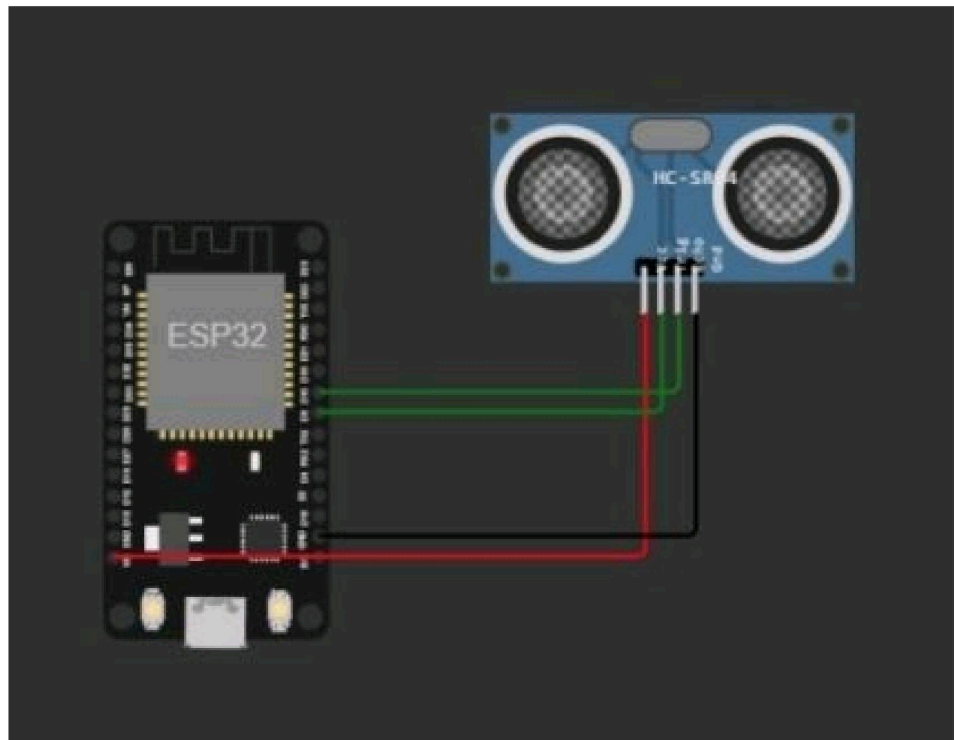
void mqttConnect() {
    if (!client.connected()) {
        Serial.print("Reconnecting MQTT client to "); Serial.println(server);
        while (!client.connect(clientId, authMethod, token)) {
            Serial.print(".");
            delay(1000);
        }
        initManagedDevice();
        Serial.println();
    }
}

void initManagedDevice() {
    if (client.subscribe(topic))
    { Serial.println(client.subscribe(topic));
      Serial.println("subscribe to cmd OK");
    }
    else {
        Serial.println("subscribe to cmd FAILED");
    }
}

void publishData()
{
    digitalWrite(trigpin,LOW);
    digitalWrite(trigpin,HIGH);
    delayMicroseconds(10);
    digitalWrite(trigpin,LOW);
    duration=pulseIn(echopin,HIGH);
    dist=duration*speed/2;

    if(dist<100){ DynamicJsonDocument
        doc(1024); String payload;
        doc["AlertDistance:"]=dist;
        serializeJson(doc, payload);
        delay(3000);
        Serial.print("\n");
        Serial.print("Sending payload: ");
        Serial.println(payload);
        if (client.publish(publishTopic, (char*) payload.c_str())) {
            Serial.println("Publish OK");
        }
        else {
            Serial.println("Publish FAILED");
        }
    }
}

```



The screenshot shows a software interface with a simulated circuit at the top and a terminal window below it. The circuit is a simplified version of the one in the first image. The terminal window displays the following text:

```
01:38.369 100%
Sending payload: {"Alert distance":93.99}
Publish OK

Sending payload: {"Alert distance":93.96}
Publish OK

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