### ASSIGNMENT – 4

## Ultrasonic sensor simulation in Wokwi

Date	25 October 2022
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Maximum Marks	2 marks

## **QUESTION:**

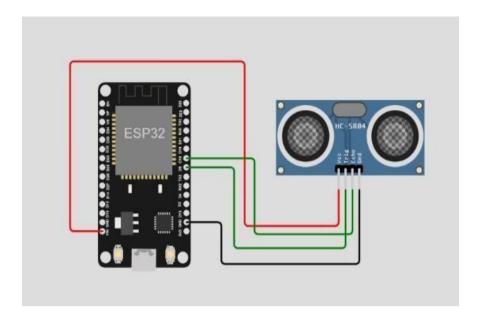
Write code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100 cms send an "alert" to the IBM cloud and display in the device recent events

#### CODE:

```
#include <WiFi.h> #include
 <PubSubClient.h>
 void callback(char* subscribetopic, byte* payload, unsigned int payloadLength);
 //----credentials of IBM Accounts-----
#define ORG "5bfis0"//IBM ORGANITION ID
#define DEVICE_TYPE "abcd"//Device type mentioned in ibm watson IOT Platform
#define DEVICE ID "1234"//Device ID mentioned in ibm watson IOT Platform
#define TOKEN "12345678" //Token
String data3;
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
 char publishTopic[] = "iot-2/evt/Data/fmt/json"; char
 subscribetopic[] = "iot-2/cmd/test/fmt/String"; char authMethod[]
 = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
 WiFiClient wifiClient;
 PubSubClient client(server, 1883, callback, wifiClient);
 const int trigPin = 5; const int echoPin = 18;
#define SOUND_SPEED 0.034
long duration;
 float distance;
 void setup() {
 Serial.begin(
 115200);
```

```
pinMode(trig
Pin,
OUTPUT);
pinMode(ech
oPin,
INPUT):
wificonnect(); mqttconnect();
} void
loop() {
digitalWrite(trigPin,
                                  LOW);
delayMicroseconds(2);
digitalWrite(trigPin,
                                 HIGH);
delayMicroseconds(10);
digitalWrite(trigPin, LOW); duration =
pulseIn(echoPin, HIGH); distance =
duration * SOUND SPEED/2;
Serial.print("Distance (cm): ");
Serial.println(distance); if(distance<100)
Serial.println("ALERT!!");
delay(1000);
PublishData(distance);
delay(1000); if
(!client.loop()) {
mqttconnect();
} }
delay(1000);
void PublishData(float dist) { mqttconnect();
String payload = "{\"Distance\":"; payload
+= dist:
payload += ",\"ALERT!!\":""\"Distance less than 100cms\"";
payload += "}";
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c_str())) {
Serial.println("Publish ok");
} else {
Serial.println("Publish failed");
} }
void mqttconnect() { if
(!client.connected()) {
```

```
Serial.print("Reconnect
ing client to ");
Serial.println(server);
while (!!!client.connect(clientId, authMethod, token)) {
Serial.print("."); delay(500);
initManagedDevice();
Serial.println();
} }
void wificonnect()
Serial.println();
Serial.print("Connecting
WiFi.begin("Wokwi-GUEST", "", 6); while
(WiFi.status() != WL_CONNECTED) {
delay(500);
Serial.print(".");
}
Serial.println("");
Serial.println("WiFi connected");
Serial.println("IP address: ");
Serial.println(WiFi.localIP());
}
void initManagedDevice() { if
(client.subscribe(subscribetopic)) {
Serial.println((subscribetopic));
Serial.println("subscribe to cmd OK");
} else {
Serial.println("subscribe to cmd FAILED");
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
Serial.print("callback invoked for topic: ");
Serial.println(subscribetopic); for (int i
= 0; i < payloadLength; i++) {
//Serial.print((char)payload[i]); data3
+= (char)payload[i];
Serial.println("data: "+ data3);
data3="";
CIRCUIT DIAGRAM:
```



# Wokwi simulation link:

https://wokwi.com/projects/3471910302342190

# **WOKWI OUTPUT:**

```
Distance (cm): 399.92
Distance (cm): 399.96
Distance (cm): 399.94
Distance (cm): 399.98
Distance (cm): 399.94
Distance (cm): 399.92
Distance (cm): 399.92
```

# **IBM CLOUD OUTPUT:**

