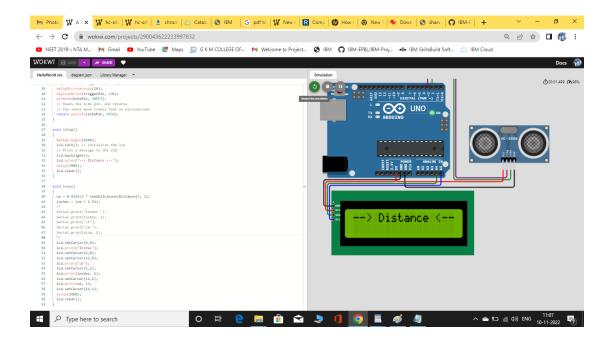
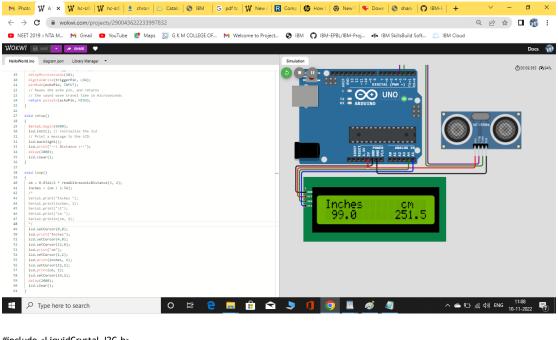
ASSIGNMENT 4

AssignmentDate	10 NOVEMBER
	2022
StudentName	Pavithra S
StudentRollNumber	410819106302

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.





#include <LiquidCrystal_I2C.h>

```
LiquidCrystal_I2C lcd(0x27,20,4);
// set the LCD address to 0x27 for a 16 chars and 2 line display
float inches;
long readUltrasonicDistance(int triggerPin, int echoPin)
            pinMode(triggerPin, OUTPUT); // Clear the trigger
            digitalWrite(triggerPin, LOW);
            delayMicroseconds(2);
            // Sets the trigger pin to HIGH state for 10 microseconds
            digitalWrite(triggerPin, HIGH);
            delayMicroseconds(10);
            digitalWrite(triggerPin, LOW);
            pinMode(echoPin, INPUT);
            \ensuremath{//} Reads the echo pin, and returns
            // the sound wave travel time in microseconds
            return pulseIn(echoPin, HIGH);
}
void setup()
 Serial.begin(9600);
lcd.init(); // initialize the lcd
 // Print a message to the LCD.
 lcd.backlight();
 lcd.print("--> Distance <--");</pre>
            delay(3000);
            lcd.clear();
}
void loop()
 cm = 0.0344/2 * readUltrasonicDistance(3, 2);
            inches = (cm / 2.54);
 /*
            Serial.print("Inches ");
            Serial.print(inches, 1);
            Serial.print("\t");
 Serial.print("cm ");
            Serial.println(cm, 1);
            lcd.setCursor(0,0);
```

lcd.print("Inches"); lcd.setCursor(4,0);

```
lcd.setCursor(12,0);
lcd.print("cm");
lcd.setCursor(1,1);
lcd.print(inches, 1);
lcd.setCursor(11,1);
lcd.print(cm, 1);
lcd.setCursor(14,1);
delay(2000);
lcd.clear();
}
```