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PROJECT TITLE	REAL TIME RIVER WATER QUALITY MONITORING AND CONTROL SYSTEM
TOPIC	CONNECTIONS IN WOKWI FOR ULTRASONIC SENSOR WHENEVER THE DISTANCE IS LESS THAN 100 cms SEND AN ALERT TO IBM CLOUD
ASSIGNMENT	04
MENTOR	PRAKASAM L ASP/ECE
COLLEGE NAME	P.S.V. COLLEGE OF ENGINEERING AND TECHNOLOGY

CODE:

```
#include <WiFi.h>
#include <PubSubClient.h>
void callback(char* subscribetopic,byte* payload, unsigned int
payloadLength);
#define ORG "112t39"
#define DEVICE TYPE "ESP32"
#define DEVICE_ID "54321"
#define TOKEN "123456789"
String data3;
char server[]= ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[]="iot-2/evt/distance/fmt/json";
char subscribeTopic[]="iot-2/cmd/test/fmt/String";
char authMethod[]="use-token-auth";
char token[]=TOKEN;
char clientID[]="d:"ORG":"DEVICE TYPE":"DEVICE ID;
WiFiClient wifiClient;
PubSubClient client(server,1883,callback,wifiClient);
#define ECHO PIN 2
#define TRIG_PIN 4
#define led 5
void setup() {
// put your setup code here, to run once:
Serial.begin(115200);
pinMode(led, OUTPUT);
pinMode(TRIG PIN, OUTPUT);
pinMode(ECHO_PIN, INPUT);
wificonnect();
mqttconnect();
float readDistanceCM() {
digitalWrite(TRIG PIN, LOW);
delayMicroseconds(2);
digitalWrite(TRIG_PIN, HIGH);
delayMicroseconds(10);
digitalWrite(TRIG_PIN, LOW);
int duration=random(1,200);
//Serial.println(duration);
//duration = pulseIn(ECHO_PIN, HIGH);
return duration ;
//Serial.println(duration);
}void loop() {
float distance = readDistanceCM();
//Serial.println(distance);
bool isNearby = distance < 100;</pre>
digitalWrite(led, isNearby);
Serial.print("Measured distance: ");
Serial.println(distance);
```

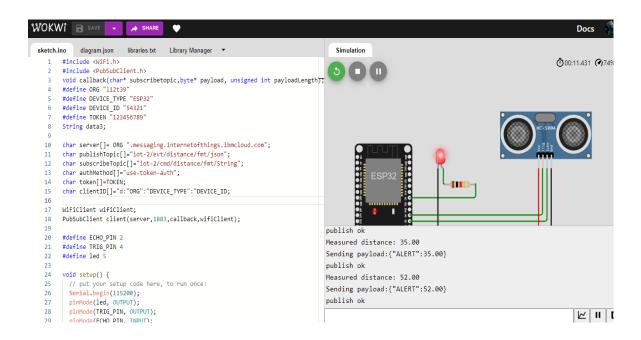
```
if(distance<100){</pre>
PublishData2(distance);
}else{
PublishData1(distance);
//PublishData(distance);
delay(1000);
if(!client.loop()){
mqttconnect();
}
//delay(2000);
}
void PublishData1(float dist){
mqttconnect();
String payload= "{\"distance\":";
payload += dist;
payload+="}";
Serial.print("Sending payload:");
Serial.println(payload);
if(client.publish(publishTopic,(char*)payload.c_str())){
Serial.println("publish ok");
} else{
Serial.println("publish failed");
}
void PublishData2(float dist){
mqttconnect();
String payload= "{\"ALERT\":";
payload += dist;
payload+="}";
Serial.print("Sending payload:");
Serial.println(payload);if(client.publish(publishTopic,(char*)payload.c_
str())){
Serial.println("publish ok");
} else{
Serial.println("publish failed");
void mqttconnect(){
if(!client.connected()){
Serial.print("Reconnecting to ");
Serial.println(server);
while(!!!client.connect(clientID, authMethod, token)){
Serial.print(".");
delay(500);
}
initManagedDevice();
Serial.println();
}
}
```

```
void wificonnect(){
Serial.println();
Serial.print("Connecting to");
WiFi.begin("Wokwi-GUEST","",6);
while(WiFi.status()!=WL_CONNECTED){
delay(500);
Serial.print(".");
Serial.println("");
Serial.println("WIFI CONNECTED");
Serial.println("IP address:");
Serial.println(WiFi.localIP());
void initManagedDevice(){
if(client.subscribe(subscribeTopic)){
Serial.println((subscribeTopic));
Serial.println("subscribe to cmd ok");
}else{
Serial.println("subscribe to cmd failed");
void callback(char* subscribeTopic, byte* payload, unsigned int
payloadLength){
Serial.print("callback invoked for topic:");
Serial.println(subscribeTopic);
for(int i=0; i<payloadLength; i++){data3 += (char)payload[i];</pre>
}
Serial.println("data:"+ data3);
if(data3=="lighton"){
Serial.println(data3);
digitalWrite(led,HIGH);
}else{
Serial.println(data3);
digitalWrite(led,LOW);
}
data3="";
```

WOKWI LINK:

https://wokwi.com/projects/346683745196048979

WOKWI SIMULATION:



CLOUD STORAGE:

