# Assignment -4 WOKWI

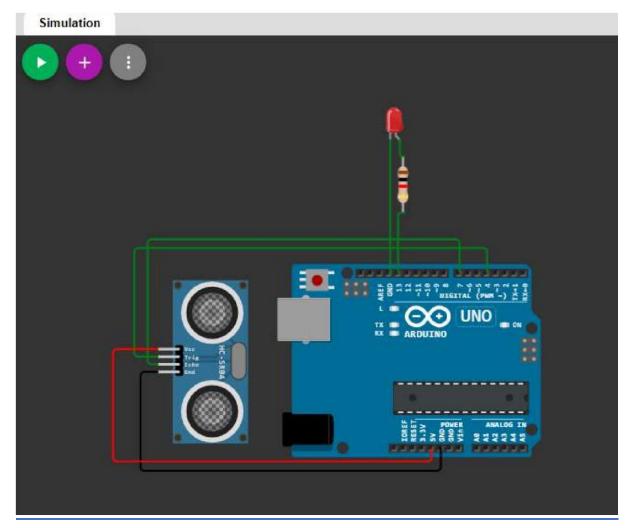
Assignment Date	28 October 2022
Student Name	SOMULA ASHOK KUMAR REDDY
Student Roll Number	721419106033
Maximum Marks	2 Marks

## **Question:**

Write a code and connection in wokwi for ultrasonic sensor .whenever distance is less than 100 cms send alert

#### **Solution:**

**SIMULATION** 



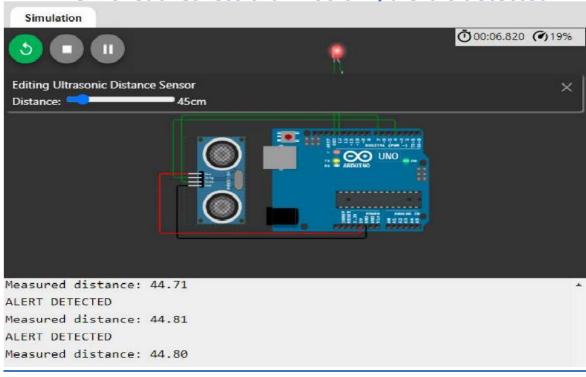
#### **CODE**

```
#define ECHO_PIN 2 #define
TRIG_PIN 9 void setup() {
Serial.begin(115200);
pinMode(LED_BUILTIN, OUTPUT);
pinMode(TRIG_PIN, OUTPUT);
pinMode(ECHO_PIN, INPUT);
}
float readDistanceCM() {
digitalWrite(TRIG_PIN, LOW); delay(2);
digitalWrite(TRIG_PIN, HIGH); delay(10);
digitalWrite(TRIG_PIN, LOW); int
duration = pulseIn(ECHO_PIN, HIGH);
```

```
return duration * 0.034 / 2;
}
void loop() { float distance =
readDistanceCM(); if (distance <
100) bool is Nearby = distance < 100;
digitalWrite(LED_BUILTIN, isNearby);
Serial.println("ALERT DETECTED ");
 Serial.print("Measured distance: ");
Serial.println(readDistanceCM()); delay(100);
 }
else {
 bool isNearby = distance > 100;
digitalWrite(LED_BUILTIN, LOW); Serial.println("ALERT
NOT DETECTED");
 Serial.print("Measured distance: ");
Serial.println(readDistanceCM()); delay(100);
}
}
```

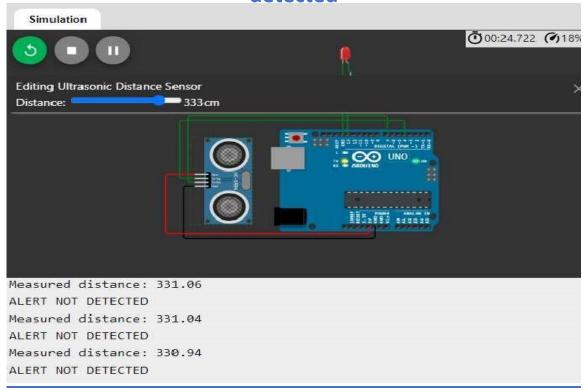
## **OUTPUT**

When it reaches less than 100 cm, alert is detected



When the distance is greater than 100 cm, alert is not

## detected



**PROGRAM AND OUTPUT** 

```
HOEFTINE ECHO PIN 7
                                                                                                                                             (†) 00:21,184 (*) 86%
2 #detine TRIG PIN 4
1 void setu() {
   Serial.begin(115280);
      pinMode(LED BUILTIN, OUTPUT);
      pinMode(TRIG PIN, OUTPUT);
      pinMode(ECHO PIN, INVII);
      fileat readDistanceCM() {
     digitallwite(TRIG_PIN, LDM);
                                                                                                                         .00 100
      delay(2);
     digitalWrite(TRIG_PIN, HIGH);
      delay(10);
     digitalWrite(TRIG_PIN, UNA);
    int duration = pulseIn(ECHO PIN, MIGH);
    return duration * 0.034 / 2;
18 void loop() {
    finat distance = readDistanceCM();
                                                                             Measured distance: 86.50
     # (distance < 100)[
                                                                             ALERT DETECTED
    bool isNearby = distance < 100;
                                                                             Measured distance: 86.50
    digitalMrite(LEO_MILLIEM, isNearby);
    Serial.println("ALERT DETECTED ");
                                                                             ALERT DETECTED
      Serial.print("Measured distance: ");
                                                                             Measured distance: 86.50
      Serial.println(readDistanceOH());
                                                                             ALERT DETECTED
      delay(180);
                                                                             Measured distance: 86.50
                                                                                                                                                 W II I
```

### **REFERENCE LINK**

https://wokwi.com/projects/346757092672012882