## **ASSIGNMENT 4**

## Ultrasonic sensor simulation in Wokwi

PROJECT NAME: Hazardous Area Monitoring for Industrial Plant powered by IOT

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**Question:** Write a code and connections in wokwi for the ultrasonic sensor. Whenever the distance less than 100cms send an "Alert" to IBM cloud and display in the device recent events.

Wokwi simulation link: <a href="https://wokwi.com/projects/347124503089775188">https://wokwi.com/projects/347124503089775188</a>

**WOKWI OUTPUT SCREENSHOT:** 

```
₩OKWÎ 🖹 SAVE 🔻 🧀 SHARE 🛡
                                                                                                                                                                                                       Docs
                                                                                                                                                                                                                    sketch.ino diagram.json Library Manager 🕶
                                                                                                                  Simulation
                                                                                                                                                                                                   Ō00:30.796 (₹)99%
             void setup() {
   Serial.begin(115200);
   pinMode(LED_BUILTIN, OUTPUT);
   pinMode(TRIG_PIN, OUTPUT);
   pinMode(ECHO_PIN, INPUT);
                                                                                                                Editing Ultrasonic Distance Sensor
                                                                                                                Distance:
                                                                                                                                                         -0110
            float readDistanceCM() {
              digitalWrite(TRIG_PIN, LOW);
delayMicroseconds(2);
digitalWrite(TRIG_PIN, HIGH);
              delayMicroseconds(10);
digitalWrite(TRIG_PIN, LOW);
int duration = pulseIn(ECHO_PIN, HIGH);
return duration * 0.034 / 2;
                                                                                                               Measured distance: 218.94
                                                                                                                Measured distance: 239.84
                                                                                                                Measured distance: 239.84
            void loop() {
   float distance = readDistanceCM();
                                                                                                                Measured distance: 113.56
                                                                                                                person detected
                                                                                                                person detected
                                                                                                                person detected
            else{
| Serial.print("Measured distance: ");
                                                                                                                                                                                                           <u>⊬</u> II □
```

CODE:

```
#define ECHO_PIN 2
#define TRIG_PIN 3
#define organization = "md8rdq"
#define deviceType = "123"
#define deviceId = "123456"
#define authMethod = "token"
#define authToken = "Titik@2002"

void setup() {
    Serial.begin(115200);
    pinMode(LED_BUILTIN, OUTPUT);
    pinMode(TRIG_PIN, OUTPUT);
    pinMode(ECHO_PIN, INPUT);
}
```

```
float readDistanceCM() {
  digitalWrite(TRIG_PIN, LOW);
  delayMicroseconds(2);
  digitalWrite(TRIG_PIN, HIGH);
  delayMicroseconds(10);
  digitalWrite(TRIG_PIN, LOW);
  int duration = pulseIn(ECHO_PIN, HIGH);
  return duration * 0.034 / 2;
void loop() {
  float distance = readDistanceCM();
if(distance<=100)</pre>
  Serial.println(" person detected");
else{
  Serial.print("Measured distance: ");
  Serial.println(readDistanceCM());
  delay(1000);
```





